

RIGIDITY OF VECTOR VALUED HARMONIC MAPS OF LINEAR GROWTH

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ABSTRACT. Consider vector valued harmonic maps of at most linear growth, defined on a complete non-compact Riemannian manifold with non-negative Ricci curvature. For the norm square of the pull-back of the target volume form by such maps, we report a strong maximum principle, and equalities among its supremum, its asymptotic average, and its large-time heat evolution.

1. INTRODUCTION

We fix a complete, non-compact Riemannian manifold (M, g) with non-negative Ricci curvature. Harmonic functions on such manifolds have been an important subject of investigation in geometric analysis (see, among others, [24], [14],[15], [18], [13],[16],[17],[10], [11], and [6], etc.).

Among all harmonic functions, those of at most linear growth are especially interesting, as they reveal the properties of the tangent cones at infinity of M , through the work of Cheeger-Colding-Minicozzi II [6]. Vector valued harmonic maps of at most linear growth are also of central importance in studying the structure of the Gromov-Hausdorff limits of a sequence of Riemannian manifolds with Ricci curvature uniformly bounded below, as signified in the series of work by Cheeger-Colding (see [2], [3], [4], and [5]), and notably the recent resolution of the codimension-4 conjecture by Cheeger-Naber [8].

Our subject of study is a vector valued harmonic map of at most linear growth. To fix the terminologies, we call a function $\mathbf{u} : (M^m, x_0) \rightarrow (\mathbb{R}^n, \mathbf{0})$ ($n \leq m$) a *vector valued harmonic map* if each component of \mathbf{u} is a harmonic function $u_\alpha : M \rightarrow \mathbb{R}$ ($\alpha = 1, \dots, n$), and call it *pointed* if $\mathbf{u}(x_0) = \mathbf{0}$. Moreover, we say that \mathbf{u} is *of at most linear growth* if there exists some $L > 0$, such that

$$\forall x \in M, \quad |\mathbf{u}(x) - \mathbf{u}(x_0)| \leq L(r(x) + 1),$$

where $\forall x \in M$, $r(x) := d(x, x_0)$, the geodesic distance between x and x_0 , induced by the Riemannian metric g .

To each vector valued harmonic map as above, we could associate an n -form

$$\omega := \mathbf{u}^*(dy^1 \wedge dy^2 \wedge \cdots \wedge dy^n) \in \Gamma(M, \Lambda^n T^*M).$$

We say that \mathbf{u} is *non-trivial* if $|\omega| \not\equiv 0$.

For any $A \in GL(n)$, define $\omega_A := (A\mathbf{u})^*(dy^1 \wedge dy^2 \wedge \cdots \wedge dy^n)$. The following invariance of the pull-back n -form under the induced $SL(n)$ -actions is fundamental for our arguments:

$$(1.1) \quad \forall A \in SL(n), \quad |\omega_A|^2 = \det A |\omega|^2 = |\omega|^2.$$

Our first result then states:

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Theorem 1.1 (Strong maximum principle). *Let $\mathbf{u} : (M, x_0) \rightarrow (\mathbb{R}^n, \mathbf{0})$ be a pointed, vector valued harmonic map of at most linear growth which is non-trivial at x_0 . Then*

$$(1.2) \quad \lim_{\rho \rightarrow \infty} \int_{B(x_0, \rho)} |\omega|^2 dV_g = \sup_M |\omega|^2.$$

Moreover, if $|\omega|(x_0) = \sup_M |\omega|$, then $|\nabla \nabla \mathbf{u}| \equiv 0$, and $(M^m, g) \equiv (N^{m-n}, h) \times (\mathbb{R}^n, g_{Euc})$ isometrically, with (N^{m-n}, h) being some $(m-n)$ -dimensional Riemannian manifold with non-negative Ricci curvature.

Clearly, there is nothing special about the choice of base point x_0 in the statement of the theorem. Our proof of this theorem is a blend of the heat kernel estimates due to Li-Yau (see [20] and [14]), and the Hessian L^2 -estimates by Cheeger-Colding-Minicozzi II [6]. Now we briefly discuss the ingredients involved in Theorem 1.1.

Notice, since $\mathcal{R}c \geq 0$, that each individual $|\nabla u_\alpha|^2$ ($\alpha = 1, \dots, n$) is sub-harmonic by the Weitzenböck formula:

$$(1.3) \quad \Delta |\nabla u_\alpha|^2 = 2|\nabla \nabla u_\alpha|^2 + 2\mathcal{R}c(\nabla u_\alpha, \nabla u_\alpha) \geq 0,$$

also notice that the linear growth of u_α gives a global upper bound of $|\nabla u_\alpha|^2$ by the Cheng-Yau gradient estimate [9]: $|\nabla u_\alpha|^2$ is a bounded, non-negative sub-harmonic function on M . By a classical theorem of Peter Li [15], we have

$$(1.4) \quad \lim_{\rho \rightarrow \infty} \int_{B(x_0, \rho)} |\nabla u_\alpha|^2 dV_g = \sup_M |\nabla u_\alpha|^2.$$

Therefore we could view (1.2) as a high-dimensional generalization of this identity for the energy of harmonic functions of at most linear growth.

The proof of (1.2) is based on the invariance of certain canonical quantities associated to a vector valued harmonic map \mathbf{u} , and the invariance properties enable the compactness of $SO(n)$ to work for limiting arguments. Besides the pull-back measure density of \mathbf{u} , we also define:

- (1) Energy density: $|\nabla \mathbf{u}|^2 := \sum_{\alpha=1}^n |\nabla u_\alpha|^2$;
- (2) Splitting error: $r^2 |\nabla \nabla \mathbf{u}|^2 := \sum_{\alpha=1}^n r^2 |\nabla \nabla u_\alpha|^2$.

We notice that the quantities $|\omega|^2$, $|\nabla \mathbf{u}|^2$ and $r^2 |\nabla \nabla \mathbf{u}|^2$ are invariant under the special orthogonal group actions on \mathbb{R}^n :

$$(1.5) \quad \forall A \in SO(n), \quad \mathbf{u} \mapsto A\mathbf{u}, \quad \text{i.e. } (A\mathbf{u})_\alpha := \sum_{\beta=1}^n A_{\alpha\beta} u_\beta.$$

For the rigidity part of Theorem 1.1, i.e. when $|\omega|(x_0) = \sup_M |\omega|$ happens, we observe that (1.3) links the difference of the average energy between two scales, and this observation is implemented through the application of the heat measure. Here the *heat measure* is defined as $d\mu_{x_0}(t) := H_{x_0}(\cdot, t) dV_g$, where $H_{x_0}(y, t)$ is the fundamental solution to the heat equation (in $y \in M$) with the Delta function at $x_0 \in M$ as its initial value. Summing (1.3) in $\alpha = 1, \dots, n$, the aforementioned observation could be expressed as (see [14] for the justification of integration by parts)

$$\frac{d}{dt} \int_M |\nabla \mathbf{u}|^2 d\mu_{x_0}(t) \geq 2 \int_M |\nabla \nabla \mathbf{u}|^2 d\mu_{x_0}(t),$$

so integrating between different scales $\rho_1 < \rho_2$, we get

$$(1.6) \quad \int_M |\nabla \mathbf{u}|^2 d\mu_{x_0}(\rho_2^2) - \int_M |\nabla \mathbf{u}|^2 d\mu_{x_0}(\rho_1^2) \geq 2 \int_{\rho_1^2}^{\rho_2^2} \int_M |\nabla \nabla \mathbf{u}|^2 d\mu_{x_0}(t) dt.$$

This inequality contains rich information about \mathbf{u} : it tells not only that the weighted energy (weighted by the heat measure based at $x_0 \in M$) on large scales dominates that on smaller ones, but also that the difference dominates the splitting error. Roughly speaking, if $|\omega|^2$ attains a global maximum at x_0 , this inequality then forces the splitting error to vanish.

Following a similar argument and with the help of a Poincaré inequality weighted by the heat measure (Lemma 4.1), we also prove:

Theorem 1.2 (Large-time heat evolution). *Let (M, g, x_0) and \mathbf{u} satisfy the assumption of Theorem 1.1, then*

$$(1.7) \quad \lim_{t \rightarrow \infty} \int_M |\omega|^2 d\mu_{x_0}(t) = \sup_M |\omega|^2.$$

This theorem, in conjunction with Theorem 1.1, then says

$$(1.8) \quad \lim_{\rho \rightarrow \infty} \int_{B(x_0, \rho)} |\omega|^2 dV_g = \sup_M |\omega|^2 = \lim_{t \rightarrow \infty} \int_M |\omega|^2 d\mu_{x_0}(t).$$

Notice that $|\omega|^2$ is *not* necessarily sub-harmonic in any obvious way (see Section 4 for more details), therefore we have to prove both sides of (1.8) separately. At this point, it is interesting to compare this identity with classical results of Peter Li in [15]:

Theorem 1.3 (Peter Li [15]). *Suppose M has positive asymptotic volume ratio at infinity, i.e. $\lim_{\rho \rightarrow \infty} \omega_m^{-1} \rho^{-m} \text{Vol}_g(B(x_0, \rho)) = \kappa > 0$, then for any bounded function f ,*

$$(1.9) \quad \lim_{\rho \rightarrow \infty} \int_{B(x_0, \rho)} f dV_g = \lim_{t \rightarrow \infty} \int_M f d\mu_{x_0}(t),$$

as long as one of these limits exists.

On the other hand, if f is a bounded, non-negative sub-harmonic function, then regardless of the positivity of the asymptotic volume ratio at infinity,

$$(1.10) \quad \lim_{\rho \rightarrow \infty} \int_{B(x_0, \rho)} f dV_g = \sup_M f \quad \text{and} \quad \lim_{t \rightarrow \infty} \int_M f d\mu_{x_0}(t) = \sup_M f.$$

Notice that when M has vanishing asymptotic volume ratio at infinity, (1.9) is not necessarily true for *any* bounded function, see [23]. However it is not clear if (1.10) *only* holds for sub-harmonic functions. Therefore, (1.8) provides another incidence when (1.10) stands for a function which is *not* necessarily sub-harmonic, *regardless* of the positivity of the asymptotic volume ratio at infinity. See Section 4 for a further discussion.

2. BACKGROUND

In this section we review the relevant facts needed for our future arguments: Cheeger-Colding's segment inequality, and the Li-Yau heat kernel estimates. We will also recall a result due Peter Li, the proof of which was embedded in other results and here we single it out. Instead of citing the original results in full generality, we will state the results in a form that suit our future applications.

Given any Riemannian manifold with Ricci curvature uniformly bounded below, a fundamental inequality which is directly built on the Bishop-Gromov volume comparison is Cheeger-Colding's segment inequality [2] (see also [1]):

Proposition 2.1 (Segment inequality). *Let (M^m, g) be a complete Riemannian manifold with $\mathcal{R}c_g \geq 0g$. Let $B(x_0, r)$ be a geodesic ball of radius $\rho > 0$ around $x_0 \in M$. For any $f \in L^1_{loc}(M)$ we define*

$$\mathcal{F}(x, y) := \inf_{\gamma_{xy}} \int_0^{d(x,y)} f(\gamma_{xy}(t)) dt,$$

where the infimum is taken over all minimal geodesics γ_{xy} connecting x and y . There is a dimensional constant $C_{CC}(m) > 0$ such that for any $f \in L^1_{loc}(M)$,

$$\int_{B(x_0, \rho) \times B(x_0, \rho)} \mathcal{F}(x, y) dV_g(x) dV_g(y) \leq C_{CC}(m) |B(x_0, \rho)|(2\rho) \int_{B(x_0, 2\rho)} f dV_g.$$

This inequality is useful in extracting estimates along *most* geodesics connecting pairs of points, see for instance [2] and [12]. It also has the Poincaré inequality as a natural consequence (see [21] and [1]):

Proposition 2.2 (Poincaré inequality). *Assume (M, g) is a complete Riemannian manifold with non-negative Ricci curvature. There is a dimensional constant $C_P(m) > 0$ such that for any $f \in W^{1,1}_{loc}(M)$,*

$$(2.1) \quad \int_{B(x_0, \rho)} \left| f - \int_{B(x_0, \rho)} f dV_g \right| dV_g \leq C_P(m) \rho \int_{B(x_0, 2\rho)} |\nabla f| dV_g.$$

In fact, with the help of the segment inequality, we will later prove a version of the Poincaré inequality (Lemma 4.1) with the heat measure $d\mu_{x_0}$ replacing the volume form dV_g . To set up the weighted Poincaré inequality, the heat kernel estimates due to Li-Yau [20] is also of crucial importance:

Proposition 2.3 (Heat kernel bounds). *Let (M, g) be a complete, non-compact Riemannian manifold with non-negative Ricci curvature. Then the fundamental solution $H_{x_0}(x, t)$ to the heat equation satisfies*

$$(2.2) \quad \frac{C_1(\varepsilon)^{-1}}{|B(x_0, \sqrt{t})|} e^{-\frac{r^2(x)}{(4-\varepsilon)t}} \leq H_{x_0}(x, t) \leq \frac{C_2(\varepsilon)}{|B(x_0, \sqrt{t})|} e^{-\frac{r^2(x)}{(4+\varepsilon)t}},$$

where the positive constants $C_1(\varepsilon), C_2(\varepsilon) \rightarrow \infty$ as $\varepsilon \rightarrow 0$.

Moreover, we will need the following Harnack inequality for heat kernels, which is also proved in [20]:

Proposition 2.4 (Harnack inequality for positive heat equation solutions). *Let $w(x, t)$ be a positive solution to the heat equation, then for x, y and $t_1 < t_2$ we have*

$$(2.3) \quad w(x, t_1) \leq w(y, t_2) \left(\frac{t_2}{t_1} \right)^{\frac{3m}{4}} \exp \left(\frac{3d(x, y)^2}{8(t_2 - t_1)} \right).$$

As a consequence of the above Harnack inequality, we have the following lemma due to Peter Li [15], see the second identity of (1.10):

Lemma 2.5. *Let u be a bounded, non-negative sub-harmonic function defined on a complete non-compact Riemannian manifold (M, g) with non-negative Ricci curvature. Let $d\mu_x$ be the heat measure based at $x \in M$, then*

$$(2.4) \quad \lim_{t \rightarrow \infty} \int_M u d\mu_x(t) = \sup_M u.$$

The proof of this lemma is contained in the proof of Proposition 2 in [15]. We include it here for the sake of completeness.

Proof. For any $x \in M$ and $t > 0$ we define $Hu(x, t) := \int_M u \, d\mu_x(t)$. By the sub-harmonicity of u we see that $Hu(x, t)$ is non-decreasing in t :

$$\forall x \in M, \forall t > 0, \quad \partial_t Hu(x, t) = \int_M \Delta u \, d\mu_x(t) \geq 0.$$

Especially $Hu(x, t) \geq u(x)$ for any $x \in M$ and any $t > 0$. Moreover, the positivity of $H_x(y, t)$ (the fundamental solution to the heat equation based at $x \in M$) and the stochastic completeness of $d\mu_x(t)$ ensure that

$$\forall x \in M, \forall t > 0, \quad 0 \leq Hu(x, t) \leq \sup_M u.$$

With the help of (2.3), we see that as $t \rightarrow \infty$, $Hu(-, t)$ converges to a function uniformly on compact subsets of M . Choosing a compact exhaustion of M and using a diagonal argument of choosing sub-sequences, we conclude that as $t \rightarrow \infty$, $Hu(-, t)$ converges to some globally defined function $Hu(-, \infty)$, uniformly on compact subsets of M .

Clearly $0 \leq Hu(-, \infty) \leq \sup_M u$, and in fact $Hu(-, \infty)$ is harmonic. Therefore, by the Cheng-Yau gradient estimate [9], $Hu(-, \infty)$ must be a constant, which must be $\sup_M u$, since $H(x, \infty) \geq u(x)$ for any $x \in M$. \square

3. THE STRONG MAXIMUM PRINCIPLE

In this section we prove the strong maximum principle, Theorem 1.1. Consider the functions $E_{\alpha\beta}(\mathbf{u}) := \langle \nabla u_\alpha, \nabla u_\beta \rangle$ on M ($\alpha, \beta = 1, \dots, n$), and the $n \times n$ -matrix valued function $\mathbb{E}(\mathbf{u}) := [E_{\alpha\beta}(\mathbf{u})]$, which is positive semi-definite throughout M . For each $\rho > 0$, we could also consider the average of $\mathbb{E}(\mathbf{u})$ over $B(x_0, \rho)$, a positive semi-definite numerical matrix:

$$\Omega_\rho(\mathbf{u}) := \left[\int_{B(x_0, \rho)} E_{\alpha\beta}(\mathbf{u}) \, dV_g \right],$$

Since $|\omega|^2 = \det \mathbb{E}(\mathbf{u})$, the theme of the proof is the interplay between the quantities $\int_{B(x_0, \rho)} \det \mathbb{E}(\mathbf{u}) \, dV_g$ and $\det \Omega_\rho(\mathbf{u})$, which are obtained by taking determinant and then average of $\mathbb{E}(\mathbf{u})$, or in the alternative order.

Pick a sequence of scales ρ_i that tend to infinity. By Li's identity (1.4), the adjusted harmonic maps (adjustments made so that Ω_{ρ_i} becomes diagonal) will see $\det \Omega_{\rho_i}$ approaching $\sup_M |\omega|^2$, since $\det \Omega_{\rho_i}$ and $|\omega|^2$ are invariant under the induced $SO(n)$ -actions, and the diagonalization enables us to deal with the determinants in a similar way as scalar functions.

On the other hand, following an argument in [6], the L^2 -average of Hessian could be shown to approach zero, therefore, by the Poincaré inequality (2.1), the process of taking determinant and taking average of $\mathbb{E}(\mathbf{u})$ on larger and larger scales will gradually commute.

The last piece is the compactness of $SO(n)$, from which we could obtain certain limiting adjustment by a special orthogonal matrix that works for the asymptotic behavior.

The proof of the rigidity part follows from a direct application of the heat measure, as outlined in the introduction. We also need Lemma 2.5 to take care of individual component functions.

Proof of Theorem 1.1. Asymptotic maximality. To prove (1.2), notice that it suffices to show the following:

$$(3.1) \quad \forall x \in M, \quad |\omega|^2(x) \leq \lim_{\rho \rightarrow \infty} \int_{B(x_0, \rho)} |\omega|^2 dV_g,$$

since $\int_{B(x_0, \rho)} |\omega|^2 dV_g \leq \sup_M |\omega|^2$ for any $\rho > 0$. To prove (3.1), pick any sequence $\rho_i \rightarrow \infty$ and let $A_i \in SO(n)$ diagonalize $\Omega_{\rho_i}(\mathbf{u})$. Then by the compactness of $SO(n)$, possibly passing to a subsequence, $A_i \rightarrow A_\infty \in SO(n)$. Denoting $\mathbf{v} := A_\infty \mathbf{u}$, we have, according to (1.1) and (1.5),

$$(3.2) \quad \det \Omega_{\rho_i}(\mathbf{u}) = \det \Omega_{\rho_i}(A_i \mathbf{u}) = \det \Omega_{\rho_i}(\mathbf{v}),$$

and $|\omega|^2 \equiv |\omega_{A_i}|^2 \equiv |\omega_{A_\infty}|^2$ on M .

Moreover, for $\lambda_{\alpha, i}^2 := \int_{B(x_0, \rho_i)} |\nabla v_\alpha|^2 dV_g$, we have, by the convergence $A_i \rightarrow A_\infty$, that

$$(3.3) \quad \lim_{i \rightarrow \infty} \left| \prod_{\alpha=1}^n \lambda_{\alpha, i}^2 - \det \Omega_{\rho_i}(\mathbf{u}) \right| = 0.$$

Since A_∞ is a linear transformation, each component function of $\mathbf{v} = A_\infty \mathbf{u}$ is harmonic, and applying (1.4) we have, for each $\alpha = 1, \dots, n$,

$$(3.4) \quad \lim_{i \rightarrow \infty} \lambda_{\alpha, i}^2 = \lim_{\rho \rightarrow \infty} \int_{B(x_0, \rho)} |\nabla v_\alpha|^2 dV_g = \sup_M |\nabla v_\alpha|^2 =: L_\alpha^2.$$

Now we follow an argument in [6] to control the average Hessian of each v_α on large enough scales. For any fixed $\rho_i > 0$, let φ_i be a cutoff function defined as in [22], such that $\text{supp } \varphi_i \subset B(x_0, 3\rho_i)$ and $\varphi_i \equiv 1$ on $B(x_0, 2\rho_i)$, moreover,

$$\rho_i^2 |\Delta \varphi_i| + \rho_i |\nabla \varphi_i| \leq C(M).$$

We can then estimate the average Hessian on scale ρ_i :

$$\begin{aligned} \int_{B(x_0, 2\rho_i)} 2|\nabla \nabla v_\alpha|^2 dV_g &\leq 2^m \int_{B(x_0, 3\rho_i)} \varphi_i \Delta (|\nabla v_\alpha|^2 - L_\alpha^2) dV_g \\ &\leq 2^m \int_{B(x_0, 3\rho_i)} |\Delta \varphi_i| (L_\alpha^2 - |\nabla v_\alpha|^2) dV_g \\ &\leq C(M) \rho_i^{-2} L_\alpha^2 \Psi(\rho_i^{-1}), \end{aligned}$$

where by (3.4), $\Psi(\rho_i^{-1}) > 0$ satisfies

$$\Psi(\rho_i^{-1}) := \max_{\alpha=1, \dots, n} \left(1 - L_\alpha^{-2} \int_{B(x_0, 3\rho_i)} |\nabla v_\alpha|^2 dV_g \right) \rightarrow 0 \quad \text{as } i \rightarrow \infty.$$

Consequently, we have for each $\alpha = 1, \dots, n$,

$$(3.5) \quad \rho_i^2 \int_{B(x_0, 2\rho_i)} |\nabla \nabla u_\alpha|^2 dV_g \leq C(M) L_\alpha^2 \Psi(\rho_i^{-1}).$$

This estimate, together with the Poincaré inequality (2.1), controls the behavior of the average pull-back measure density on large scales:

$$\begin{aligned}
& \int_{B(x_0, \rho_i)} \left| |\omega_{A_\infty}|^2 - \det \Omega_{\rho_i}(\mathbf{v}) \right| dV_g \\
& \leq \sum_{\sigma \in S_n} \int_{B(x_0, \rho_i)} \left| \prod_{\alpha=1}^n \langle \nabla v_\alpha, \nabla v_{\sigma(\alpha)} \rangle - \prod_{\alpha=1}^n \int_{B(x_0, \rho_i)} \langle \nabla v_\alpha, \nabla v_{\sigma(\alpha)} \rangle dV_g \right| dV_g \\
& \leq \sum_{\sigma \in S_n} \sum_{\alpha=1}^n \left(\prod_{\beta \neq \alpha} L_\beta L_{\sigma(\beta)} \right) \int_{B(x_0, \rho_i)} \left| \langle \nabla v_\alpha, \nabla v_{\sigma(\alpha)} \rangle - \int_{B(x_0, \rho_i)} \langle \nabla v_\alpha, \nabla v_{\sigma(\alpha)} \rangle dV_g \right| dV_g,
\end{aligned}$$

now for each $\alpha = 1, \dots, n$ and $\sigma \in S_n$ (the n -symmetric group), we apply the Poincaré inequality (2.1) and the Hölder inequality and (3.5) to see:

$$\begin{aligned}
& \int_{B(x_0, \rho_i)} \left| \langle \nabla v_\alpha, \nabla v_{\sigma(\alpha)} \rangle - \int_{B(x_0, \rho_i)} \langle \nabla v_\alpha, \nabla v_{\sigma(\alpha)} \rangle dV_g \right| dV_g \\
& \leq C_P \rho \int_{B(x_0, 2\rho_i)} |\nabla \langle \nabla v_\alpha, \nabla v_{\sigma(\alpha)} \rangle| dV_g \\
& \leq 2C_P(m)C(M) L_\alpha L_{\sigma(\alpha)} \Psi(\rho_i^{-1})^{\frac{1}{2}}.
\end{aligned}$$

Consequently,

$$(3.6) \quad \int_{B(x_0, \rho_i)} \left| |\omega_{A_\infty}|^2 - \det \Omega_{\rho_i}(\mathbf{v}) \right| dV_g \leq 2C_P(m)C(M)n!n \left(\prod_{\alpha=1}^n L_\alpha^2 \right) \Psi(\rho_i^{-1})^{\frac{1}{2}}.$$

Combining (3.2), (3.3), (3.4) and (3.6), we see that

$$(3.7) \quad \forall x \in M, \quad \lim_{i \rightarrow \infty} \int_{B(x_0, \rho_i)} |\omega|^2 dV_g = \prod_{\alpha=1}^n L_\alpha^2 \geq |\omega|^2(x),$$

where the last inequality stands as $\forall x \in M$,

$$|\omega|^2(x) = |\omega_{A_\infty}|^2(x) = |\nabla v_1 \wedge \dots \wedge \nabla v_n|^2(x) \leq \prod_{\alpha=1}^n |\nabla v_\alpha|^2(x).$$

Since for every sequence $\rho_i \rightarrow \infty$, there is a subsequence for which (3.7) holds, we have finished proving (3.1).

Rigidity. When $|\omega|(x_0) = \sup_M |\omega|$, we may renormalize $\tilde{v}_\alpha := L_\alpha^{-1} v_\alpha$, so that $|\nabla \tilde{v}_\alpha|^2 \leq 1$ and $\sup_M |\nabla \tilde{v}_\alpha| = 1$ for $\alpha = 1, \dots, n$. By (3.3) and (3.4), we see $\det \Omega_{\rho_i}(\tilde{\mathbf{v}}) \rightarrow 1$. This fact, together with (3.6) and (3.7), ensure

$$|\tilde{\omega}|(x_0) = \sup_M |\tilde{\omega}| = 1.$$

On the other hand, since each $|\nabla \tilde{v}_\alpha|^2$ is bounded, non-negative and sub-harmonic, by Lemma 2.5 we have

$$\lim_{\rho \rightarrow \infty} \int_M |\nabla \tilde{\mathbf{v}}|^2 d\mu_{x_0}(\rho^2) = n.$$

By (1.6), the splitting error between the zero scale and the infinity scale is controlled as

$$\begin{aligned}
|\nabla\tilde{\mathbf{v}}|^2(x_0) &\leq |\nabla\tilde{\mathbf{v}}|^2(x_0) + \int_0^\infty \int_M |\nabla\nabla\tilde{\mathbf{v}}|^2 d\mu_{x_0}(t)dt \\
(3.8) \qquad &\leq \lim_{\rho \rightarrow \infty} \int_M |\nabla\tilde{\mathbf{v}}|^2 d\mu_{x_0}(\rho^2) \\
&= n.
\end{aligned}$$

However, applying the arithmetic mean - geometric mean inequality at x_0 , we have

$$n = n|\tilde{\omega}|^{\frac{2}{n}}(x_0) \leq |\nabla\tilde{\mathbf{v}}|^2(x_0),$$

which, together with (3.8), ensures all inequalities there to be equalities; especially

$$(3.9) \quad \int_0^\infty \int_M |\nabla\nabla\tilde{\mathbf{v}}|^2 d\mu_{x_0}(t)dt = 0 \implies \forall t > 0, \quad \int_M |\nabla\nabla\tilde{\mathbf{v}}|^2 d\mu_{x_0}(t) = 0,$$

whence the vanishing of $|\nabla\nabla\tilde{\mathbf{v}}|^2$ throughout M .

Since $\tilde{\mathbf{v}}$ is obtained from \mathbf{u} by a linear transformation, this shows that $|\nabla\nabla\mathbf{u}|^2 \equiv 0$ on M . The isometric splitting then follows easily from the vanishing of the splitting error of \mathbf{u} and its non-degeneracy. For the details of the argument, see for instance [7]. \square

Corollary 3.1. *Suppose (M, g) and $\mathbf{u} : M \rightarrow \mathbb{R}^n$ satisfy the same assumptions as in the strong maximum principle. We have $|\nabla\nabla\mathbf{u}| \equiv 0$ whenever one of the following conditions are satisfied:*

- (1) $|\nabla\omega| \equiv 0$;
- (2) $\Delta|\omega|^2 \equiv 0$;
- (3) $\Delta|\nabla\omega|^2 \equiv 0$

Proof. Condition (1) implies that $|\omega| \equiv \text{constant}$ by a direct computation.

For Condition (2), first notice that $|\omega|^2 = |\nabla u_1 \wedge \nabla u_2 \wedge \cdots \wedge \nabla u_n|^2$ is uniformly bounded throughout M , according to the control of \mathbf{u} and Cheng-Yau gradient estimate [9] applied to each component of \mathbf{u} . Since Condition (2) says that $|\omega|^2$ is actually harmonic, applying Cheng-Yau's gradient estimate again to $|\omega|^2$ we immediately see that $|\omega|^2$ is a constant.

Since on M any non-negative harmonic function is constant (Corollary 1 of [24]), Condition (3) implies that $|\nabla\omega|^2 \equiv C \geq 0$. However, $|\nabla\omega|^2 \leq C(m, n)L^{n-2}|\nabla\nabla\mathbf{u}|^2$ on M and according to (3.5),

$$\lim_{\rho \rightarrow \infty} \int_{B(x, \rho)} |\nabla\nabla\mathbf{u}|^2 dV = 0.$$

Therefore, we have

$$\begin{aligned}
\lim_{\rho \rightarrow \infty} \int_{B(x, \rho)} |\nabla\omega|^2 dV &\leq C(m, n)L^{n-2} \lim_{\rho \rightarrow \infty} \int_{B(x, \rho)} |\nabla\nabla\mathbf{u}|^2 dV \\
&= 0,
\end{aligned}$$

whence the constancy of $|\omega|$ throughout M . \square

4. WEIGHTED POINCARÉ INEQUALITY AND APPLICATIONS

In this section, we first set up the technical tools needed for proving Theorem 1.2: a Poincaré inequality on M with respect to the heat measure $d\mu_{x_0}(t)$. The long-time behavior of the heat solution, whose initial value is the pull-back measure density, is then studied following a similar strategy as in last section.

4.1. Poincaré inequality weighted by the heat measure. We will control the weighted (by the heat measure) difference between a function $f \in L^\infty(M) \cap C^1(M)$ and its heat evolution, roughly by the heat evolution of its derivative (the “central part”) and an error term (the “tail part”).

The estimate of the “central part” is based on the heat kernel estimate of Li-Yau (Proposition 2.3), as well as Cheeger-Colding’s segment inequality (Proposition 2.1). We begin with an elementary estimate of the distance to points on a minimal geodesic by that to the end points: Let $x, y \in M$ and γ be a minimal geodesic connecting them. Since

$$\forall s \in [0, d(x, y)], \quad d(x, \gamma(s)) + d(y, \gamma(s)) = d(x, y),$$

we have

$$\begin{aligned} 2d(x_0, \gamma(s)) &\leq d(x_0, x) + d(x, \gamma(s)) + d(x_0, y) + d(y, \gamma(s)) \\ &= d(x_0, x) + d(y_0, y) + d(x, y) \\ &\leq 2d(x_0, x) + 2d(y_0, y), \end{aligned}$$

and thus

$$\frac{1}{2}r^2(\gamma(s)) \leq r^2(x) + r^2(y).$$

This gives, for almost every pair of $x, y \in M$, and $s \in [0, d(x, y)]$, that

$$\begin{aligned} |f(x) - f(y)| e^{-\frac{2}{9r}(r^2(x)+r^2(y))} &\leq \int_0^{d(x,y)} |\nabla f|(\gamma(s)) e^{-\frac{2}{9r}(r^2(x)+r^2(y))} ds \\ &\leq \int_0^{d(x,y)} |\nabla f|(\gamma(s)) e^{-\frac{1}{9r}r^2(\gamma(s))} ds. \end{aligned}$$

Using this estimate, together with Proposition 2.3 and Proposition 2.1, we could control the “central part” as following:

$$\begin{aligned} &\int_{B(x_0, R)} \int_{B(x_0, R)} |f(x) - f(y)| d\mu_{x_0}(x, t) d\mu_{x_0}(y, t) \\ (4.1) \quad &\leq \frac{C_2(1/2)^2}{|B(x_0, \sqrt{t})|^2} \int_{B(x_0, R)} \int_{B(x_0, R)} |f(x) - f(y)| e^{-\frac{2}{9r}(r^2(x)+r^2(y))} dV_g(x) dV_g(y) \\ &\leq \frac{C_2(1/2)^2}{|B(x_0, \sqrt{t})|^2} \int_{B(x_0, R)} \int_{B(x_0, R)} \left(\int_0^{d(x,y)} |\nabla f|(\gamma(s)) e^{-\frac{1}{9r}r^2(\gamma(s))} ds \right) dV_g(x) dV_g(y) \\ &\leq C_{CC}(m) C_2(1/2)^2 \frac{|B(x_0, 2R)|}{|B(x_0, \sqrt{t})|^2} (2R) \int_{B(x_0, 2R)} |\nabla f|(x) e^{-\frac{1}{9r}r^2(x)} dV_g(x) \\ &\leq C_{CC}(m) C_2(1/2)^2 C_1(1) 3^{\frac{m}{2}} \frac{|B(x_0, 2R)|}{|B(x_0, \sqrt{t})|^2} (2R) \int_{B(x_0, 2R)} |\nabla f| d\mu_{x_0}(3t). \end{aligned}$$

On the other hand, we could estimate the “tail part” of the heat measure for $R \geq \sqrt{t}$. Using the heat kernel upper bound and integrating radially, we have

$$\begin{aligned} \int_{M \setminus B(x_0, R)} 1 d\mu_{x_0}(t) &\leq \frac{C_2(1/2)}{|B(x_0, \sqrt{t})|} \int_{M \setminus B(x_0, \sqrt{t})} e^{-\frac{2r^2(x)}{9r}} dV_g(x) \\ &= \frac{C_2(1/2)}{|B(x_0, \sqrt{t})|} \int_R^\infty e^{-\frac{2r^2}{9r}} |\partial B(x_0, r)| dr. \end{aligned}$$

Since M is complete and $\mathcal{R}c_g \geq 0$, by the Bishop-Gromov volume comparison, we have

$$|\partial B(x_0, r)| \leq mr^{-1} |B(x_0, r)| \leq mr^{m-1} t^{-\frac{m}{2}} |B(x_0, \sqrt{t})|,$$

and thus

$$(4.2) \quad \begin{aligned} \int_{M \setminus B(x_0, R)} 1 \, d\mu_{x_0}(t) &\leq C_2(1/2)m \int_R^\infty e^{-\frac{2r^2}{9t}} r^{m-1} t^{-\frac{m}{2}} \, dr \\ &= C_2(1/2)m \int_{\frac{R}{\sqrt{t}}}^\infty e^{-\frac{2s^2}{9}} s^{m-1} \, ds. \end{aligned}$$

Denoting

$$(4.3) \quad \Psi_2(\sqrt{t}/R \mid m) := C_2(1/2)m \int_{\frac{R}{\sqrt{t}}}^\infty e^{-\frac{2s^2}{9}} s^{m-1} \, ds,$$

we clearly see that

$$(4.4) \quad \lim_{\frac{R}{\sqrt{t}} \rightarrow \infty} \Psi_2(\sqrt{t}/R \mid m) = 0.$$

Combining the above estimates, we have the following Poincaré inequality:

Lemma 4.1 (Weighted Poincaré inequality). *Let f be a bounded function on M . Suppose $|f| \leq L$ and $\int_M |\nabla f| \, d\mu_{x_0}(t)$ is defined for $t > 0$. Then for $t > 0$ and $R \geq \sqrt{t}$ we have*

$$\int_M \left| f - \int_M f \, d\mu_{x_0}(t) \right| \, d\mu_{x_0}(t) \leq C_{WP} \frac{|B(x_0, R)|}{|B(x_0, \sqrt{t})|} R \int_M |\nabla f| \, d\mu_{x_0}(3t) + \Psi_{WP}(\sqrt{t}/R \mid m) L,$$

with $C_{WP} := C_{CC}(m)C_2(1/2)^2C_1(1)6^m$ being a dimensional constant and $\Psi_{WP} := 6\Psi_2$.

Proof. Since $\int_M 1 \, d\mu_{x_0}(t) = 1$, we see

$$\begin{aligned} &\int_M \left| f - \int_M f \, d\mu_{x_0}(t) \right| \, d\mu_{x_0}(t) \\ &\leq \int_{B(x_0, R)} \int_{B(x_0, R)} |f(x) - f(y)| \, d\mu_{x_0}(x, t) d\mu_{x_0}(y, t) + 3 \int_{M \setminus B(x_0, R)} 2L \, d\mu_{x_0}(t), \end{aligned}$$

then the conclusion follows easily from the previous estimates (4.1), (4.2) and (4.3). \square

4.2. Large-time evolution of the pull-back measure density by the heat equation.

In this sub-section we prove Theorem 1.2. The proof follows in the same way as that of Theorem 1.1. However, due to the complication in the weighted Poincaré inequality (Lemma 4.1), for any sequence $t_i \rightarrow \infty$, we need to make a careful selection of the subsequences.

We will also need Li-Yau's Harnack inequality for the heat kernel (Proposition 2.4), which especially implies the following estimate: If $H_{x_0}(x, t)$ is the fundamental solution to the heat equation with initial value being the Delta function at $x_0 \in M$, then for any $t_2 > t_1 > 0$,

$$(4.5) \quad H_{x_0}(x, t_1) \leq \left(\frac{t_2}{t_1} \right)^{\frac{3m}{4}} H_{x_0}(x, t_2).$$

Proof of Theorem 1.2. In view of the proof of Theorem 1.1, we only need to show that for any $t_i \rightarrow \infty$, there is a subsequence t_{i_j} such that

$$\forall x \in M, \quad \lim_{j \rightarrow \infty} \int_M |\omega|^2 \, d\mu_{x_0}(t_{i_j}) \geq |\omega|^2(x).$$

In a similar way as proving Theorem 1.1, we pick $t_i \rightarrow \infty$ and consider special orthogonal matrices \bar{A}_i that diagonalize $\bar{\Omega}_{t_i}(\mathbf{u}) := \left[\int_M E_{\alpha\beta}(\mathbf{u}) \, d\mu_{x_0}(t_i) \right]$. We then have some limiting

$\bar{A}_\infty \in SO(n)$ to which a subsequence of \bar{A}_i converges. For $\bar{\mathbf{v}} := \bar{A}_\infty \mathbf{u}$, by the $SO(n)$ -invariance we have

$$\det \bar{\Omega}_t(\mathbf{u}) = \det \bar{\Omega}_t(\bar{A}_i \mathbf{u}) = \det \bar{\Omega}_t(\bar{\mathbf{v}}),$$

and $|\omega| \equiv |\omega_{\bar{A}_i}| \equiv |\bar{A}_\infty \omega|$ on M .

Moreover, invoking Lemma 2.5, we have

$$\lim_{i \rightarrow \infty} \int_M |\nabla \bar{v}_\alpha|^2 d\mu_{x_0}(t_i) = \sup_M |\nabla \bar{v}_\alpha|^2 =: \bar{L}_\alpha^2,$$

and $\lim_{i \rightarrow \infty} \det \bar{\Omega}_t(\mathbf{u}) = \prod_{\alpha=1}^n \bar{L}_\alpha^2$.

As made clear in the proof of Theorem 1.1, the key step is to obtain a heat measure version of (3.6). This will be our focus of the rest of the proof.

By (1.6) and Lemma 2.5, we have for any $t > 0$ and $\alpha = 1, \dots, n$,

$$2 \int_{3t}^{4t} \int_M |\nabla \nabla \bar{v}_\alpha|^2 d\mu_{x_0}(s) ds \leq \int_M |\nabla \bar{v}_\alpha|^2 d\mu_{x_0}(4t) - \int_M |\nabla \bar{v}_\alpha|^2 d\mu_{x_0}(3t) \\ \leq \Psi_3(t^{-\frac{1}{2}} | m) \bar{L}_\alpha^2,$$

with $\Psi_3(t^{-\frac{1}{2}} | m) \rightarrow 0$ as $t \rightarrow \infty$. So for some $\bar{t} \in [3t, 4t]$, we have

$$2t \int_M |\nabla \nabla \bar{v}_\alpha|^2 d\mu_{x_0}(\bar{t}) \leq \Psi_3(t^{-\frac{1}{2}} | m) \bar{L}_\alpha^2,$$

and by Li-Yau's Harnack inequality (4.5), we have

$$2t \int_M |\nabla \nabla \bar{v}_\alpha|^2 d\mu_{x_0}(3t) \leq \left(\frac{4}{3}\right)^{\frac{3m}{4}} \Psi_3(t^{-\frac{1}{2}} | m) \bar{L}_\alpha^2.$$

For each positive integer j , let i_j be the first index so that $\forall i \geq i_j$,

$$(4.6) \quad 2t_i \int_M |\nabla \nabla \bar{v}_\alpha|^2 d\mu_{x_0}(3t_i) \leq j^{-2m-3} \bar{L}_\alpha^2.$$

We could now estimate as before:

$$\int_M \left| |\omega_{\bar{A}_\infty}|^2 - \det \bar{\Omega}_{t_{i_j}}(\mathbf{v}) \right| d\mu_{x_0}(t_{i_j}) \\ \leq \sum_{\sigma \in S_k} \sum_{\alpha=1}^n \left(\prod_{\beta \neq \alpha} \bar{L}_\beta \bar{L}_{\sigma(\beta)} \right) \int_M \left| \langle \nabla \bar{v}_\alpha, \nabla \bar{v}_{\sigma(\alpha)} \rangle - \int_M \langle \nabla \bar{v}_\alpha, \nabla \bar{v}_{\sigma(\alpha)} \rangle d\mu_{x_0}(t_{i_j}) \right| d\mu_{x_0}(t_{i_j}).$$

For each $\alpha = 1, \dots, n$ and $\sigma \in S_n$, we now apply the weighted Poincaré inequality (Lemma 4.1) with the choice of $R_j := j \sqrt{t_{i_j}}$, the Hölder inequality and (4.6) to see:

$$\int_M \left| \langle \nabla \bar{v}_\alpha, \nabla \bar{v}_{\sigma(\alpha)} \rangle - \int_M \langle \nabla \bar{v}_\alpha, \nabla \bar{v}_{\sigma(\alpha)} \rangle d\mu_{x_0}(t_i) \right| d\mu_{x_0}(t_i) \\ \leq C_{WP} j^{m+1} \sqrt{t_{i_j}} \int_M |\nabla \langle \nabla \bar{v}_\alpha, \nabla \bar{v}_{\sigma(\alpha)} \rangle| d\mu_{x_0}(3t_{i_j}) + \Psi_{WP}(j^{-1} | m) \bar{L}_\alpha \bar{L}_{\sigma(\alpha)} \\ \leq 2C_{WP} j^{-\frac{1}{2}} \bar{L}_\alpha \bar{L}_{\sigma(\alpha)} + \Psi_{WP}(j^{-1} | m) \bar{L}_\alpha \bar{L}_{\sigma(\alpha)}.$$

Therefore as $j \rightarrow \infty$,

$$\int_M \left| |\omega_{\bar{A}_\infty}|^2 - \det \bar{\Omega}_{t_{i_j}}(\mathbf{v}) \right| d\mu_{x_0}(t_{i_j}) \leq (C_{WP} j^{-\frac{1}{2}} + \Psi_{WP}(j^{-1} | m)) \prod_{\alpha=1}^n \bar{L}_\alpha^2 \rightarrow 0.$$

This is the heat measure analogue of (3.6) and it suffices to conclude the proof as argued before. \square

5. DISCUSSION

5.1. Sub-harmonicity of the pull-back energy density. Continuing with the discussion and notations in the introduction, we recall that we have found $|\omega|^2$, as a bounded, non-negative function on M , but is *not* necessarily sub-harmonic. However, there has not been any non-trivial example where the associated pull-back density of a vector valued harmonic map is shown not to be sub-harmonic. Notice that any meaningful example should be considered on a manifold which is non-parabolic (say, the volume of radius r geodesic ball grows at least $\approx r^3$) and with vanishing volume ratio at infinity.

If it were shown that $\Delta|\omega|^2 \geq 0$, then we would not need Theorem 1.2 to conclude (1.8). However, the following computation indicates that one should hardly expect $|\omega|^2$ to be sub-harmonic: Recall that $E_{\alpha\beta} = \langle \nabla u_\alpha, \nabla u_\beta \rangle$ and $\mathbb{E} = [E_{\alpha\beta}]$, a non-negative definite matrix valued function on M . Then $|\omega|^2 = \det \mathbb{E}$, and

$$\begin{aligned} \Delta \det \mathbb{E} &= \sum_{\alpha, \beta=1}^n (-1)^{\alpha+\beta} \nabla \cdot (\det \mathbb{E}_{\alpha\beta}^* \nabla E_{\alpha\beta}) \\ &= \sum_{\alpha, \beta=1}^n (-1)^{\alpha+\beta} \left(\det \mathbb{E}_{\alpha\beta}^* \Delta E_{\alpha\beta} + \sum_{\gamma \neq \alpha, \delta \neq \beta} (-1)^{\gamma+\delta} \det \mathbb{E}_{\alpha\gamma; \beta\delta}^* \langle \nabla E_{\gamma\delta}, \nabla E_{\alpha\beta} \rangle \right) \\ &= \sum_{\alpha, \beta=1}^n \sum_{\gamma \neq \alpha, \delta \neq \beta} (-1)^{\alpha+\beta+\gamma+\delta} \det \mathbb{E}_{\alpha\gamma; \beta\delta}^* (E_{\gamma\delta} \Delta E_{\alpha\beta} + \langle \nabla E_{\gamma\delta}, \nabla E_{\alpha\beta} \rangle), \end{aligned}$$

where we use $\mathbb{E}_{\alpha_1 \dots \alpha_k; \beta_1 \dots \beta_k}^*$ to denote the $(n-k, n-k)$ -matrix obtained by deleting row $\alpha_1, \dots, \alpha_k$ and column β_1, \dots, β_k from \mathbb{E} .

5.2. Directions of future research. The results in this paper leave the following directions open for further investigation:

- (1) For a vector valued harmonic map $\mathbf{u} : M^m \rightarrow \mathbb{R}^n$ ($2 < n \leq m$), we consider the matrix \mathbb{E} and denote the k^{th} -symmetric polynomial of the eigenvalues of \mathbb{E} by σ_k ($k = 1, \dots, n$). Suppose (M^m, g) is complete, non-compact with non-negative Ricci curvature, and \mathbf{u} is of at most linear growth, then Li's identities say that

$$\lim_{\rho \rightarrow \infty} \int_{B(x_0, \rho)} \sigma_1 dV_g = \sup_M \sigma_1 = \lim_{t \rightarrow \infty} \int_M \sigma_1 d\mu_{x_0}(t);$$

while Theorem 1.1 and Theorem 1.2 together tell that

$$\lim_{\rho \rightarrow \infty} \int_{B(x_0, \rho)} \sigma_n dV_g = \sup_M \sigma_n = \lim_{t \rightarrow \infty} \int_M \sigma_n d\mu_{x_0}(t).$$

It is therefore interesting to ask whether such identities hold for the symmetric polynomials in between, i.e. for σ_k with $2 \leq k \leq n-1$, and whether achieving a global maximum of any of such σ_k 's will induce isometric splitting of M .

- (2) On the other direction, it is interesting to consider more general harmonic maps $\mathbf{u} : (M^m, g) \rightarrow (N^n, h)$ into a Cartan-Hadamard manifold N (i.e. (N, h) has non-positive sectional curvature everywhere). Assume that (M^m, g) is complete, non-compact and has non-negative Ricci curvature, then by the Weitzenböck formula,

we have

$$\begin{aligned} \Delta|\nabla\mathbf{u}|^2 &= 2|\nabla\nabla\mathbf{u}|^2 + 2\sum_{\alpha,\beta=1}^m \text{Tr}_h(\mathcal{R}c_{\alpha\beta}^M \nabla_\alpha \mathbf{u} \nabla_\beta \mathbf{u}) - \sum_{\alpha,\beta=1}^m (\mathbf{u}^* \mathcal{R}m^N)_{\alpha\beta\beta\alpha} \\ &\geq 2|\nabla\nabla\mathbf{u}|^2. \end{aligned}$$

It is clear that if \mathbf{u} has uniformly bounded energy density, then same argument as before (see Lemma 2.5) gives

$$\lim_{t \rightarrow \infty} \int_M |\nabla\mathbf{u}|^2 d\mu_{x_0}(t) = \sup_M |\nabla\mathbf{u}|^2.$$

Thus if $|\nabla\mathbf{u}|^2$ achieves the global maximum, then $|\nabla\nabla\mathbf{u}| \equiv 0$, so N has to be the n -dimensional Euclidean space and M isometrically splits \mathbb{R}^n . Again, it is interesting to see if such maximum principle still holds for the corresponding σ_k for $k > 1$, i.e. if any σ_k sees a global maximum on M , then both $N \equiv \mathbb{R}^n$ and $M \equiv M' \times \mathbb{R}^n$. See [19] for more information in this direction.

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