

REGULAR SOLUTIONS TO THE FRACTIONAL EULER ALIGNMENT SYSTEM IN THE BESOV SPACES FRAMEWORK

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ABSTRACT. We here construct (large) local and small global-in-time regular unique solutions to the fractional Euler alignment system in the whole space \mathbb{R}^d , in the case where the deviation of the initial density from a constant is sufficiently small. Our analysis strongly relies on the use of Besov spaces of the type $L^1(0, T; \dot{B}_{p,1}^s)$, which allow to get time independent estimates for the density even though it satisfies a transport equation with no damping. Our choice of a functional setting is not optimal but aims at providing a transparent and accessible argumentation.

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1. INTRODUCTION

Collective dynamics of interactive particles leading to an emergent phenomenon is an increasingly popular subject of research with a number of applications ranging from biology or robotics to social sciences [30, 34]. The common trait of such models is that relatively simplistic agents basing their behavior on limited information produce a complex structure like in e.g. anthills or specific formations of birds. Interestingly, this may be also observed in seemingly more sophisticated phenomena, such as emergence of languages in primitive cultures [25], distribution of goods [41] or gang-related crime [39].

From the mathematical viewpoint, these models are a source of many challenging problems like deriving the kinetic and then hydrodynamic models from basic ODE systems. One may mention e.g. the well-known Hilbert's sixth problem of axiomatization of mathematical physics, that consists in providing a mathematically rigorous derivation of Boltzmann and Euler equations from the Newtonian particle systems.

The model of interactive particles we aim at considering here is the following Euler-type hydrodynamic version of the Cucker-Smale (CS) flocking model introduced in [8]:

$$(1) \quad \begin{cases} \rho_t + \operatorname{div}(\rho u) = 0, \\ \rho u_t + \rho(u \cdot \nabla)u = \int_{\mathbb{R}^d} \left(\frac{u(t, y) - u(t, x)}{|y - x|^{d+\alpha}} \right) \rho(t, x) \rho(t, y) \, dy . \end{cases}$$

We refer to (1) as the *fractional Euler flocking system*. Here $\rho(t, x) \in \mathbb{R}_+$ denotes the density of particles at position $x \in \mathbb{R}^d$ and time $t > 0$. The vector field $u(t, x) \in \mathbb{R}^d$ represents the velocity of a particle that occupies the position $x \in \mathbb{R}^d$ at time $t \in \mathbb{R}_+$. The exponent α is assumed to be in the range $(1, 2)$.

We further suppose that the velocity tends to 0 at infinity, and that the density goes to some positive constant (say 1 with no loss of generality), in a sense that will be made clear once we will have introduced our functional setting (see below).

Before we proceed, let us elaborate on the origin of the system. Going back to the ODE's and kinetic theory we begin with the CS model governed by the following system of N particles

$$(2) \quad \begin{cases} \frac{d}{dt}x_i &= v_i, \\ \frac{d}{dt}v_i &= \frac{1}{N} \sum_{j=1}^N (v_j - v_i)\psi(|x_i - x_j|), \end{cases}$$

where $x_i(t)$ and $v_i(t)$ denote the position and velocity of the i -th particle at time t . The function ψ , referred to as the *communication weight*, is usually non-negative, non-increasing and Lipschitz continuous.

The CS model is a simple example of interacting particles' models that has been extensively studied in various, mostly qualitative, directions such as collision avoidance [1, 6, 4] and asymptotic and pattern formation [5, 16]. These two directions lead to further branching of research into the CS model with singular communication weight [31, 32], or various additional forces that ensure specific asymptotic pattern formation [15, 17] or under a leadership of selected individuals [7, 35].

Further, taking $N \rightarrow \infty$ in (2), we formally obtain the kinetic equation

$$(3) \quad f_t + v \cdot \nabla_x f + \operatorname{div}_v [F(f)f] = 0,$$

with $F(f)(t, x, v) := \int_{\mathbb{R}^d \times \mathbb{R}^d} (w - v)\psi(|x - y|)f(t, y, w) \, dy \, dw,$

where $f(t, x, v)$ stands for the distribution of the particles that at time t have position x and velocity v .

The mathematical derivation of (3) is a challenging problem that has been considered in e.g. [18, 19]. Particularly interesting from the point of view of this paper is the case of singular communication weight $\psi(s) = s^{-\gamma}$ which was studied in [28, 20].

Finally, taking the hydrodynamical limit

$$f(t, x, v) = \rho(t, x)\delta_{u(t, x)}$$

in (3) and integrating over \mathbb{R}_v^d , we find out the continuity equation (1)₁. As for the momentum equation (1)₂, it is obtained by testing with $v\rho(t, x)\delta_{u(t, x)}$.

The mathematically rigorous derivation of (1) as a hydrodynamic limit of (3) has not yet been solved in full generality (see e.g. [33] for recent developments in this direction). It is worthwhile noting that the cases of regular and singular communication weights are significantly different. In the present paper, we consider the singular communication weight $\psi(s) = s^{-\gamma}$ with $\gamma = d + \alpha$ and $\alpha \in (1, 2)$. Let us point out that (1) can be alternatively counted as an element of non-classical hydrodynamics related to the description of phenomena of aggregation, flocking, and in general, of modeling of collective dynamics of interacting particles. It may be seen as a coupling between the classical continuity equation and a nonlinear parabolic system of fractional order, and analyzed by means of techniques that are barely related to the kinetic origin of the system.

Let us now bring the reader up to date with the research on system (1). Precisely this model but in the periodic 1D case has been investigated by Do *et al.* in [13] and simultaneously by Shvydkoy and Tadmor in [36, 37, 38]. The main advantage of dimension 1 is that $u(t)$ and $\rho(t)$ are real numbers, and can thus be directly compared. Indeed, an easy calculation then reveals that quantity

$$e(t, x) := u_x(t, x) + \int_{\mathbb{T}} \psi(|x - y|)(\rho(t, x) - \rho(t, y)) \, dy$$

satisfies

$$e_t + (ue)_x = 0.$$

Thanks to these relations, one can compare the regularity of u and ρ and, using the compactness of the 1D torus, obtain a global-in-time positive lower bound on the density, thanks to which the “good” term on the right-hand side of (1)₂ does not disappear. That method unfortunately fails in higher dimension. Another approach is used in [21, 40], where the 1D and 2D models with compact initial data are studied by the method of characteristic.

Our goal here is to provide a general existence result in any dimension $d \geq 1$, and to connect this class of problems to the well-developed language of Besov spaces. Our main result reads:

Theorem 1.1. *Assume that $\alpha \in (1, 2)$ and consider initial data (ρ_0, u_0) so that u_0 and ∇u_0 are in $\dot{B}_{d,1}^{2-\alpha}$, and $\rho_0 - 1$ and $\nabla \rho_0$ are in $\dot{B}_{d,1}^1$. There exists $\varepsilon > 0$ such that if in addition*

$$(4) \quad \|u_0\|_{\dot{B}_{d,1}^{2-\alpha}} + \|\rho_0 - 1\|_{\dot{B}_{d,1}^1} < \varepsilon,$$

then the fractional Euler system (1) has a unique global solution (ρ, u) such that

$$u, \nabla u \in \mathcal{C}_b(\mathbb{R}_+; \dot{B}_{d,1}^{2-\alpha}) \cap L^1(\mathbb{R}_+; \dot{B}_{d,1}^2) \quad \text{and} \quad (\rho - 1), \nabla \rho \in \mathcal{C}_b(\mathbb{R}_+; \dot{B}_{d,1}^1).$$

In the case where the smallness condition is fulfilled only by ρ_0 then there exist a unique solution (ρ, u) on some time interval $[0, T]$ with $T > 0$ so that

$$u, \nabla u \in \mathcal{C}_b([0, T]; \dot{B}_{d,1}^{2-\alpha}) \cap L^1([0, T]; \dot{B}_{d,1}^2) \quad \text{and} \quad (\rho - 1), \nabla \rho \in \mathcal{C}_b([0, T]; \dot{B}_{d,1}^1).$$

Let us point out that the above result is not quite optimal as regards regularity assumptions. Indeed, the reader may check that System (1) is invariant for all $\lambda > 0$ by the rescaling

$$\rho(t, x) \rightsquigarrow \rho(\lambda^\alpha t, \lambda x) \quad \text{and} \quad u(t, x) \rightsquigarrow \lambda^{\alpha-1} u(\lambda^\alpha t, \lambda x).$$

Optimal spaces for well-posedness are thus expected to have the above invariance. In the class of Besov spaces that we considered above, this would correspond to taking initial data such that $(\rho_0 - 1, u_0)$ is only in $\dot{B}_{d,1}^1 \times \dot{B}_{d,1}^{2-\alpha}$. The smallness condition (4) is thus at the critical level of regularity, but one more derivative is required on the data. The reason we choose to work with so much regularity is essentially to offer the reader an elementary proof with as less as possible technicalities. This choice gives us the possibility to obtain solutions in the class that naturally comes from the a priori estimate, and higher regularity allows to control uniqueness. From the mathematical viewpoint the biggest challenge is to control the regularity of density for all time (if (4) is fulfilled). Roughly speaking, the transport theory requires the velocity field to be at least in $L^1(0, \mathbb{R}_+; \text{Lip})$, and it is guaranteed by regularity $L^1(\mathbb{R}_+; \dot{B}_{d,1}^2)$ of the vector field obtained by analysis of (1)₂. We derive estimates of solutions to (1) at this level of regularity, but they are insufficient to prove the uniqueness, owing to the hyperbolic nature of the continuity equation. Here the troublemaker is the nonlinear nonlocal term

$$\int_{\mathbb{R}^d} \left(\frac{u(t, y) - u(t, x)}{|y - x|^{d+\alpha}} \right) \rho(t, x) \rho(t, y) \, dy,$$

which, for too low regularity, cannot be estimated properly.

It is not clear whether one could find a suitable setting to avoid higher regularity like in [23] or [11]. Here we chose to increase the regularity of solutions by one derivative. That choice is the simplest one as it enables us to use essentially the same functional setting for the solution and its first order space derivatives.

As a general remark we would like to underline that Theorem 1.1 can be seen as a first quantitative result for system (1), which allows to investigate interesting qualitative properties of solutions to the studied system. The basic energy balance for (1)

$$\frac{d}{dt} \int_{\mathbb{R}^d} \rho |u|^2 dx + \int_{\mathbb{R}^d \times \mathbb{R}^d} \frac{|u(x) - u(y)|^2}{|x - y|^{d+\alpha}} \rho(x) \rho(y) \, dy \, dx = 0$$

leads, under the assumption $\rho \approx 1$, to the asymptotic decay of the velocity to 0. However, since we are working in whole space, proving exponential decay is impossible (in contrast with [13]

that analysis the system with periodic boundary conditions, in the one-dimensional case). The information coming from Theorem 1.1 allows to obtain the following information concerning the decay of the velocity at infinity, showing the expected flocking (see the proof in Appendix).

Corollary 1.1. *Let (ρ, u) be a global in time solution given by Theorem 1.1. Then*

$$\|u(t)\|_{L^\infty} \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

System (1) is comparable to the classical compressible Navier-Stokes system. The main difference for us is the lack of an ‘effective viscous flux’ (like $-\operatorname{div} u + p(\rho)$ for the compressible Navier-Stokes system) enabling us to glean some time-decay or compactness for the density. Recall that exhibiting such a quantity is the cornerstone of the proof of global results both for weak solutions [14, 24, 29] or regular solutions [9, 26, 27]. In the case of (1), the only way to control regularity of the density is through the velocity, whence the need of the L^1 integrability in time of suitable norms of u . This is of course closely connected with our choice of Besov spaces of the type $\dot{B}_{p,1}^s$.

The paper is organized as follows. In Section 2 we introduce the notation and basic definitions and tools related to Besov spaces. Then, in Section 3, we reformulate the main result and give an overview of the proof. Finally, in Section 4, we prove Theorem 1.1. For the reader convenience, we include in the appendix basic existence results for the continuity and the linearized momentum equations in Besov spaces and the proof of Corollary 1.1.

2. PRELIMINARIES

Let us shortly introduce the main notation of the paper. By \mathcal{S} we denote the Schwartz space and consequently \mathcal{S}' is the space of tempered distributions. The Fourier transform of u with respect to the space variable is denoted by $\mathcal{F}u = \widehat{u}$. We shall use $\|\cdot\|_p$ to denote the norm in the space $L^p(\mathbb{R}^d)$. Finally, we use the abbreviated form $L_T^p X$ for the space $L^p(0, T; X)$ and $L^p X$ means $L^p(\mathbb{R}_+; X)$. Throughout the paper the letter C denotes a generic constant.

Let us next introduce the *fractional Laplacian* and *homogeneous Besov spaces*.

Fractional Laplacian. Let $u : \mathbb{R}^d \mapsto \mathbb{R}$ be a Schwartz function and $\alpha \in (0, 2)$. Then, the fractional Laplacian of u is given by

$$(5) \quad (-\Delta)^{\alpha/2} u(x) = -c_{d,\alpha} \operatorname{pv} \int_{\mathbb{R}^d} \frac{u(x) - u(y)}{|x - y|^{d+\alpha}} dy.$$

Here pv stands for the principal value of integral and $c_{d,\alpha}$ is a dimensional constant that ensures that for all smooth enough function u on \mathbb{R}^d , we have¹

$$(-\Delta)^{\alpha/2} u = \mathcal{F}^{-1} \{ |\xi|^\alpha \widehat{u}(\xi) \}.$$

As can be easily observed by looking on the Fourier side, operator $(-\Delta)^{\alpha/2}$ maps the subspace \mathcal{S}_0 of \mathcal{S} functions with Fourier transform supported away from the origin, to itself.

Besov spaces. Let χ be a smooth function compactly supported in the ball $B(0, \frac{4}{3})$, and set $\varphi(\xi) := \chi(\xi/2) - \chi(\xi)$ so that φ is smooth, supported in the annulus $B(0, \frac{8}{3}) \setminus B(0, \frac{3}{4})$ and fulfills

$$\sum_{j \in \mathbb{Z}} \varphi(2^{-j} \xi) = 1 \quad \text{on } \mathbb{R}^d \setminus \{0\}.$$

Let us introduce

$$h = \mathcal{F}^{-1} \varphi \quad \text{and} \quad \widetilde{h} = \mathcal{F}^{-1} \chi.$$

¹According to e.g. [3, formula (2.15)], we have $c_{d,\alpha} = \frac{2^\alpha \Gamma(d/2 + \alpha/2)}{\pi^{d/2} \Gamma(-\alpha/2)}$.

The homogeneous dyadic blocks $\dot{\Delta}_j$ are defined for all $j \in \mathbb{Z}$ by

$$\dot{\Delta}_j u := 2^{jd} \int_{\mathbb{R}^d} h(2^j y) u(x - y) dy = \mathcal{F}^{-1}(\varphi(2^{-j} \cdot) u).$$

The homogeneous low-frequency cut-off operator \dot{S}_j is defined by

$$\dot{S}_j u := 2^{jd} \int_{\mathbb{R}^d} \tilde{h}(2^j y) u(x - y) dy = \mathcal{F}^{-1}(\chi(2^{-j} \cdot) u).$$

All of the above operators are bounded in L^p with norms independent of j and p .

For $s \in \mathbb{R}$ and $p, q \in [1, \infty]$, we introduce the following homogeneous Besov (semi)-norms :

$$\|u\|_{\dot{B}_{p,q}^s} := \left\| 2^{js} \|\dot{\Delta}_j u\|_p \right\|_{\ell^q(\mathbb{Z})}.$$

Then, following [2], we define the homogeneous Besov space to be the set of tempered distributions u so that

$$\|u\|_{\dot{B}_{p,q}^s} < \infty \quad \text{and} \quad \lim_{j \rightarrow -\infty} \|\dot{S}_j u\|_\infty = 0.$$

The low frequency condition guarantees that $\dot{B}_{p,q}^s$ is a normed space.

In the case $s \in (0, 1)$, equivalent norms may be defined in terms of finite difference. More precisely, for a given function $f : \mathbb{R}^d \mapsto \mathbb{R}^m$ and $y \in \mathbb{R}^d$, let us denote

$$(6) \quad \Delta_y f(x) := f(x + y) - f(x).$$

Then we have (see e.g. [2, p. 74]) for all function u in \mathcal{S} , the following equivalence:

$$(7) \quad c \|u\|_{\dot{B}_{p,q}^s} \leq \left\| \frac{\|\Delta_y u\|_p}{|y|^{d+s}} \right\|_q \leq C \|u\|_{\dot{B}_{p,q}^s},$$

where the positive constants c and C depend only on s, d and p .

As in the rest of the paper, we will only consider Besov spaces with finite p , and $q = 1$, we just enumerate in the following lemma the most important properties of those spaces (see [2, Chap. 2] for more details).

Lemma 2.1 (Basic properties of homogeneous Besov spaces). *(a) The space $\dot{B}_{p,1}^s$ is complete whenever $s \leq d/p$.*

(b) If p is finite then \mathcal{S}_0 is dense in $\dot{B}_{p,1}^s$, and so does \mathcal{S} if $s > -d/p'$.

(c) We have the continuous embedding $\dot{B}_{p,1}^s \hookrightarrow \dot{B}_{q,1}^{s-d/p+d/q}$ for all $1 \leq p \leq q \leq \infty$, and the homogeneous Besov space $\dot{B}_{d,1}^1$ is continuously embedded in the space of continuous functions vanishing at infinity.

(d) For all $s_1 < s_2$ and $\theta \in (0, 1)$ we have $\dot{B}_{p,1}^{s_1} \cap \dot{B}_{p,1}^{s_2} \subset \dot{B}_{p,1}^{\theta s_1 + (1-\theta)s_2}$ and

$$\|u\|_{\dot{B}_{p,1}^{\theta s_1 + (1-\theta)s_2}} \leq \|u\|_{\dot{B}_{p,1}^{s_1}}^\theta \|u\|_{\dot{B}_{p,1}^{s_2}}^{1-\theta}.$$

(e) For any $s \in \mathbb{R}$ and $p \in [1, \infty]$, the gradient operator maps $\dot{B}_{p,1}^{s+1}$ to $\dot{B}_{p,1}^s$.

(f) For any $s \leq d/p$ and $p \in [1, \infty)$ the operator $(-\Delta)^{\alpha/2}$ maps $\dot{B}_{p,1}^{s+\alpha}$ to $\dot{B}_{p,1}^s$.

(g) The space $\dot{B}_{d,1}^1$ is stable by product, and there exists $C > 0$ independent of u and v such that we have

$$\|uv\|_{\dot{B}_{d,1}^1} \leq C \|u\|_{\dot{B}_{d,1}^1} \|v\|_{\dot{B}_{d,1}^1}.$$

(h) For any $\alpha \in [1, 2]$ and $\theta \in [0, \alpha - 1]$, we have

$$(8) \quad \|uv\|_{\dot{B}_{d,1}^{2-\alpha}} \leq C \|u\|_{\dot{B}_{d,1}^{1-\theta}} \|v\|_{\dot{B}_{d,1}^{2+\theta-\alpha}};$$

(i) Let w be a vector field over \mathbb{R}^d . Define

$$R_j := [w \cdot \nabla, \Delta_j]u = w \cdot \nabla \dot{\Delta}_j u - \dot{\Delta}_j (w \cdot \nabla u).$$

If $-1 < s \leq 2$ then there exists a positive constant C , independent of u and w , such that

$$\|R_j\|_{\dot{B}_{d,1}^s} \leq C \|\nabla w\|_{\dot{B}_{d,1}^1} \|u\|_{\dot{B}_{d,1}^s}.$$

Proof. For the proofs of the above statements we redirect the reader to standard references regarding Besov spaces. More specifically, (a), (b), (c), (d), (e – f) and (g) follow from [2], Theorem 2.25, Proposition 2.27, Proposition 2.39, Proposition 2.22, Proposition 2.30 and Corollary 2.54, respectively. As for (i), it is a particular case of Lemma 2.100. Finally, (8) stems from the results of continuity of the remainder and paraproduct operators that are stated in [2, Theorems 2.47 and 2.52] (see also [10, Lemma 1.5] for a more detailed proof). \square

3. RENORMALIZED SYSTEM AND RESTATEMENT OF THE MAIN RESULT

In order to properly define all elements of system (1) in low regularity, we renormalize it in three steps. First, we rewrite (1)₁ as an equation on $\sigma := \rho - 1$. Next, we divide (1)₂ by ρ and replace ρ by $1 + \sigma$ in the last term of (1)₂. Taking advantage of (5) and denoting $\mu := c_{d,\alpha}^{-1}$, we eventually obtain

$$(9) \quad \begin{cases} \sigma_t + \operatorname{div}(\sigma u) &= -\operatorname{div} u, \\ u_t + \mu(-\Delta)^{\alpha/2} u &= F(u, \sigma) \end{cases}$$

with

$$(10) \quad \begin{aligned} F(u, \sigma) &:= I_\alpha(u, \sigma) - \mu\sigma(-\Delta)^{\alpha/2} u - (u \cdot \nabla)u \\ \text{and } I_\alpha(u, \sigma) &:= \operatorname{pv} \int_{\mathbb{R}^d} \left(\frac{u(x+y) - u(x)}{|y|^{d+\alpha}} \right) (\sigma(x+y) - \sigma(x)) \, dy. \end{aligned}$$

Throughout the paper we consider system (9), noting that it is equivalent to (1) for sufficiently smooth solutions. The main result of the paper restated in the above setting reads as follows:

Theorem 3.1. *Assume that $\alpha \in (1, 2)$. There exists $\varepsilon > 0$, such that the fractional Euler system (9) with initial data u_0 and σ_0 satisfying*

$$(11) \quad \|u_0\|_{\dot{B}_{d,1}^{2-\alpha}} + \|\sigma_0\|_{\dot{B}_{d,1}^1} < \varepsilon$$

and $\nabla u_0 \in \dot{B}_{d,1}^{2-\alpha}$, $\nabla \sigma_0 \in \dot{B}_{d,1}^1$ admits a unique global in time solution (σ, u) with

$$u, \nabla u \in L^1(\mathbb{R}_+; \dot{B}_{d,1}^2) \cap \mathcal{C}_b(\mathbb{R}_+; \dot{B}_{d,1}^{2-\alpha}) \quad \text{and} \quad \sigma, \nabla \sigma \in \mathcal{C}_b(\mathbb{R}_+; \dot{B}_{d,1}^1).$$

If Condition (11) is fulfilled only by σ_0 then there exists a time $T > 0$ that may be bounded from below in terms of the norms of the data, and such that system (9) with initial data u_0 and σ_0 admits a unique solution (σ, u) on $[0, T]$ with

$$(12) \quad u, \nabla u \in L^1(0, T; \dot{B}_{d,1}^2) \cap \mathcal{C}_b([0, T]; \dot{B}_{d,1}^{2-\alpha}) \quad \text{and} \quad \sigma, \nabla \sigma \in \mathcal{C}_b([0, T]; \dot{B}_{d,1}^1).$$

Let us briefly present the main steps of the proof of Theorem 3.1. Renormalization of (1) into (9) is the primary idea behind our approach, as it reduces our problem to the coupling of two well known equations, namely

$$(13) \quad \partial_t \sigma + \operatorname{div}(u\sigma) = f_1,$$

$$(14) \quad \partial_t u + \mu(-\Delta)^{\frac{\alpha}{2}} u = f_2.$$

As $\alpha \in (1, 2)$ and the external forces f_1 and f_2 are smooth, strong existence to equations (13) and (14) is relatively easy to obtain. In our case however, the external forces are dependent on u and σ , which makes the problem more complicated and pushes us to consider small initial

data for getting a global statement. The main difficulty comes from the nonlocal bilinear term $I_\alpha(u, \sigma)$ appearing in (10). It will be handled thanks to the following lemma:

Lemma 3.1. *Assume that $\alpha \in (1, 2)$ and that $\theta \in [0, \min(2 - \alpha, \alpha - 1)]$. There exists $K > 0$ such that for all u and σ in $\mathcal{S}(\mathbb{R}^d)$, we have*

$$\|I_\alpha(u, \sigma)\|_{\dot{B}_{d,1}^{2-\alpha}} \leq K \|\nabla u\|_{\dot{B}_{d,1}^{1-\theta}} \|\sigma\|_{\dot{B}_{d,1}^{1+\theta}},$$

where I_α is defined by (10).

The proof of Theorem 3.1 can be summarized by the following steps:

- (1) We begin with the proof of Lemma 3.1.
- (2) We introduce an iterative scheme that, somehow, decouples system (9). It is complemented with smooth and decaying initial data that approximate (σ_0, u_0) .
- (3) The iterative scheme produces a sequence (σ^n, u^n) of global smooth approximate solutions that solve equations of the form (13) and (14). Assuming that (11) is fulfilled, we obtain uniform estimates for the sequence in the critical space $L^\infty \dot{B}_{d,1}^1 \times (L^1 \dot{B}_{d,1}^2 \cap L^\infty \dot{B}_{d,1}^{2-\alpha})$.
- (4) We estimate (σ^n, u^n) in higher-order spaces by differentiating equations on σ^n and u^n .
- (5) Thanks to the higher-order estimates we are able to establish that (σ^n, u^n) is a Cauchy sequence in the space

$$\mathcal{C}([0, T]; \dot{B}_{d,1}^1) \times (\mathcal{C}([0, T]; \dot{B}_{d,1}^{2-\alpha}) \cap L_T^1 \dot{B}_{d,1}^2), \quad \text{for all } T \geq 0.$$

- (6) We show that the limit (σ, u) of that Cauchy sequence fulfills system (9) and that it does have the regularity stated in Theorem 3.1.
- (7) Assuming only that σ_0 is small, we prove the existence of a time $T > 0$ and of a solution (σ, u) to (9) in the space (12).
- (8) We give a proof of uniqueness that requires only σ to be small for one of the two solutions.

4. PROOF OF THE MAIN RESULT

We begin with the study of the nonlocal term.

Step 1: Proof of Lemma 3.1. For u in $\mathcal{S}(\mathbb{R}^d)$, one may write, using the notation of (6),

$$\Delta_y u(x) = u(x + y) - u(x) = y \cdot \int_0^1 \nabla u(x + ty) dt,$$

so that the operator I_α can be written as

$$\begin{aligned} I_\alpha(u, \sigma)(x) &= \int_{\mathbb{R}^d} \int_0^1 \left(\frac{y}{|y|^{d+\alpha}} \cdot \nabla u(x + ty) \right) (\sigma(x + y) - \sigma(x)) dt dy \\ &= \underbrace{\int_{\mathbb{R}^d} \int_0^1 \left(\frac{y}{|y|^{d+\alpha}} \cdot \Delta_{yt} \nabla u(x) \right) \Delta_y \sigma(x) dt dy}_{=: A(x)} + \underbrace{\int_{\mathbb{R}^d} \left(\frac{y}{|y|^{d+\alpha}} \cdot \nabla u(x) \right) \Delta_y \sigma(x) dy}_{=: B(x)}. \end{aligned}$$

In light of (7) and triangular inequality, one thus has

$$\|I_\alpha\|_{\dot{B}_{d,1}^{2-\alpha}} \leq \|A\|_{\dot{B}_{d,1}^{2-\alpha}} + \|B\|_{\dot{B}_{d,1}^{2-\alpha}} \leq C \left\| \frac{\|\Delta_h A(\cdot)\|_d}{|h|^{d+2-\alpha}} \right\|_1 + \|B\|_{\dot{B}_{d,1}^{2-\alpha}}.$$

Now, the trivial identity

$$\Delta_y(gf)(x) = g(x + y)\Delta_y f(x) + f(x)\Delta_y g(x).$$

implies that

$$\Delta_h(\Delta_{ty} \nabla u(x) \cdot \Delta_y \sigma(x)) = \Delta_{ty} \nabla u(x + h) \cdot \Delta_h \Delta_y \sigma(x) + \Delta_y \sigma(x) \cdot \Delta_h \Delta_{ty} \nabla u(x),$$

whence

$$\begin{aligned} \Delta_h A(x) &= \underbrace{\int_{\mathbb{R}^d} \int_0^1 \left(\frac{y}{|y|^{d+\alpha}} \cdot \Delta_{ty} \nabla u(x+h) \right) \Delta_h \Delta_y \sigma(x) \, dt \, dy}_{=: E(x,h)} + \underbrace{\int_{\mathbb{R}^d} \int_0^1 \left(\frac{y}{|y|^{d+\alpha}} \Delta_y \sigma(x) \right) \cdot \Delta_h \Delta_{ty} \nabla u(x) \, dt \, dy}_{=: F(x,h)} \end{aligned}$$

which leads to

$$\left\| \frac{\|\Delta_h A(\cdot)\|_d}{|h|^{d+2-\alpha}} \right\|_1 \leq \left\| \frac{\|E(\cdot, h)\|_d}{|h|^{d+2-\alpha}} \right\|_1 + \left\| \frac{\|F(\cdot, h)\|_d}{|h|^{d+2-\alpha}} \right\|_1.$$

We estimate the term $\left\| \frac{\|E(\cdot, h)\|_d}{|h|^{d+2-\alpha}} \right\|_1$ in the following way (where exponents q and q' fulfill the relation $1/q + 1/q' = 1/d$):

$$\begin{aligned} \left\| \frac{\|E(\cdot, h)\|_d}{|h|^{d+2-\alpha}} \right\|_1 &= \\ &= \int_{\mathbb{R}^d} \frac{1}{|h|^{d+2-\alpha}} \left(\int_{\mathbb{R}^d} \left| \int_{\mathbb{R}^d} \int_0^1 \frac{y}{|y|^{d+\alpha}} \cdot \Delta_{ty} \nabla u(x+h) \cdot \Delta_h \Delta_y \sigma(x) \, dt \, dy \right|^d dx \right)^{1/d} dh \\ &\leq \int_{\mathbb{R}^d} \frac{1}{|h|^{d+2-\alpha}} \int_{\mathbb{R}^d} \frac{1}{|y|^{d+\alpha-1}} \cdot \int_0^1 \|\Delta_{ty} \nabla u(\cdot + h) \cdot \Delta_h \Delta_y \sigma(\cdot)\|_d \, dt \, dy \, dh \\ &\leq \int_{\mathbb{R}^d} \frac{1}{|h|^{d+2-\alpha}} \int_{\mathbb{R}^d} \frac{1}{|y|^{d+\alpha-1}} \cdot \int_0^1 \|\Delta_{ty} \nabla u(\cdot + h)\|_q \cdot \|\Delta_h \Delta_y \sigma\|_{q'} \, dt \, dy \, dh \\ &\leq \int_{\mathbb{R}^d} \frac{1}{|h|^{d+2-\alpha}} \int_{\mathbb{R}^d} \frac{1}{|y|^{d+\alpha-1}} \int_0^1 \|\Delta_{ty} \nabla u\|_q \cdot \|\Delta_h \Delta_y \sigma\|_{q'} \, dt \, dy \, dh \\ &= \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \frac{\|\Delta_h \Delta_y \sigma\|_{q'}}{|h|^{d+2-\alpha}} \cdot \int_0^1 \frac{\|\Delta_{ty} \nabla u\|_q}{|y|^{d+\alpha-1}} \, dt \, dy \, dh \\ &\leq \int_{\mathbb{R}^d} \sup_y \left\{ \frac{\|\Delta_h \Delta_y \sigma\|_{q'}}{|h|^{d+2-\alpha}} \right\} \cdot \int_0^1 \int_{\mathbb{R}^d} \frac{\|\Delta_{ty} \nabla u\|_q}{|y|^{d+\alpha-1}} \, dt \, dy \, dh \\ &= \frac{1}{\alpha} \int_{\mathbb{R}^d} \frac{\|\Delta_z \nabla u\|_q}{|z|^{d+\alpha-1}} \, dz \cdot \int_{\mathbb{R}^d} \sup_y \left\{ \frac{\|\Delta_h \Delta_y \sigma\|_{q'}}{|h|^{d+2-\alpha}} \right\} \, dh. \end{aligned}$$

Here we have used the fact that the norm of a function is translation invariant. As $\|\Delta_h \Delta_y \sigma\|_{q'} = \|\Delta_y \Delta_h \sigma\|_{q'} \leq 2\|\Delta_h \sigma\|_{q'}$ we finally obtain

$$\left\| \frac{\|E(\cdot, h)\|_d}{|h|^{d+2-\alpha}} \right\|_1 \leq C \int_{\mathbb{R}^d} \frac{\|\Delta_z \nabla u\|_q}{|z|^{d+\alpha-1}} \, dz \cdot \int_{\mathbb{R}^d} \frac{\|\Delta_h \sigma\|_{q'}}{|h|^{d+2-\alpha}} \, dh.$$

We use Lemma 2.1 to determine what the exponent q should be to match with our assumptions that $\nabla u \in \dot{B}_{d,1}^{1-\theta}$ and $\sigma \in \dot{B}_{d,1}^{1+\theta}$.

- In order to obtain the embedding $\dot{B}_{d,1}^{1-\theta} \subset \dot{B}_{q,1}^{\alpha-1}$, $[2-\alpha \geq \theta]$ we need $q \geq d$ and

$$\frac{1+\theta}{d} = \frac{2-\alpha}{d} + \frac{1}{q}.$$

- In order to obtain the embedding $\dot{B}_{d,1}^{1+\theta} \subset \dot{B}_{q',1}^{2-\alpha}$, we need $q' \geq d$ and

$$\frac{1-\theta}{d} = \frac{\alpha-1}{d} + \frac{1}{q'}.$$

These two conditions uniquely determine the exponents to be

$$q = \frac{d}{\alpha + \theta - 1} \quad \text{and} \quad q' = \frac{d}{2 - \alpha - \theta}.$$

Clearly, $1/q + 1/q' = 1/d$ and our conditions on θ guarantee that $q, q' \geq d$. So, using the above embeddings, we conclude that

$$\left\| \frac{\|E(\cdot, h)\|_d}{|h|^{d+2-\alpha}} \right\|_1 \leq C \|\nabla u\|_{\dot{B}_{q,1}^{\alpha-1}} \|\sigma\|_{\dot{B}_{q',1}^{2-\alpha}} \leq C \|\nabla u\|_{\dot{B}_{d,1}^{1-\theta}} \|\sigma\|_{\dot{B}_{d,1}^{1+\theta}}.$$

Analogous calculations can be performed for bounding the term with F : we introduce another two exponents r and r' such that $1/r + 1/r' = 1/d$, and write that

$$\begin{aligned} \left\| \frac{\|F(\cdot, h)\|_d}{|h|^{d+2-\alpha}} \right\|_1 &= \int_{\mathbb{R}^d} \frac{1}{|h|^{d+2-\alpha}} \left(\int_{\mathbb{R}^d} \left| \int_{\mathbb{R}^d} \int_0^1 \left(\frac{y}{|y|^{d+\alpha}} \Delta_y \sigma(x) \right) \cdot \Delta_h \Delta_{ty} \nabla u(x) \, dt \, dy \right|^d dx \right)^{1/d} dh \\ &\leq \int_{\mathbb{R}^d} \frac{1}{|h|^{d+2-\alpha}} \int_{\mathbb{R}^d} \frac{1}{|y|^{d+\alpha-1}} \int_0^1 \|\Delta_y \sigma(\cdot) \Delta_h \Delta_{ty} \nabla u(\cdot)\|_d \, dt \, dy \, dh \\ &\leq \int_{\mathbb{R}^d} \frac{1}{|h|^{d+2-\alpha}} \int_{\mathbb{R}^d} \frac{1}{|y|^{d+\alpha-1}} \int_0^1 \|\Delta_y \sigma(\cdot)\|_r \|\Delta_h \Delta_{ty} \nabla u(\cdot)\|_{r'} \, dt \, dy \, dh \\ &\leq \int_{\mathbb{R}^d} \frac{1}{|h|^{d+2-\alpha}} \int_{\mathbb{R}^d} \frac{2}{|y|^{d+\alpha-1}} \|\Delta_y \sigma(\cdot)\|_r \|\Delta_h \nabla u(\cdot)\|_{r'} \, dy \, dh \\ &\leq C \|\sigma\|_{\dot{B}_{r,1}^{\alpha-1}} \|\nabla u\|_{\dot{B}_{r',1}^{2-\alpha}}. \end{aligned}$$

At this stage, we use the following embeddings (keeping in mind that $0 \leq \theta \leq \alpha - 1$):

$$\begin{aligned} \dot{B}_{d,1}^{1+\theta} &\hookrightarrow \dot{B}_{r,1}^{\alpha-1} \quad \text{with} \quad r = \frac{d}{\alpha - \theta - 1} \\ \text{and} \quad \dot{B}_{d,1}^{1-\theta} &\hookrightarrow \dot{B}_{r',1}^{2-\alpha} \quad \text{with} \quad r' = \frac{d}{2 - \alpha + \theta}, \end{aligned}$$

and eventually get

$$\left\| \frac{\|F(\cdot, h)\|_d}{|h|^{d+2-\alpha}} \right\|_1 \leq C \|\sigma\|_{\dot{B}_{d,1}^{1+\theta}} \|\nabla u\|_{\dot{B}_{d,1}^{1-\theta}}.$$

For the term B , we just have to use the fact that

$$B = \nabla u \cdot T\sigma \quad \text{with} \quad T\sigma(x) := \int_{\mathbb{R}^d} \frac{y}{|y|^{d+\alpha}} (\sigma(x+y) - \sigma(x)) \, dy.$$

The Fourier multiplier corresponding to T may be computed as follows:

$$\begin{aligned} \mathcal{F}\{T\sigma\}(\xi) &= \int_{\mathbb{R}^d} \frac{y}{|y|^{d+\alpha}} \widehat{\sigma}(\xi) \left(e^{i\langle y, \xi \rangle} - 1 \right) \, dy \\ &= \widehat{\sigma}(\xi) |\xi|^{\alpha-1} \underbrace{\int_{\mathbb{R}^d} \frac{z}{|z|^{d+\alpha}} \left(e^{i\langle z, \frac{\xi}{|\xi|} \rangle} - 1 \right) \, dz}_{=: R(\xi)}. \end{aligned}$$

The function R is smooth away of zero, constant on rays and bounded. Furthermore, that $d + \alpha > d + 1$ guarantees convergence at infinity, while the features of $\left(e^{i\langle z, \frac{\xi}{|\xi|} \rangle} - 1 \right)$ controls the convergence near $z = 0$, since $\alpha < 2$.

In order to show that the operator T is bounded from $\dot{B}_{d,1}^1$ to $\dot{B}_{d,1}^{2-\alpha}$, one may proceed as follows. Take some smooth function ψ compactly supported away from 0 and with value 1 in the neighborhood of $\text{supp } \varphi$ (the function used in the definition of dyadic blocks). Then we have

$$\mathcal{F}\{\dot{\Delta}_j T\sigma\}(\xi) = \varphi(2^{-j}\xi) |\xi|^{\alpha-1} R(\xi) \widehat{\sigma}(\xi) = (\psi(2^{-j}\xi) |\xi|^{\alpha-1} R(\xi)) \mathcal{F}\{\dot{\Delta}_j \sigma\}(\xi)$$

and by defining

$$g_j(x) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \psi(2^{-j}\xi) |\xi|^{\alpha-1} R(\xi) e^{i\langle x, \xi \rangle} d\xi$$

we obtain by Young's inequality for convolutions:

$$\|\dot{\Delta}_j T\sigma\|_d = \|g_j * \dot{\Delta}_j \sigma\|_d \leq \|g_j\|_1 \|\dot{\Delta}_j \sigma\|_d.$$

Since, by a change of variables, we have

$$g_j(x) = 2^{j(\alpha-1)} 2^{jd} \int_{\mathbb{R}^d} \psi(\eta) |\eta|^{\alpha-1} R(\eta) e^{i\langle 2^{-j}x, \eta \rangle} d\eta,$$

it is sufficient to show that the L^1 -norm of the function

$$g(x) = \int_{\mathbb{R}^d} \psi(\eta) |\eta|^{\alpha-1} R(\eta) e^{i\langle x, \eta \rangle} d\eta$$

is finite because $\|g_j(\cdot)\|_1 = 2^{j(\alpha-1)} \|2^{jd} g(2^j \cdot)\|_1 = \|g\|_1$. Using integration by parts we write

$$\begin{aligned} g(x) &= (1 + |x|^2)^{-d} \int_{\mathbb{R}^d} \psi(\eta) |\eta|^{\alpha-1} R(\eta) (\text{Id} - \Delta_\eta)^d \left(e^{i\langle x, \eta \rangle} \right) d\eta \\ &= (1 + |x|^2)^{-d} \int_{\mathbb{R}^d} (\text{Id} - \Delta_\eta)^d (\psi(\eta) |\eta|^{\alpha-1} R(\eta)) e^{i\langle x, \eta \rangle} d\eta \end{aligned}$$

from which it follows that g is in L^1 , since $|g(x)| \leq C(1 + |x|^2)^{-d}$. Hence

$$\|\dot{\Delta}_j T\sigma\|_d \leq C 2^{j(\alpha-1)} \|\dot{\Delta}_j \sigma\|_d \quad \text{for all } j \in \mathbb{Z}.$$

By the assumption that $\sigma \in \dot{B}_{d,1}^{1+\theta}$, this implies that $T\sigma \in \dot{B}_{d,1}^{2+\theta-\alpha}$. Finally, since the product maps $\dot{B}_{d,1}^{1-\theta} \times \dot{B}_{d,1}^{2+\theta-\alpha}$ to $\dot{B}_{d,1}^{2-\alpha}$ by (h) in Lemma 2.1 if $0 \leq \theta \leq \alpha - 1$, we get the desired estimate for B . \square

Step 2: Iterative scheme. Fix some nonnegative integer n_0 and define

$$u_0^n := \sum_{|j| \leq n+n_0} \dot{\Delta}_j u_0 \quad \text{and} \quad \sigma_0^n := \sum_{|j| \leq n+n_0} \dot{\Delta}_j \sigma_0.$$

It is clear that those two sequences belongs to the space W_d^∞ of smooth functions with derivatives of any order in L^d , and that

$$\begin{aligned} u_0^n &\rightarrow u_0 \quad \text{and} \quad \nabla u_0^n \rightarrow \nabla u_0 \quad \text{in } \dot{B}_{d,1}^{2-\alpha}, \\ \sigma_0^n &\rightarrow \sigma_0 \quad \text{and} \quad \nabla \sigma_0^n \rightarrow \nabla \sigma_0 \quad \text{in } \dot{B}_{d,1}^1. \end{aligned}$$

In what follows, we set²

$$(15) \quad \varepsilon := \sup_{n \in \mathbb{N}} \|u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} \quad \text{and} \quad \eta := \sup_{n \in \mathbb{N}} \|a_0^n\|_{\dot{B}_{d,1}^1}.$$

We then introduce the following iterative scheme: for $n = 0$, let

$$\sigma^0 \equiv \sigma_0^0, \quad u^0 \equiv 0,$$

while for all $n = 1, 2, \dots$, let u^n be the solution to the system

$$(16) \quad u_t^n + \mu(-\Delta)^{\alpha/2} u^n = F(u^{n-1}, \sigma^{n-1})$$

with the initial data $u^n(0) = u_0^n$ and F defined in (10). Finally, let σ^n be a solution to

$$(17) \quad \sigma_t^n + \text{div}(\sigma^n u^n) = -\text{div} u^n$$

with the initial data $\sigma^n(0) = \sigma_0^n$.

²By taking n_0 large enough, one may make ε and η as close as $\|u_0\|_{\dot{B}_{d,1}^{2-\alpha}}$ and $\|a_0\|_{\dot{B}_{d,1}^1}$ as we want.

Step 3: Existence of approximate solutions and estimates for critical regularity. Given that the data are in W_d^∞ , the existence of a sequence $(\sigma^n, u^n)_{n \in \mathbb{N}}$ of global approximate solutions in $\mathcal{C}^1(\mathbb{R}_+; W_d^\infty)$ follows from an easy induction argument, based on the two propositions below, that are proved in appendix.

Proposition 4.1. *Let $u : \mathbb{R}_+ \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ be a given time-dependent vector field with components in $\mathcal{C}(\mathbb{R}_+; W_d^\infty)$. Then the transport equation*

$$(18) \quad \sigma_t + \operatorname{div}(u\sigma) = f$$

with initial data σ_0 in W_d^∞ and source term f in $\mathcal{C}(\mathbb{R}_+; W_d^\infty)$ admits a unique solution σ in $\mathcal{C}^1(\mathbb{R}_+; W_d^\infty)$. Moreover, there exists a constant $C > 0$, such that for all $T \geq 0$,

$$\|\sigma\|_{L_T^\infty \dot{B}_{d,1}^1} \leq \|\sigma_0\|_{\dot{B}_{d,1}^1} + \|f\|_{L_T^1 \dot{B}_{d,1}^1} + C \int_0^T \|\nabla u(t)\|_{\dot{B}_{d,1}^1} \|\sigma(t)\|_{\dot{B}_{d,1}^1} dt.$$

Taking $\sigma = \sigma^n$, $u = u^n$ and $f = -\operatorname{div} u^n$, and using Lemma 2.1(e) and Gronwall lemma, we readily get:

Proposition 4.2. *For all $n = 1, 2, \dots$, equation (17) admits a unique global solution $\sigma^n \in \mathcal{C}^1(\mathbb{R}_+; W_d^\infty)$ and there exists a constant C_1 such that for all $T > 0$,*

$$\|\sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq e^{C_1 \|u^n\|_{L_T^1 \dot{B}_{d,1}^2}} \left(\|\sigma_0^n\|_{\dot{B}_{d,1}^1} + \|u^n\|_{L_T^1 \dot{B}_{d,1}^2} \right).$$

Secondly, we prove existence and present an estimate for u^n depending on u^{n-1} and σ^{n-1} . Here, as in the density case, we use a classical result, the proof of which may be found in the appendix.

Proposition 4.3. *Let $0 < T \leq \infty$, $1 \leq p \leq \infty$ and $s \in \mathbb{R}$. Assume that $u_0 \in \dot{B}_{p,1}^s$ and $f \in L_T^1 \dot{B}_{p,1}^s$. Then the Cauchy problem*

$$(19) \quad \begin{cases} u_t + \mu(-\Delta)^{\alpha/2} u = f(t, x), & (t, x) \in \mathbb{R}^+ \times \mathbb{R}^d \\ u(0, x) = u_0(x), & x \in \mathbb{R}^d \end{cases}$$

has a unique solution $u \in \mathcal{C}([0, T]; \dot{B}_{p,1}^s) \cap L_T^1 \dot{B}_{p,1}^{s+\alpha}$ and there exists $C > 0$ such that

$$\|u\|_{L_T^1 \dot{B}_{p,1}^{s+\alpha}} + \|u\|_{L_T^\infty \dot{B}_{p,1}^s} \leq C \left[\|u_0\|_{\dot{B}_{p,1}^s} + \|f\|_{L_T^1 \dot{B}_{p,1}^s} \right].$$

The above proposition enables us to get the following result for u^n .

Proposition 4.4. *For all $n = 1, 2, \dots$, given u^{n-1} and σ^{n-1} in $\mathcal{C}(\mathbb{R}_+; W_d^\infty)$, there exists a unique solution $u^n \in \mathcal{C}^1(\mathbb{R}_+; W_d^\infty)$ to (16) such that for all $T \geq 0$,*

$$(20) \quad \|u^n\|_{L_T^1 \dot{B}_{d,1}^2} + \|u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} \leq \|u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} + C_2 \int_0^T \|u^{n-1}\|_{\dot{B}_{d,1}^2} (\|\sigma^{n-1}\|_{\dot{B}_{d,1}^1} + \|u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}}) dt.$$

Proof. The proof is an application of Proposition 4.3 with $s = 2 - \alpha$, $p = d$, and

$$f = F(u^{n-1}, \sigma^{n-1}).$$

We estimate the norm $\|f\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}}$ dealing with each term separately. Bounding the first term follows directly from Lemma 3.1 and Hölder's inequality:

$$\|I_\alpha(u^{n-1}, \sigma^{n-1})\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} \leq C \int_0^T \|\nabla u^{n-1}\|_{\dot{B}_{d,1}^1} \|\sigma^{n-1}\|_{\dot{B}_{d,1}^1} dt.$$

Lemma 2.1 and Hölder's inequality allow us to estimate norms of the second and the third terms of f as follows:

$$\begin{aligned} \|\sigma^{n-1}(-\Delta)^{\alpha/2} u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \int_0^T \|\sigma^{n-1}\|_{\dot{B}_{d,1}^1} \|(-\Delta)^{\alpha/2} u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}} dt \\ &\leq C \int_0^T \|\sigma^{n-1}\|_{\dot{B}_{d,1}^1} \|u^{n-1}\|_{\dot{B}_{d,1}^2} dt \end{aligned}$$

and

$$\begin{aligned} \|(u^{n-1} \cdot \nabla)u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \int_0^T \|u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}} \|\nabla u^{n-1}\|_{\dot{B}_{d,1}^1} dt \\ &\leq C \int_0^T \|u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}} \|u^{n-1}\|_{\dot{B}_{d,1}^2} dt. \end{aligned}$$

Thus we have the inequality

$$\|f\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} \leq C \int_0^T \|u^{n-1}\|_{\dot{B}_{d,1}^2} (\|\sigma^{n-1}\|_{\dot{B}_{d,1}^1} + \|u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}}) dt,$$

from which we get the stated result. \square

It is now easy to check that if ε and η in (15) have been taken sufficiently small then we have for all $n \in \mathbb{N}$ and $T \geq 0$,

$$(21) \quad \|u^n\|_{L_T^1 B_{d,1}^2} + \|u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} \leq 2\varepsilon \quad \text{and} \quad \|\sigma^n\|_{L_T^\infty B_{d,1}^1} \leq 2\eta.$$

Indeed, the result is obviously true for $n = 0$, and if it is true for $n - 1$ then Inequality (20) implies that

$$\|u^n\|_{L_T^1 B_{d,1}^2} + \|u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} \leq \varepsilon + 4C_2\varepsilon(\varepsilon + \eta).$$

Hence (21) is fulfilled by u^n if ε and η are so small that

$$4C_2(\varepsilon + \eta) \leq 1.$$

Then, taking advantage of Proposition 4.2, we get

$$\|\sigma^n\|_{L_T^\infty B_{d,1}^1} \leq e^{2C_1\varepsilon}(\eta + 2C_1\varepsilon) \leq 2\eta$$

provided that in addition we have for instance

$$(22) \quad 2C_1\varepsilon \leq \log(3/2) \quad \text{and} \quad 6C_1\varepsilon \leq \eta.$$

Step 4: Higher-order estimates. In order to obtain higher-order estimates we simply differentiate equations (16) and (17) with respect to the space variable. Denoting by ∂_k the derivative with respect to the variable x_k , we get for $k = 1, \dots, d$,

$$(\partial_k \sigma^n)_t + \operatorname{div}(u^n \partial_k \sigma^n) = -\operatorname{div}(\partial_k u^n \sigma^n) - \operatorname{div} \partial_k u^n \quad \text{and}$$

$$(23) \quad (\partial_k u^n)_t + \mu(-\Delta)^{\alpha/2} \partial_k u^n = -\mu \partial_k \sigma^{n-1} (-\Delta)^{\alpha/2} u^{n-1} - \mu \sigma^{n-1} (-\Delta)^{\alpha/2} \partial_k u^{n-1} \\ + I_\alpha(\partial_k u^{n-1}, \sigma^{n-1}) + I_\alpha(u^{n-1}, \partial_k \sigma^{n-1}) - (\partial_k u^{n-1} \cdot \nabla) u^{n-1} - (u^{n-1} \cdot \nabla) \partial_k u^{n-1}.$$

Proposition 4.5. *Approximate solutions σ^n to (17) satisfy*

$$\|\nabla \sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq e^{C_3 \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^1}} \left[\|\nabla \sigma_0^n\|_{\dot{B}_{d,1}^1} + C_3 \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^2} (\|\sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} + 1) \right].$$

Proof. We apply Proposition 4.1 with $\sigma = \partial_k \sigma^n$, $u = u^n$ and $f = -\operatorname{div}(\partial_k u^n \sigma^n) - \operatorname{div} \partial_k u^n$. We need to estimate f . Clearly, we have

$$\|f\|_{L_T^1 \dot{B}_{d,1}^1} \leq \|\sigma^n \nabla \operatorname{div} u^n\|_{L_T^1 \dot{B}_{d,1}^1} + \|\nabla u^n \otimes \nabla \sigma^n\|_{L_T^1 \dot{B}_{d,1}^1} + \|\nabla \operatorname{div} u^n\|_{L_T^1 \dot{B}_{d,1}^1}$$

and with the use of Hölder's inequality and Lemma 2.1, we get

$$\|f\|_{L_T^1 \dot{B}_{d,1}^1} \leq C_3 \left(\|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^2} (\|\sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} + 1) + \int_0^T \|\nabla u^n\|_{\dot{B}_{d,1}^1} \|\nabla \sigma^n\|_{\dot{B}_{d,1}^1} dt \right).$$

By Proposition 4.1 and Gronwall lemma, this leads to the desired inequality. \square

Likewise, applying Proposition 4.3 to equation (23) provides us with higher-order bounds for u^n :

Proposition 4.6. *Approximate solutions u^n to (16) satisfy for all $T \geq 0$,*

$$\begin{aligned} \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha} \cap L_T^\infty \dot{B}_{d,1}^{2-\alpha}} &\leq C_4 \left[\|\nabla u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} + \|\nabla u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1} \right. \\ &\left. + \|u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\nabla \sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1} + \|\nabla u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} + \|u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\nabla u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} \right]. \end{aligned}$$

Proof. We now apply Proposition 4.3 to $\partial_k u$ in equation (23), with f being the right-hand side, $s = 2 - \alpha$ and $p = d$. Below, we bound the $L_T^1 \dot{B}_{d,1}^{2-\alpha}$ norm of each term of f separately, using repeatedly Lemmas 2.1 and 3.1 and Hölder's inequality:

$$\begin{aligned} \|\sigma^{n-1}(-\Delta)^{\alpha/2} \partial_k u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \int_0^T \|\sigma^{n-1}\|_{\dot{B}_{d,1}^1} \|(-\Delta)^{\alpha/2} \partial_k u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}} dt \\ &\leq C \int_0^T \|\sigma^{n-1}\|_{\dot{B}_{d,1}^1} \|\partial_k u\|_{\dot{B}_{d,1}^2} dt \\ &\leq C \|\partial_k u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}; \\ \|\partial_k \sigma^{n-1}(-\Delta)^{\alpha/2} u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \int_0^T \|\partial_k \sigma^{n-1}\|_{\dot{B}_{d,1}^1} \|(-\Delta)^{\alpha/2} u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}} dt \\ &\leq C \|u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\partial_k \sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}; \\ \|I_\alpha[\partial_k u^{n-1}, \sigma^{n-1}]\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \int_0^T \|\partial_k u^{n-1}\|_{\dot{B}_{d,1}^2} \|\sigma^{n-1}\|_{\dot{B}_{d,1}^1} dt \\ &\leq C \|\partial_k u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}; \\ \|I_\alpha[u^{n-1}, \partial_k \sigma^{n-1}]\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \int_0^T \|u^{n-1}\|_{\dot{B}_{d,1}^2} \|\partial_k \sigma^{n-1}\|_{\dot{B}_{d,1}^1} dt \\ &\leq C \|u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\partial_k \sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}; \\ \|u^{n-1} \cdot \partial_k \nabla u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \int_0^T \|u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}} \|\partial_k \nabla u^{n-1}\|_{\dot{B}_{d,1}^1} dt \\ &\leq C \|\partial_k u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}; \\ \|\partial_k u^{n-1} \cdot \nabla u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \int_0^T \|\partial_k u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}} \|\nabla u^{n-1}\|_{\dot{B}_{d,1}^1} dt \\ &\leq C \|u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\partial_k u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}. \end{aligned}$$

Putting together all these estimates and summing on $k = 1, \dots, d$ completes the proof. \square

Denote $S_0 := \sup_{n \in \mathbb{N}} \|\nabla \sigma_0^n\|_{\dot{B}_{d,1}^1}$ and $U'_0 := \sup_{n \in \mathbb{N}} \|\nabla u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}}$. From Proposition 4.5 and (21), we get for all $T \geq 0$, taking C_3 slightly larger if need be,

$$(24) \quad \|\nabla \sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq C_3 (S_0 + \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^2})$$

and, thanks to Proposition 4.6, keeping in mind (22),

$$(25) \quad \|\nabla u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha} \cap L_T^1 \dot{B}_{d,1}^2} \leq C_4 (U'_0 + \eta \|\nabla u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha} \cap L_T^1 \dot{B}_{d,1}^2} + \varepsilon \|\nabla \sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}).$$

Therefore, combining (24) and (25), we find that

$$\begin{aligned} \|\nabla u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha} \cap L_T^1 \dot{B}_{d,1}^2} &+ \frac{1}{2C_3} \|\nabla \sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq \frac{S_0}{2} + C_4 U'_0 \\ &+ \frac{1}{2} \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^2} + \eta C_4 \|\nabla u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha} \cap L_T^1 \dot{B}_{d,1}^2} + \varepsilon C_4 \|\nabla \sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}. \end{aligned}$$

Provided η and ε also fulfill

$$2\eta C_4 \leq 1/2 \quad \text{and} \quad 2\varepsilon C_3 C_4 \leq 1/2,$$

one can then get by induction the following uniform bound for all $T \geq 0$:

$$(26) \quad \|\nabla u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha} \cap L_T^1 \dot{B}_{d,1}^2} + \frac{1}{C_3} \|\nabla \sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq 2S_0 + 4C_4 U'_0.$$

Step 5: Convergence estimates. Previous steps established that the sequence of approximate solutions $(\sigma^n, u^n)_{n \in \mathbb{N}}$ exists globally and satisfies the uniform estimates (21) and (26). Proving the convergence of that sequence will stem from the following bounds for the differences between subsequent terms of the sequence.

Proposition 4.7. *Let $(\sigma^n, u^n)_{n \in \mathbb{N}}$ be a sequence of approximate solutions. Then for $\delta\sigma^n := \sigma^n - \sigma^{n-1}$ and $\delta u^n := u^n - u^{n-1}$, we have for all $n \geq 1$,*

$$\|\delta\sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq C_5 e^{C_5 \|u^n\|_{L_T^1 \dot{B}_{d,1}^2}} \left[\|\delta\sigma_0^n\|_{L_T^1 \dot{B}_{d,1}^1} + \|\delta u^n\|_{L_T^1 \dot{B}_{d,1}^2} \left(\|\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1} + 1 \right) + \|\nabla \sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1} \|\delta u^n\|_{L_T^1 \dot{B}_{d,1}^1} \right],$$

and for all $n \geq 2$,

$$\begin{aligned} \|\delta u^n\|_{L_T^1 \dot{B}_{d,1}^2} + \|\delta u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} &\leq C_6 \left[\|\delta u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} + \|\sigma^{n-2}\|_{L_T^\infty \dot{B}_{d,1}^1} \|\delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \right. \\ &\quad + \|\delta\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1} \|u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} + \|\delta\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1} \|u^{n-2}\|_{L_T^1 \dot{B}_{d,1}^2} \\ &\quad + \|\delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1} + \|u^{n-2}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} \|\delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \\ &\quad \left. + \|\delta u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} \|u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \right]. \end{aligned}$$

Proof. In order to prove the first item, we use the fact that

$$\delta\sigma_t^n + \operatorname{div}(u^n \delta\sigma^n) = -\operatorname{div}(\delta u^n \sigma^{n-1}) - \operatorname{div}(\delta u^n).$$

Then, applying Proposition 4.1 with

$$\sigma = \delta\sigma^n, \quad u = u^n \quad \text{and} \quad f = -\operatorname{div}(\delta u^n \sigma^{n-1}) - \operatorname{div}(\delta u^n),$$

and using the all too familiar argumentation based on Lemma 2.1, we get

$$\begin{aligned} \|f\|_{L_T^1 \dot{B}_{d,1}^1} &\leq C \left(\|\sigma^{n-1} \operatorname{div}(\delta u^n)\|_{L_T^1 \dot{B}_{d,1}^1} + \|\delta u^n \cdot \nabla \sigma^{n-1}\|_{L_T^1 \dot{B}_{d,1}^1} + \|\operatorname{div} \delta u^n\|_{L_T^1 \dot{B}_{d,1}^1} \right) \\ &\leq C \|\delta u^n\|_{L_T^1 \dot{B}_{d,1}^2} \left(\|\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1} + 1 \right) + C \|\delta u^n\|_{L_T^1 \dot{B}_{d,1}^2} \|\nabla \sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}, \end{aligned}$$

whence the desired inequality.

For proving the second item, we observe from (16) that

$$\begin{aligned} \partial_t \delta u^n + \mu(-\Delta)^{\alpha/2} \delta u^n &= -\sigma^{n-2}(-\Delta)^{\alpha/2} \delta u^{n-1} - \delta\sigma^{n-1}(-\Delta)^{\alpha/2} u^{n-1} \\ &\quad + I_\alpha(u^{n-2}, \delta\sigma^{n-1}) + I_\alpha(\delta u^{n-1}, \sigma^{n-1}) - (u^{n-2} \cdot \nabla) \delta u^{n-1} - (\delta u^{n-1} \cdot \nabla) u^{n-1}. \end{aligned}$$

Arguing as in the previous steps, we get:

$$\begin{aligned} \|\sigma^{n-2}(-\Delta)^{\alpha/2} \delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \|\delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\sigma^{n-2}\|_{L_T^\infty \dot{B}_{d,1}^1}; \\ \|\delta\sigma^{n-1}(-\Delta)^{\alpha/2} u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \|u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\delta\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}; \\ \|I_\alpha(u^{n-2}, \delta\sigma^{n-1})\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \|u^{n-2}\|_{L_T^1 \dot{B}_{d,1}^2} \|\delta\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}; \\ \|I_\alpha(\delta u^{n-1}, \sigma^{n-1})\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \|\delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}; \\ \|(u^{n-2} \cdot \nabla) \delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \|\delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \|u^{n-2}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}; \\ \|(\delta u^{n-1} \cdot \nabla) u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} &\leq C \|\delta u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} \|u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2}. \end{aligned}$$

Then, taking advantage of Proposition 4.3 completes the proof of the second item. \square

Step 6: The proof of existence. In order to show that the sequence $(\sigma^n, u^n)_{n \in \mathbb{N}}$ converges, we are going to establish that, for all $T > 0$, it is a Cauchy sequence in the space

$$\mathcal{C}([0, T]; \dot{B}_{d,1}^1) \times (\mathcal{C}([0, T]; \dot{B}_{d,1}^{2-\alpha}) \cap L_T^1(\dot{B}_{d,1}^2)).$$

That property will come up from Proposition 4.7 and Estimates (21)–(26) that entail for all $n \geq 1$, changing slightly C_5 and C_6 and denoting by C_0 some constant that may be computed from the right-hand side of (26),

$$(27) \quad \begin{aligned} \|\delta\sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} &\leq C_5 \|\delta\sigma_0^n\|_{\dot{B}_{d,1}^1} + C_5 \|\delta u^n\|_{L_T^1 \dot{B}_{d,1}^2} + C_0 \|\delta u^n\|_{L_T^1 \dot{B}_{d,1}^1}, \\ \|\delta u^n\|_{L_T^1 \dot{B}_{d,1}^2} + \|\delta u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} &\leq C_6 (\|\delta u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} \\ &\quad + \eta \|\delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} + \eta \|\delta u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} + \varepsilon \|\delta\sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1}). \end{aligned}$$

Hence plugging the first inequality (at rank $n - 1$) in the second one yields if $C_5 \varepsilon \leq \eta$,

$$\begin{aligned} \|\delta u^n\|_{L_T^1 \dot{B}_{d,1}^2} + \|\delta u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} &\leq C_6 \left(\|\delta u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} + C_5 \varepsilon \|\delta\sigma_0^n\|_{\dot{B}_{d,1}^1} \right. \\ &\quad \left. + 2\eta (\|\delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} + \|\delta u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}) + C_0 \varepsilon \|\delta u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^1} \right). \end{aligned}$$

Using interpolation, then Young inequality, we get that

$$\begin{aligned} C_0 \|\delta u^{n-1}\|_{\dot{B}_{d,1}^1} &\leq C_0 \|\delta u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}}^{\frac{1}{\alpha}} \|\delta u^{n-1}\|_{\dot{B}_{d,1}^2}^{\frac{\alpha-1}{\alpha}} \\ &\leq \left(\frac{\alpha-1}{\alpha} \right) \|\delta u^{n-1}\|_{\dot{B}_{d,1}^2} + \frac{C_0^\alpha}{\alpha} \|\delta u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}}. \end{aligned}$$

Therefore, denoting

$$\mathcal{U}_T^n := \|\delta u^n\|_{L_T^1 \dot{B}_{d,1}^2} + \|\delta u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}$$

and assuming (just for expository purpose) that $C_5 = C_6 = 1$, we end up with

$$\mathcal{U}_T^n \leq \|\delta u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} + \varepsilon \|\delta\sigma_0^n\|_{\dot{B}_{d,1}^1} + 2\eta \mathcal{U}_T^{n-1} + C_0^\alpha \varepsilon \int_0^T \mathcal{U}_t^{n-1} dt.$$

We sum over $n \geq 2$ and get

$$\sum_{n \geq 2} \mathcal{U}_T^n \leq \sum_{n \geq 2} (\|\delta u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} + \varepsilon \|\delta\sigma_0^n\|_{\dot{B}_{d,1}^1}) + \sum_{n \geq 1} \left(2\eta \mathcal{U}_T^n + C_0^\alpha \varepsilon \int_0^T \mathcal{U}_t^n dt \right).$$

For small enough η , bounding \mathcal{U}_T^1 by means of (21), this implies that

$$\sum_{n \geq 1} \mathcal{U}_T^n \leq 2 \left(\varepsilon + \sum_{n \geq 1} (\|\delta u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} + \varepsilon \|\delta\sigma_0^n\|_{\dot{B}_{d,1}^1}) + C_0^\alpha \varepsilon \int_0^T \sum_{n \geq 1} \mathcal{U}_t^n dt \right).$$

Then, using Gronwall lemma and, we get

$$\sum_{n \geq 1} \mathcal{U}_T^n \leq 2 \left(\varepsilon + \sum_{n \geq 1} (\|\delta u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} + \varepsilon \|\delta\sigma_0^n\|_{\dot{B}_{d,1}^1}) \right) \exp(2C_0^\alpha \varepsilon T).$$

The right-hand side being finite for all $T \geq 0$, one may conclude that $(u^n)_{n \in \mathbb{N}}$ is a Cauchy sequence in the Banach³ space $\mathcal{C}([0, T]; \dot{B}_{d,1}^{2-\alpha}) \cap L_T^1 \dot{B}_{d,1}^2$ for all $T \geq 0$. Then reverting to (27) and using a similar argument, we discover that $(\sigma^n)_{n \in \mathbb{N}}$ is a Cauchy sequence in the space $\mathcal{C}([0, T]; \dot{B}_{d,1}^1)$. So finally, there exists a pair (σ, u) such that for all $T \geq 0$, we have

$$(28) \quad (\sigma^n, u^n) \rightarrow (\sigma, u) \text{ in } \mathcal{C}([0, T]; \dot{B}_{d,1}^1) \times (\mathcal{C}([0, T]; \dot{B}_{d,1}^{2-\alpha}) \cap L_T^1 \dot{B}_{d,1}^2).$$

³See Lemma 2.1.

The uniform estimates of the previous step and the properties of the Besov spaces for the weak convergence guarantee that we also have $(\nabla\sigma, \nabla u)$ in $L_T^\infty \dot{B}_{d,1}^1 \times L_T^\infty \dot{B}_{d,1}^{2-\alpha}$ with the same bounds.

Let us now check that (σ, u) indeed fulfills (9) in the sense of distributions. Regarding the continuity equation, we find that

$$\sigma_t + \operatorname{div}(\sigma u) + \operatorname{div} u = (\sigma - \sigma^n)_t + \operatorname{div}(\sigma u - \sigma^n u^n) + \operatorname{div}(u - u^n).$$

We have just proved that $\sigma_n \rightarrow \sigma$ in $\mathcal{C}([0, T]; \dot{B}_{d,1}^1)$, hence uniformly on $[0, T] \times \mathbb{R}^d$. Therefore, $(\sigma - \sigma^n)_t \rightarrow 0$ in the sense of distributions. To prove the convergence of the last two terms, we note that the convergence property of (28) for u^n , the uniform estimates of the previous step and interpolation ensure that

$$u^n \rightarrow u \text{ in } \mathcal{C}([0, T]; \dot{B}_{d,1}^1).$$

Hence, using once more the embedding of $\dot{B}_{d,1}^1$ in the set of continuous bounded functions, we see that $\sigma^n u^n$ converges uniformly to σu on $[0, T] \times \mathbb{R}^d$. Therefore, we eventually have

$$(\sigma - \sigma^n)_t + \operatorname{div}(\sigma u - \sigma^n u^n) + \operatorname{div}(u - u^n) \rightarrow 0 \text{ in } \mathcal{D}'(\mathbb{R}_+ \times \mathbb{R}^d).$$

One can argue similarly for the momentum equation, writing that

$$\begin{aligned} u_t + u \cdot \nabla u + \mu(1 + \sigma)(-\Delta)^{\alpha/2} u - I_\alpha(u, \sigma) &= (u - u^n)_t + (u \cdot \nabla u - u^n \cdot \nabla u^n) \\ &+ \mu((1 + \sigma)(-\Delta)^{\alpha/2} u - (1 + \sigma^n)(-\Delta)^{\alpha/2} u^n) - (I_\alpha(u, \sigma) - I_\alpha(u^n, \sigma^n)). \end{aligned}$$

Making an extensive use of product estimates in Besov spaces, embedding and Lemma 3.1, one may conclude that the right-hand side is going to zero in the distributional sense. Hence (σ, u) is a solution to System (9).

We still have to establish that $(\nabla\sigma, \nabla u)$ is in $\mathcal{C}(\mathbb{R}_+; \dot{B}_{d,1}^1 \times \dot{B}_{d,1}^{2-\alpha})$ and that ∇u is in $L^1 \dot{B}_{d,1}^2$. The first property follows from the second one and classical properties for the transport equation and parabolic equations with fractional Laplacian.

As regards the proof of $\nabla u \in L^1 \dot{B}_{d,1}^2$, the difficulty is that having $(\nabla u^n)_{n \in \mathbb{N}}$ bounded in $L^1 \dot{B}_{d,1}^2$ just ensures that the weak limit ∇u is a measure on \mathbb{R}_+ with values on $\dot{B}_{d,1}^2$. We follow ideas stated in [12]. In order to show that, indeed, $\nabla u \in L^1 \dot{B}_{d,1}^2$, one may use the fact that, owing to $\nabla u \in L^1 \dot{B}_{d,1}^1$ and Bernstein inequality, one may write for all $J \in \mathbb{N}$ and all $n \in \mathbb{N}$,

$$\begin{aligned} \sum_{j=-\infty}^J 2^{2j} \int_{\mathbb{R}_+} \|\dot{\Delta}_j \nabla u\|_d dt &\leq \sum_{j=-\infty}^J 2^{2j} \int_{\mathbb{R}_+} \|\dot{\Delta}_j \nabla u^n\|_d dt + \sum_{j=-\infty}^J 2^{2j} \int_{\mathbb{R}_+} \|\dot{\Delta}_j \nabla(u^n - u)\|_d dt \\ &\leq \|\nabla u^n\|_{L^1 \dot{B}_{d,1}^2} + C2^J \sum_{j=-\infty}^J 2^{2j} \int_{\mathbb{R}_+} \|\dot{\Delta}_j(u^n - u)\|_d dt. \end{aligned}$$

The first term in the right-hand side is uniformly bounded (see (26)) while the last one tends to 0 for n going to ∞ . This completes the proof of the fact that ∇u belongs to $L^1 \dot{B}_{d,1}^2$ and is bounded by the right-hand side of (26).

Step 7: The case of a large initial velocity. We here explain how the above arguments have to be adapted to handle large initial velocity, assuming only that for some small enough (absolute) $\eta > 0$,

$$\|\sigma_0\|_{\dot{B}_{d,1}^1} \leq \eta.$$

We keep the iterative scheme of Step 2 to define a sequence $(\sigma^n, u^n)_{n \in \mathbb{N}}$ of approximate solutions (note that, there, no smallness is required whatsoever). Then we denote

$$U_0 := \sup_{n \in \mathbb{N}} \|u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}}, \quad U'_0 := \sup_{n \in \mathbb{N}} \|\nabla u_0^n\|_{\dot{B}_{d,1}^{2-\alpha}} \quad \text{and} \quad S_0 := \sup_{n \in \mathbb{N}} \|\nabla \sigma_0^n\|_{\dot{B}_{d,1}^1}.$$

We also introduce the notation

$$U_T^n := \|u^n\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}}.$$

We claim that there exists a time $T > 0$ (that will be bounded by below in terms of U_0 and U'_0 , see below) so that for all $n \in \mathbb{N}$, we have

$$(29) \quad \begin{aligned} & \|\sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq 2\eta, \quad \|u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} + \|u^n\|_{L_T^1 \dot{B}_{d,1}^2} \leq 2U_0 \\ & \text{and } \|\nabla u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} + \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^2} + \|\nabla \sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq M(S_0 + U'_0). \end{aligned}$$

We shall argue by induction. The case $n = 0$ being obvious, let us assume that (29) is true for $n - 1$ and suppose that, for a small enough $c > 0$,

$$(30) \quad U_T^{n-1} \leq c.$$

Then Inequality (20) tells us that

$$\|u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}} + \|u^n\|_{L_T^1 \dot{B}_{d,1}^2} \leq U_0 + 2C_2 U_T^{n-1} (\eta + U_0).$$

Hence (29) is fulfilled by u^n if

$$(31) \quad 2cC_2(\eta + U_0) \leq U_0.$$

In order to bound the high norm of u^n , we shall slightly modify Proposition 4.6, estimating the term with $u^{n-1} \cdot \partial_k \nabla u^{n-1}$ as follows:

$$\begin{aligned} \|u^{n-1} \cdot \partial_k \nabla u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha}} & \leq C \int_0^T \|u^{n-1}\|_{\dot{B}_{d,1}^1} \|\partial_k \nabla u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}} dt \\ & \leq C \int_0^T \|u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}}^{\frac{1}{\alpha}} \|u^{n-1}\|_{\dot{B}_{d,1}^2}^{1-\frac{1}{\alpha}} \|\nabla u^{n-1}\|_{\dot{B}_{d,1}^2}^{\frac{1}{\alpha}} \|\nabla u^{n-1}\|_{\dot{B}_{d,1}^{2-\alpha}}^{1-\frac{1}{\alpha}} dt \\ & \leq C(U_T^{n-1})^{1-\frac{1}{\alpha}} \|u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}^{\frac{1}{\alpha}} \|\nabla u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2}^{\frac{1}{\alpha}} \|\nabla u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}^{1-\frac{1}{\alpha}}. \end{aligned}$$

Bounding the other terms as in the proof of Proposition 4.6 and using the first line of (29) at rank $n - 1$ and (30), we end up with

$$(32) \quad \begin{aligned} & \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^2 \cap L_T^\infty \dot{B}_{d,1}^{2-\alpha}} \leq C_4 \left[U'_0 + \eta \|\nabla u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2} \right. \\ & \left. + c(\|\nabla \sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1} + \|\nabla u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}) + (U_T^{n-1})^{1-\frac{1}{\alpha}} U_0^{\frac{1}{\alpha}} \|\nabla u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2}^{\frac{1}{\alpha}} \|\nabla u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}^{1-\frac{1}{\alpha}} \right]. \end{aligned}$$

Let us assume for a while that

$$(33) \quad U_T^n \leq c.$$

Then Proposition 4.2 tells us that the first inequality of (29) is fulfilled at rank n if c has been chosen so that

$$(34) \quad C_1 c \leq \log(3/2) \quad \text{and} \quad 3C_1 c \leq \eta.$$

Then, assuming also that $C_3 c \leq \log 2$, Proposition 4.5 guarantees (increasing slightly C_3 if need be) that

$$\|\nabla \sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq 2S_0 + C_3 \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^2}.$$

At this stage, combining with (32) and assuming also that $c \leq \eta$, we discover that

$$\begin{aligned} & \frac{1}{2} \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^2 \cap L_T^\infty \dot{B}_{d,1}^{2-\alpha}} + \frac{1}{2C_3} \|\nabla \sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq 2S_0 + C_4 \left[U'_0 \right. \\ & \left. + \eta(\|\nabla \sigma^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^1} + \|\nabla u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2 \cap L_T^\infty \dot{B}_{d,1}^{2-\alpha}}) + c^{1-\frac{1}{\alpha}} U_0^{\frac{1}{\alpha}} \|\nabla u^{n-1}\|_{L_T^1 \dot{B}_{d,1}^2}^{\frac{1}{\alpha}} \|\nabla u^{n-1}\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}^{1-\frac{1}{\alpha}} \right]. \end{aligned}$$

Since we assumed that (29) is fulfilled at rank $n - 1$, we conclude that

$$\frac{1}{2} \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^2 \cap L_T^\infty \dot{B}_{d,1}^{2-\alpha}} + \frac{1}{2C_3} \|\nabla \sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq 2S_0 + C_4 \left[U'_0 + (\eta M + c^{1-\frac{1}{\alpha}} U_0^{\frac{1}{\alpha}})(S_0 + U'_0) \right].$$

Therefore, assuming with no loss of generality that $C_3 \geq 1$ and $C_4 \geq 2$,

$$\|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^{2-\alpha} \cap L_T^\infty \dot{B}_{d,1}^{2-\alpha}} + \|\nabla \sigma^n\|_{L_T^\infty \dot{B}_{d,1}^1} \leq 2C_3 C_4 \left[S_0 + U'_0 + (\eta M + c^{1-\frac{1}{\alpha}} U_0^{\frac{1}{\alpha}})(S_0 + U'_0) \right].$$

Let us take $M := 4C_3 C_4$. Then the second line of (29) is fulfilled provided

$$\eta M + c^{1-\frac{1}{\alpha}} U_0^{\frac{1}{\alpha}} \leq 1.$$

One can thus take $\eta \leq 1/(2M)$ (a constraint that does not depend on the size of u_0) and c fulfilling (31), (34) and $c^{1-\frac{1}{\alpha}} U_0^{\frac{1}{\alpha}} \leq 1/2$. In order to complete the proof of uniform estimates, we still have to justify (33). Again, this stems from interpolation, as

$$\begin{aligned} U^n(T) &\leq C \int_0^T \|\nabla u^n\|_{\dot{B}_{d,1}^{2-\alpha}}^{\frac{1}{\alpha}} \|\nabla u^n\|_{\dot{B}_{d,1}^2}^{1-\frac{1}{\alpha}} dt \\ &\leq C T^{\frac{1}{\alpha}} \|\nabla u^n\|_{L_T^\infty \dot{B}_{d,1}^{2-\alpha}}^{\frac{1}{\alpha}} \|\nabla u^n\|_{L_T^1 \dot{B}_{d,1}^2}^{1-\frac{1}{\alpha}} dt \leq C M T^{\frac{1}{\alpha}} (S_0 + U'_0). \end{aligned}$$

Therefore, one can conclude to (29) provided T fulfills

$$\max\left(U_0^{\frac{1}{\alpha}} (T^{\frac{1}{\alpha}} (S_0 + U'_0))^{1-\frac{1}{\alpha}}, T^{\frac{1}{\alpha}} (S_0 + U'_0)\right) \leq \varepsilon$$

for a small enough absolute $\varepsilon > 0$.

At this stage, one can easily repeat Step 6 so as to prove the convergence of the sequence $(\sigma^n, u^n)_{n \in \mathbb{N}}$ to some solution of (9) fulfilling (12). The details are left to the reader.

Step 8: Uniqueness. In this step, we assume that we are given two solutions (σ, u) and $(\bar{\sigma}, \bar{u})$ of (9) on $[0, T]$ satisfying (12). One can assume that (σ, u) is the one that has been constructed before, and thus, passing to the limit in (29),

$$(35) \quad \|\sigma\|_{L_T^\infty \dot{B}_{d,1}^1} \leq 2\eta.$$

Proving uniqueness is essentially the same as proving convergence, except that we now consider the difference $(\delta\sigma, \delta u) := (\bar{\sigma} - \sigma, u - \bar{u})$ between the two solutions. Since we have

$$\begin{cases} \partial_t \delta\sigma + \operatorname{div}(\bar{u} \delta\sigma) = -\operatorname{div} \delta u - \operatorname{div}(\sigma \delta u), \\ \partial_t \delta u + \mu(-\Delta)^{\alpha/2} \delta u = I_\alpha(\delta u, \sigma) + I_\alpha(\bar{u}, \delta\sigma) \\ \quad - \mu\sigma(-\Delta)^{\alpha/2} \delta u - \mu\delta\sigma(-\Delta)^{\alpha/2} \bar{u} - \bar{u} \cdot \nabla \delta u - \delta u \cdot \nabla \bar{u}, \end{cases}$$

applying Propositions 4.1 and 4.3 and the usual product laws in Besov spaces yields for all $t \in [0, T]$,

$$\begin{aligned} \|\delta\sigma(t)\|_{\dot{B}_{d,1}^1} &\leq C \int_0^t \left(\|\nabla \bar{u}\|_{\dot{B}_{d,1}^1} \|\delta\sigma\|_{\dot{B}_{d,1}^1} + \|\operatorname{div} \delta u\|_{\dot{B}_{d,1}^1} (1 + \|\sigma\|_{\dot{B}_{d,1}^1}) + \|\nabla \sigma\|_{\dot{B}_{d,1}^1} \|\delta u\|_{\dot{B}_{d,1}^1} \right) d\tau, \\ \|\delta u(t)\|_{\dot{B}_{d,1}^{2-\alpha}} + \|\delta u\|_{L_t^1 \dot{B}_{d,1}^2} &\leq C \int_0^t \left(\|\sigma\|_{\dot{B}_{d,1}^1} \|\delta u\|_{\dot{B}_{d,1}^2} + \|\delta\sigma\|_{\dot{B}_{d,1}^1} \|\bar{u}\|_{\dot{B}_{d,1}^2} \right. \\ &\quad \left. + \|\bar{u}\|_{\dot{B}_{d,1}^1} \|\nabla \delta u\|_{\dot{B}_{d,1}^{2-\alpha}} + \|\nabla \bar{u}\|_{\dot{B}_{d,1}^1} \|\delta u\|_{\dot{B}_{d,1}^{2-\alpha}} \right) d\tau. \end{aligned}$$

Then, taking advantage of (35), we get for any small enough $c > 0$ and $t \in [0, T]$,

$$(36) \quad \begin{aligned} &\|\delta u(t)\|_{\dot{B}_{d,1}^{2-\alpha}} + \|\delta u\|_{L_t^1 \dot{B}_{d,1}^2} + c \|\delta\sigma(t)\|_{\dot{B}_{d,1}^1} \\ &\leq C \int_0^t \left(\|\delta\sigma\|_{\dot{B}_{d,1}^1} \|\bar{u}\|_{\dot{B}_{d,1}^2} + c \|\delta u\|_{\dot{B}_{d,1}^1} \|\nabla \sigma\|_{\dot{B}_{d,1}^1} + \|\bar{u}\|_{\dot{B}_{d,1}^1} \|\delta u\|_{\dot{B}_{d,1}^{3-\alpha}} + \|\nabla \bar{u}\|_{\dot{B}_{d,1}^1} \|\delta u\|_{\dot{B}_{d,1}^{2-\alpha}} \right) d\tau. \end{aligned}$$

By interpolation and Young inequality, one may write

$$\begin{aligned} cC\|\delta u\|_{\dot{B}_{d,1}^1}\|\nabla\sigma\|_{\dot{B}_{d,1}^1} &\leq cC\|\nabla\sigma\|_{\dot{B}_{d,1}^1}\|\delta u\|_{\dot{B}_{d,1}^{2-\alpha}}^{\frac{1}{\alpha}}\|\delta u\|_{\dot{B}_{d,1}^2}^{1-\frac{1}{\alpha}} \\ &\leq \frac{\alpha-1}{\alpha}c^{\frac{\alpha}{\alpha-1}}\|\delta u\|_{\dot{B}_{d,1}^2} + \frac{C^\alpha}{\alpha}\|\nabla\sigma\|_{\dot{B}_{d,1}^1}^\alpha\|\delta u\|_{\dot{B}_{d,1}^{2-\alpha}}, \end{aligned}$$

and, similarly,

$$\begin{aligned} C\|\bar{u}\|_{\dot{B}_{d,1}^1}\|\delta u\|_{\dot{B}_{d,1}^{3-\alpha}} &\leq C\|\bar{u}\|_{\dot{B}_{d,1}^1}\|\delta u\|_{\dot{B}_{d,1}^2}^{\frac{1}{\alpha}}\|\delta u\|_{\dot{B}_{d,1}^{2-\alpha}}^{1-\frac{1}{\alpha}} \\ &\leq \frac{1}{\alpha}\|\delta u\|_{\dot{B}_{d,1}^2} + \frac{\alpha-1}{\alpha}(C\|\bar{u}\|_{\dot{B}_{d,1}^1})^{\frac{\alpha}{\alpha-1}}\|\delta u\|_{\dot{B}_{d,1}^{2-\alpha}}. \end{aligned}$$

Hence taking c small enough and plugging those two inequalities in (36), we get

$$\begin{aligned} \|\delta u(t)\|_{\dot{B}_{d,1}^{2-\alpha}} + \|\delta u\|_{L_t^1\dot{B}_{d,1}^2} + c\|\delta\sigma(t)\|_{\dot{B}_{d,1}^1} \\ \leq C\int_0^t\left(\|\delta\sigma\|_{\dot{B}_{d,1}^1}\|\bar{u}\|_{\dot{B}_{d,1}^2} + (\|\nabla\sigma\|_{\dot{B}_{d,1}^1}^\alpha + \|\bar{u}\|_{\dot{B}_{d,1}^1}^{\frac{\alpha}{\alpha-1}} + \|\nabla u\|_{\dot{B}_{d,1}^1})\|\delta u\|_{\dot{B}_{d,1}^{2-\alpha}}\right)d\tau. \end{aligned}$$

As having (12) implies that

$$\bar{u} \in L_T^\infty\dot{B}_{d,1}^1, \quad u, \bar{u} \in L_T^1\dot{B}_{d,1}^2 \quad \text{and} \quad \nabla\sigma \in L_T^\infty\dot{B}_{d,1}^1,$$

applying Gronwall lemma ensures that $(\delta\sigma, \delta u) \equiv 0$ on $[0, T]$. This implies uniqueness on the whole interval $[0, T]$.

APPENDIX A. PROOFS OF COROLLARY 1.1, PROPOSITIONS 4.1 AND 4.3

Proof of Corollary 1.1. On the one hand, the fact that $u \in L^\infty(\mathbb{R}_+; \dot{B}_{d,1}^{2-\alpha}) \cap L^1(\mathbb{R}_+; \dot{B}_{d,1}^2)$ implies that we have

$$(37) \quad u \in L^m(\mathbb{R}_+; \dot{B}_{d,1}^1) \quad \text{with} \quad m = \frac{\alpha}{\alpha-1} < \infty.$$

On the other hand, one can prove from the equation and the regularity of the solution given by Theorem 1.1 that

$$(38) \quad u_t \in L^1(\mathbb{R}_+; \dot{B}_{d,1}^{2-\alpha} \cap \dot{B}_{d,1}^{3-\alpha}) \subset L^1(\mathbb{R}_+; \dot{B}_{d,1}^1).$$

Therefore, since $\dot{B}_{d,1}^1$ is embedded continuously in L^∞ , we discover that for all $k \in \mathbb{N}$,

$$\|u\|_{L^1(k, k+1; L^\infty)} + \|u_t\|_{L^1(k, k+1; L^\infty)} \rightarrow 0 \quad \text{as} \quad k \rightarrow \infty,$$

which readily gives the assertion of the corollary. \square

Proof of Proposition 4.1. The proof of existence begin standard, we focus on the estimates. Applying $\dot{\Delta}_j$ to (18) yields

$$\partial_t \dot{\Delta}_j \sigma + \dot{\Delta}_j [\sigma \operatorname{div} u] + u \cdot \nabla \dot{\Delta}_j \sigma = \dot{\Delta}_j f - R_j,$$

where

$$R_j := u \cdot \nabla \dot{\Delta}_j \sigma - \dot{\Delta}_j (u \cdot \nabla \sigma).$$

Multiplying (18) by $|\Delta_j \sigma|^{d-2} \Delta_j \sigma$ and integrating with respect to x , we obtain

$$\begin{aligned} (39) \quad \frac{1}{d} \frac{d}{dt} \|\dot{\Delta}_j \sigma\|_d^d + \underbrace{\int_{\mathbb{R}^d} \dot{\Delta}_j [\sigma \operatorname{div} u] |\dot{\Delta}_j \sigma|^{d-2} \dot{\Delta}_j \sigma \, dx}_{I_1} + \underbrace{\int_{\mathbb{R}^d} u \cdot \nabla \dot{\Delta}_j \sigma |\dot{\Delta}_j \sigma|^{d-2} \dot{\Delta}_j \sigma \, dx}_{I_2} \\ = \int_{\mathbb{R}^d} \dot{\Delta}_j f |\dot{\Delta}_j \sigma|^{d-2} \dot{\Delta}_j \sigma \, dx - \underbrace{\int_{\mathbb{R}^d} R_j |\dot{\Delta}_j \sigma|^{d-2} \dot{\Delta}_j \sigma \, dx}_{I_3}. \end{aligned}$$

By Hölder's inequality, we have

$$|I_1| \leq \|\dot{\Delta}_j[\sigma \operatorname{div}]u\|_d \|\dot{\Delta}_j\sigma\|_d^{d-1}.$$

By integration by parts (note that $\nabla\sigma$ is a Schwartz function)

$$I_2 = \frac{1}{d} \int_{\mathbb{R}^d} u \cdot \nabla |\dot{\Delta}_j\sigma|^d dx = -\frac{1}{d} \int_{\mathbb{R}^d} \operatorname{div}u |\dot{\Delta}_j\sigma|^d dx,$$

which, since $\dot{B}_{d,1}^1 \hookrightarrow L^\infty$ by Lemma 2.1, implies that

$$|I_2| \leq C \|\operatorname{div}u\|_{\dot{B}_{d,1}^1} \|\dot{\Delta}_j\sigma\|_d^d.$$

Regarding the commutator term R_j in I_3 , we have by Hölder's inequality

$$|I_3| \leq \|R_j\|_d \|\dot{\Delta}_j\sigma\|_d^{d-1}.$$

Combining the above estimates of I_1, I_2 and I_3 with (39), we end up with

$$\frac{1}{d} \frac{d}{dt} \|\dot{\Delta}_j\sigma\|_d^d \leq C \|\nabla u\|_{\dot{B}_{d,1}^1} \|\dot{\Delta}_j\sigma\|_d^d + \left(\|\dot{\Delta}_j[\sigma \operatorname{div}]u\|_d + \|R_j\|_d + \|\dot{\Delta}_j f\|_d \right) \|\dot{\Delta}_j\sigma\|_d^{d-1}$$

which, after time integration, leads to

$$\|\dot{\Delta}_j\sigma(t)\|_d \leq \|\dot{\Delta}_j\sigma_0\|_d + \int_0^t \|\dot{\Delta}_j f\|_d d\tau + \int_0^t \left(C \|\nabla u\|_{\dot{B}_{d,1}^1} \|\dot{\Delta}_j\sigma\|_d + \|\dot{\Delta}_j[\sigma \operatorname{div}]u\|_d + \|R_j\|_d \right) d\tau.$$

Then, multiplying by 2^j and summing over $j \in \mathbb{Z}$, we obtain for all $t \geq 0$,

$$\|\sigma(t)\|_{\dot{B}_{d,1}^1} \leq \|\sigma_0\|_{\dot{B}_{d,1}^1} + \int_0^t \left(\|f\|_{\dot{B}_{d,1}^1} + \|\sigma \operatorname{div}u\|_{\dot{B}_{d,1}^1} + C \|\nabla u\|_{\dot{B}_{d,1}^1} \|\sigma\|_{\dot{B}_{d,1}^1} + \sum_{j \in \mathbb{Z}} 2^j \|R_j\|_d d\tau \right).$$

By Lemma 2.1(g), we have

$$\|\sigma \operatorname{div}u\|_{\dot{B}_{d,1}^1} \leq \|\sigma\|_{\dot{B}_{d,1}^1} \|\operatorname{div}u\|_{\dot{B}_{d,1}^1},$$

and by Lemma 2.1(i) we know that

$$\sum_{j \in \mathbb{Z}} 2^j \|R_j\|_d = \|R_j\|_{\dot{B}_{d,1}^1} \leq C \|\nabla u\|_{\dot{B}_{d,1}^1} \|\sigma\|_{\dot{B}_{d,1}^1}.$$

Hence, altogether, we get the desired inequality. \square

Proposition 4.3 relies on the following Bernstein-type lemma for the fractional Laplacian semigroup.

Lemma A.1. *Let \mathcal{C} be an annulus centered at 0, and $\alpha > 0$. There exist $C, c > 0$ such that for any $1 \leq p \leq \infty$ and $\lambda > 0$, if $\operatorname{supp} \mathcal{F}u \subset \lambda\mathcal{C}$ then*

$$(40) \quad \left\| e^{-t((-\Delta)^{\alpha/2})} u \right\|_p \leq C e^{-c\lambda^\alpha t} \|u\|_p \quad \text{for all } t \geq 0.$$

Proof. The proof can be found in e.g. [22, Proposition 2.2] or [42, Lemma 3.1]. \square

Proof of Proposition 4.3. Arguing by density, it suffices to consider the case where u_0 and f are in \mathcal{S}_0 and $\mathcal{C}(\mathbb{R}_+; \mathcal{S}_0)$, respectively. Then the Cauchy problem (19) has a unique solution u in $\mathcal{C}^1(\mathbb{R}_+; \mathcal{S}_0)$ that satisfies

$$\widehat{u}(t, \xi) = e^{-t\mu|\xi|^\alpha} \widehat{u}_0(\xi) + \int_0^t e^{-\mu|\xi|^\alpha(t-\tau)} \widehat{f}(\tau, \xi) d\tau.$$

We take the Fourier transform of (19) with respect to the space variable, and multiply it by the function $\varphi(2^{-k} \cdot)$ from the Littlewood-Paley decomposition, obtaining

$$\varphi(2^{-k} \cdot) \widehat{u}_t + \mu|\xi|^\alpha \varphi(2^{-k} \cdot) \widehat{u} = \varphi(2^{-k} \cdot) \widehat{f}.$$

Using estimate (40) and Minkowski inequality, we obtain the following time-pointwise estimate:

$$\|\dot{\Delta}_k u(t)\|_{L^p} \leq C e^{-c\mu t 2^{\alpha k}} \|\dot{\Delta}_k u_0\|_p + C \int_0^t e^{-c\mu 2^{k\alpha}(t-\tau)} \|\dot{\Delta}_k f(\tau)\|_p d\tau.$$

Hence

$$\|u\|_{L_T^\infty \dot{B}_{p,1}^s} = \sup_{t \in (0,T)} \left\{ \sum_{k \in \mathbb{Z}} 2^{sk} \|\dot{\Delta}_k u\|_p \right\} \leq C \|u_0\|_{\dot{B}_{p,1}^s} + C \int_0^T \|f(t)\|_{\dot{B}_{p,1}^s} dt$$

and

$$\begin{aligned} \|u\|_{L_T^1 \dot{B}_{p,1}^{s+\alpha}} &= \int_0^T \sum_{k \in \mathbb{Z}} 2^{k(\alpha+s)} \|\Delta_k u(t)\|_p dt \\ &\leq C \int_0^T \sum_{k \in \mathbb{Z}} 2^{k(\alpha+s)} \left\{ e^{-ct\mu 2^{\alpha k}} \|\Delta_k u_0\|_p + \int_0^t e^{-c\mu 2^{\alpha k}(t-\tau)} \|\Delta_k f(\tau)\|_p d\tau \right\} dt \\ &\leq C \sum_{k \in \mathbb{Z}} \left(2^{k(\alpha+s)} 2^{-\alpha k} \|\Delta_k u_0\|_p + 2^{k(\alpha+s)} \|e^{-c\mu 2^{\alpha k} t}\|_{L^1(0,T)} \int_0^T \|\Delta_k f(t)\|_p dt \right) \\ &\leq C \|u_0\|_{\dot{B}_{p,1}^s} + C \sum_{k \in \mathbb{Z}} 2^{k(\alpha+s)} 2^{-\alpha k} \int_0^T \|\Delta_k f(t)\|_p dt \\ &\leq C \left(\|u_0\|_{\dot{B}_{p,1}^s} + \|f\|_{L_T^1 \dot{B}_{p,1}^s} \right). \end{aligned}$$

□

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