

Piecewise linear sheaves

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Abstract

On a finite-dimensional real vector space, we give a microlocal characterization of (derived) piecewise linear sheaves (PL sheaves) and prove that the triangulated category of such sheaves is generated by sheaves associated with convex polyhedra. We then give a similar theorem for PL γ -sheaves, that is, PL sheaves associated with the γ -topology, for a closed convex polyhedral proper cone γ . Our motivation is that convex polyhedra may be considered as building blocks for higher dimensional barcodes.

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Introduction

Persistent homology is an essential tool of Topological Data Analysis appearing in numerous papers. To our opinion it may be interpreted as follows (see [KS18]). One has some data on a manifold X which define a constructible sheaf F on X , one has a function $f: X \rightarrow \mathbb{R}$ (playing the role of a Morse function) and one can calculate the direct image by f of the data, that is, the derived direct image Rf_*F . Assuming that f is proper on the support of F , one gets a constructible (derived) sheaf on \mathbb{R} and a variant of a theorem of Crawley-Boevey [CB14] (see also [Gui16] and, for the non compact case, [KS18, Th. 2.17]) asserts that such an object is nothing but a graded barcode. Moreover, in practice, the data on X are associated with an order and it follows that the barcodes are half-closed intervals (e.g., closed on the left and open on the right). In the language of sheaves, this means that one gets a γ -sheaf represented by a γ -barcode, where γ is the cone $\{t \in \mathbb{R}; t \leq 0\}$.

However it is natural in many problems to replace the ordered set (\mathbb{R}, \leq) with an ordered finite dimensional vector space \mathbb{V} and the order may be deduced from the data of a closed convex proper cone γ with non-empty interior. Then it is natural to endow \mathbb{V} with the so-called γ -topology \mathbb{V}_γ introduced in [KS90, Ch. III § 5]. We are led to the study of (derived) constructible γ -sheaves (that is, sheaves on \mathbb{V}_γ) and the category of such sheaves is no more equivalent to any natural category of barcodes. The aim of this paper, a kind of continuation of [KS18], is to find a substitute to this non existing equivalence.

First, we replace constructible sheaves with PL sheaves (PL for piecewise linear) which are much easier to manipulate. A convex polyhedron is the intersection of a finite family of open or closed affine half-spaces and a constructible sheaf F is PL if there is a finite covering of \mathbb{V} by convex polyhedra on which it is constant. It has been proved in loc. cit. that constructible sheaves may be approximated, for a kind of derived bottleneck distance, by PL sheaves and similarly for constructible γ -sheaves. A natural higher dimensional analogue to the category of γ -barcodes is given by the additive category of finite direct sums of constant sheaves on convex γ -locally closed polyhedra and the main result of this paper asserts that the triangulated category of PL γ -sheaves is generated by the additive category of such γ -barcodes.

This paper also contains a systematic study of PL-sheaves. We show in particular that a sheaf is PL if and only if its microsupport is a PL Lagrangian variety or, equivalently, is contained in such a Lagrangian variety. We note that the six Grothendieck operations hold for PL sheaves and that PL sheaves on \mathbb{V} may be considered as the restriction to \mathbb{V} of PL sheaves on its projective compactification \mathbb{P} . In the course of the paper, we recall several results of loc. cit. that we shall need and also give a new application of the stability theorem of the bottleneck distance.

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Remark 0.1. Some notations and conventions in this paper differ from those of [KS18].

(a) A polyhedron was called a polytope in loc. cit.

- (b) A PL set or a PL sheaf in loc. cit. is called here an LPL set or an LPL sheaf.
- (c) The microsupport of a sheaf F is denoted here by $\text{SS}(F)$ as in [KS90], instead of $\mu\text{supp}(F)$ in [KS18].

1 PL geometry

1.1 PL sets and PL stratifications

Let \mathbb{V} be a real finite-dimensional vector space.

Definition 1.1. (a) A *convex polyhedron* P in \mathbb{V} is the intersection of a finite family of open or closed affine half-spaces.

- (b) A PL set is a finite union of convex polyhedra.
- (c) A locally PL set (an LPL set for short) is a locally finite union of convex polyhedra.

Note that an LPL set is subanalytic.
The next result is obvious.

Lemma 1.2. (i) *The family of PL sets in \mathbb{V} is stable by finite unions and finite intersections.*

(ii) *If Z is PL, then its closure \overline{Z} , its interior $\text{Int}(Z)$ and its complementary set $\mathbb{V} \setminus Z$ are PL.*

(iii) *Any connected component of a PL set is PL.*

(iv) *Let $u: \mathbb{V} \rightarrow \mathbb{W}$ be a linear map.*

(a) *If $S \subset \mathbb{V}$ is PL, then $u(S) \subset \mathbb{W}$ is PL.*

(b) *If $Z \subset \mathbb{W}$ is PL, then $u^{-1}(Z) \subset \mathbb{V}$ is PL.*

(v) *The preceding results still hold when replacing PL with LPL, except (iva) in which case one has to assume that u is proper on \overline{S} .*

For a locally closed submanifold $Z \subset \mathbb{V}$, one sets for short

$$T_Z^*\mathbb{V} := T_Z^*U \text{ where } U \text{ is an open subset of } \mathbb{V} \text{ containing } Z \text{ as a closed subset.}$$

Definition 1.3. A PL-stratification of a set S of \mathbb{V} is a finite family $Z = \{Z_a\}_{a \in A}$ of non-empty convex polyhedra such that

- (i) $S = \bigcup_{a \in A} Z_a$,
- (ii) each Z_a is a locally closed submanifold,
- (iii) $Z_a \cap Z_b = \emptyset$ for $a \neq b$,

(iv) $Z_a \cap \overline{Z}_b \neq \emptyset$ implies $Z_a \subset \overline{Z}_b$.

Replacing “a finite family” with “a locally finite family” we get the notion of an LPL-stratification.

Recall the operation $\widehat{+}$ and the notion of a μ -stratification of [KS90, Def. 6.2.4, 8.3.19].

Proposition 1.4. *Let $Z = \{Z_a\}_{a \in A}$ be an LPL stratification. Then*

- (i) $\{Z_a\}_{a \in A}$ is a μ -stratification, that is, $Z_a \subset \overline{Z}_b$ implies $(T_{Z_a}^* \mathbb{V} \widehat{+} T_{Z_b}^* \mathbb{V}) \cap \pi^{-1}(Z_a) \subset T_{Z_a}^* \mathbb{V}$.
- (ii) Set $\Lambda = \bigsqcup_{a \in A} T_{Z_a}^* \mathbb{V}$. Then $\Lambda \widehat{+} \Lambda = \Lambda$.

Proof. We shall prove both statements together.

Assume that $Z_a \subset \overline{Z}_b \cap \overline{Z}_c$. We may assume (in a neighborhood of a point of Z_a) that $\mathbb{V} = \mathbb{W} \oplus \mathbb{W}'$ for two linear spaces \mathbb{W} and \mathbb{W}' and $Z_a = \mathbb{W}$. Then $Z_b = \mathbb{W} \times S$ and $Z_c = \mathbb{W} \times L$ where S is open in some linear subspace \mathbb{W}'' of \mathbb{W}' and similarly for L . Then one immediately checks that $(T_{Z_b}^* \mathbb{V} \widehat{+} T_{Z_c}^* \mathbb{V}) \cap \pi^{-1}(Z_a) \subset T_{Z_a}^* \mathbb{V}$.

This proves (ii). Choosing $c = a$ we get (i). \square

Proposition 1.5. *Consider a finite family $\{P_b\}_{b \in B}$ of convex polyhedra. Then there exists a PL-stratification $\mathbb{V} = \bigsqcup_{a \in A} Z_a$ such that each P_b is a union of strata.*

In the sequel, an interval of \mathbb{R} means a convex subset of \mathbb{R} .

Proof. There exists a finite family $\{f_1, \dots, f_l\}$ of linear forms and a finite family $\{I_c\}_{c \in C}$ such that each I_c is either an open interval or a point, $\mathbb{R} = \bigsqcup_{c \in C} I_c$ and for all $b \in B$,

$$P_b = \bigcap_{1 \leq j \leq l} f_j^{-1}(J_{j,b}), \text{ where } J_{j,b} \text{ is a union of some } I_c, c \in C.$$

For any family $d = \{c_1, \dots, c_l\} \in C^l$, set

$$Z_d = \bigcap_{j=1}^l f_j^{-1}(I_{c_j}).$$

Then the family $\{Z_d\}_{d \in C^l}$ is a PL-stratification of \mathbb{V} finer than the family $\{P_b\}_{b \in B}$. \square

1.2 PL Lagrangian subvarieties

Recall that the notions of co-isotropic, isotropic and Lagrangian subanalytic subvarieties are given in [KS90, Def. 6.5.1, 8.3.9].

Proposition 1.6. *Let Λ be a locally closed conic LPL isotropic subset of $T^*\mathbb{V}$. Then for any $p \in \Lambda_{\text{reg}}$ there exists a linear affine subspace $L \subset \mathbb{V}$ with $\Lambda \subset T_L^*\mathbb{V}$ in a neighborhood of p .*

Proof. If λ is a linear affine isotropic subspace of $T^*\mathbb{V}$, then there exists a linear affine subspace L of \mathbb{V} such that $\lambda \subset T_L^*\mathbb{V}$. \square

Lemma 1.7. *Let $\{L_a\}_{a \in A}$ be a finite family of affine linear subspaces in a vector space \mathbb{W} . Set $X = \bigcup_{a \in A} L_a$ and let S be a closed subset of X . Assume that $S \cap X_{\text{reg}}$ is open in X_{reg} and S is the closure of $S \cap X_{\text{reg}}$. Then S is PL.*

Proof. Indeed $S \cap X_{\text{reg}}$ is a locally finite union of connected components of X_{reg} . \square

Theorem 1.8. (a) *Let Λ be a locally closed conic PL isotropic subset of $T^*\mathbb{V}$. Then there exists a PL stratification $\{P_a\}_{a \in A}$ of \mathbb{V} such that $\Lambda \subset \bigsqcup_{a \in A} T_{P_a}^*\mathbb{V}$.*

(b) *Let Λ be a locally closed conic subanalytic Lagrangian subset of $T^*\mathbb{V}$ and assume that Λ is contained in a closed conic PL isotropic subset. Then Λ is PL.*

Proof. (a) Let $\{\Omega_i\}_{i \in I}$ be the family of connected components of Λ_{reg} . Note that the Ω_i 's are PL. Then there exists an affine linear subspace L_i such that $\Omega_i \subset T_{L_i}^*\mathbb{V}$ by Proposition 1.6. Choose a PL stratification $\{P_a\}_{a \in A}$ finer than the family $\{L_i\}_{i \in I}$. Then $\Lambda_{\text{reg}} \subset \bigsqcup T_{P_a}^*\mathbb{V}$ and Proposition 1.4 (ii) implies that this last set is closed, hence contains Λ .

(b) follows from Lemma 1.7 with $\mathbb{W} = T^*\mathbb{V}$. \square

Remark 1.9. In Lemma 1.7 and Theorem 1.8, all statements remain true when replacing everywhere “finite” with “locally finite” and “PL” with “LPL”.

2 PL sheaves

2.1 Review on sheaves

Let us recall some definitions extracted from [KS90] and a few notations.

- Throughout this paper, \mathbf{k} denotes a field. We denote by $\text{Mod}(\mathbf{k})$ the abelian category of \mathbf{k} -vector spaces.
- For an abelian category \mathcal{C} , we denote by $D^b(\mathcal{C})$ its bounded derived category. However, we write $D^b(\mathbf{k})$ instead of $D^b(\text{Mod}(\mathbf{k}))$.
- For a vector bundle $E \rightarrow M$, we denote by $a: E \rightarrow E$ the antipodal map, $a(x, y) = (x, -y)$. For a subset $Z \subset E$, we simply denote by Z^a its image by the antipodal map. In particular, for a cone γ in E , we denote by $\gamma^a = -\gamma$ the opposite cone. For such a cone, we denote by γ° the polar cone (or dual cone) in the dual vector bundle E^* :

$$(2.1) \quad \gamma^\circ = \{(x; \xi) \in E^*; \langle \xi, v \rangle \geq 0 \text{ for all } v \in \gamma_x\}.$$

- Let M be a real manifold of dimension $\dim M$. We shall use freely the classical notions of microlocal sheaf theory, referring to [KS90]. We denote by $\text{Mod}(\mathbf{k}_M)$ the abelian category of sheaves of \mathbf{k} -modules on M and by $D^b(\mathbf{k}_M)$ its bounded derived category. For short, an object of $D^b(\mathbf{k}_M)$ is called a “sheaf” on M .

- For a locally closed subset $Z \subset M$, one denotes by \mathbf{k}_Z the constant sheaf with stalk \mathbf{k} on Z extended by 0 on $M \setminus Z$. One defines similarly the sheaf L_Z for $L \in D^b(\mathbf{k})$.
- For $F \in D^b(\mathbf{k}_M)$ we denote by $\text{SS}(F)$ its singular support, or microsupport, a closed conic co-isotropic subset of T^*M .

Constructible sheaves

We refer the reader to [KS90] for terminologies not explained here.

Definition 2.1. Let M be a real analytic manifold and let $F \in \text{Mod}(\mathbf{k}_M)$. One says that F is weakly \mathbb{R} -constructible if there exists a subanalytic stratification $M = \bigsqcup_{a \in A} M_a$ such that for each stratum M_a , the restriction $F|_{M_a}$ is locally constant. If moreover, the stalk F_x is of finite rank for all $x \in M$, then one says that F is \mathbb{R} -constructible.

Notation 2.2. (i) One denotes by $\text{Mod}_{\mathbb{R}c}(\mathbf{k}_M)$ the abelian category of \mathbb{R} -constructible sheaves, a thick abelian subcategory of $\text{Mod}(\mathbf{k}_M)$.

(ii) One denotes by $D_{\mathbb{R}c}^b(\mathbf{k}_M)$ the full triangulated subcategory of $D^b(\mathbf{k}_M)$ consisting of sheaves with \mathbb{R} -constructible cohomology and by $D_{\mathbb{R}c,c}^b(\mathbf{k}_M)$ the full triangulated subcategory of $D_{\mathbb{R}c}^b(\mathbf{k}_M)$ consisting of sheaves with compact support.

Recall that the natural functor $D^b(\text{Mod}_{\mathbb{R}c}(\mathbf{k}_M)) \rightarrow D_{\mathbb{R}c}^b(\mathbf{k}_M)$ is an equivalence of categories.

2.2 Microlocal characterization of PL sheaves

Recall Remark 0.1.

Definition 2.3. One says that $F \in D^b(\mathbf{k}_{\mathbb{V}})$ is PL if there exists a finite family $\{P_a\}_{a \in A}$ of convex polyhedra such that $\mathbb{V} = \bigcup_{a \in A} P_a$ and $F|_{P_a}$ is constant of finite rank for any $a \in A$.

Replacing the finite family $\{P_a\}_{a \in A}$ with a locally finite family, we get the notion of an LPL sheaf.

By this definition

$$(2.2) \quad F \text{ is PL if and only if } H^j(F) \text{ is PL for all } j \in \mathbb{Z}.$$

One sets

$$(2.3) \quad \begin{cases} D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}}) := \{F \in D^b(\mathbf{k}_{\mathbb{V}}); F \text{ is PL}\}, \\ \text{Mod}_{\text{PL}}(\mathbf{k}_{\mathbb{V}}) := \text{Mod}(\mathbf{k}_{\mathbb{V}}) \cap D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}}). \end{cases}$$

Of course, $D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}})$ is a subcategory of $D_{\mathbb{R}c}^b(\mathbf{k}_{\mathbb{V}})$ and $\text{Mod}_{\text{PL}}(\mathbf{k}_{\mathbb{V}})$ is a subcategory of $\text{Mod}_{\mathbb{R}c}(\mathbf{k}_{\mathbb{V}})$.

Proposition 2.4. *The natural functor $D^b(\text{Mod}_{\text{PL}}(\mathbf{k}_{\mathbb{V}})) \rightarrow D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}})$ is an equivalence.*

Proof. There exists a triangulation $\mathbb{S} = (S, \Delta)$ and a homeomorphism $f: |\mathbb{S}| \rightarrow \mathbb{V}$ such that its restriction to $|\sigma|$ is linear for any $\sigma \in \Delta$. Then the result follows from [KS90, Th. 8.1.10]. \square

Theorem 2.5. *Let $F \in D_{\mathbb{R}c}^b(\mathbf{k}_{\mathbb{V}})$. Then the conditions below are equivalent.*

- (a) $F \in D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}})$,
- (b) $\text{SS}(F)$ is a closed conic PL Lagrangian subset of $T^*\mathbb{V}$,
- (c) $\text{SS}(F)$ is contained in a closed conic PL isotropic subset of $T^*\mathbb{V}$.

Proof. (a) \Rightarrow (c) Consider a finite covering $\{P_b\}_{b \in B}$ by convex polyhedra such that $F|_{P_b}$ is constant and choose a finer PL stratification $\mathbb{V} = \bigsqcup_{a \in A} Z_a$. This is a μ -stratification and this implies $\text{SS}(F) \subset \bigsqcup_{a \in A} T_{Z_a}^* \mathbb{V}$ by [KS90, Prop. 8.4.1].

(b) \Rightarrow (a) By Theorem 1.8 (a), there exists a PL stratification $\mathbb{V} = \bigsqcup_{a \in A} Z_a$ such that $\text{SS}(F) \subset \bigsqcup_{a \in A} T_{Z_a}^* \mathbb{V}$. Then $F|_{Z_a}$ is locally constant for each $a \in A$ by [KS90, Prop. 8.4.1].

(b) \Leftrightarrow (c) in view of Theorem 1.8 (b). \square

The next result immediately follows from Definition 2.3. It can also easily be deduced from [KS90], Theorem 1.8 and Theorem 2.5.

Corollary 2.6. (i) *The category $D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}})$ is a full triangulated subcategory of the category $D^b(\mathbf{k}_{\mathbb{V}})$ and the category $\text{Mod}_{\text{PL}}(\mathbf{k}_{\mathbb{V}})$ is a full thick abelian subcategory of the category $\text{Mod}(\mathbf{k}_{\mathbb{V}})$.*

(ii) *If F_1 and F_2 are PL, then so are $F_1 \otimes F_2$ and $\text{R}\mathcal{H}om(F_1, F_2)$.*

(iii) *Let $f: \mathbb{V} \rightarrow \mathbb{W}$ be a linear map.*

(a) *If G is a PL sheaf on \mathbb{W} , then $f^{-1}G$ and $f^!G$ are PL sheaves on \mathbb{V} .*

(b) *If F is a PL sheaf on \mathbb{V} then $\text{R}f_*F$ and $\text{R}f_!F$ are PL sheaves on \mathbb{W} .*

Recall that the convolution functor $\star: D^b(\mathbf{k}_{\mathbb{V}}) \times D^b(\mathbf{k}_{\mathbb{V}}) \rightarrow D^b(\mathbf{k}_{\mathbb{V}})$ is defined by the formula:

$$F \star G := \text{R}s_!(F \boxtimes G),$$

where $s: \mathbb{V} \times \mathbb{V} \rightarrow \mathbb{V}$ is the map $(x, y) \mapsto x + y$.

Corollary 2.7. *The convolution functor induces a functor $\star: D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}}) \times D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}}) \rightarrow D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}})$.*

Proposition 2.8. *Let Z be a locally closed subset of \mathbb{V} . Then Z is PL if and only if $\text{SS}(\mathbf{k}_Z)$ is PL.*

Proof. (i) Assume that Z is PL. Then the sheaf \mathbf{k}_Z is PL and its microsupport is PL by Theorem 2.5.

(ii) Conversely, assume that $\text{SS}(\mathbf{k}_Z)$ is PL. Set $\partial Z = \overline{Z} \setminus Z$. Since Z is locally closed, ∂Z is closed.

(ii)–(a) First, notice that $\overline{Z} = \pi(\text{SS}(\mathbf{k}_Z))$ is PL.

(ii)–(b) Now consider the exact sequence of sheaves $0 \rightarrow \mathbf{k}_Z \rightarrow \mathbf{k}_{\overline{Z}} \rightarrow \mathbf{k}_{\partial Z} \rightarrow 0$. Since \mathbf{k}_Z and $\mathbf{k}_{\overline{Z}}$ are PL sheaves, the sheaf $\mathbf{k}_{\partial Z}$ is PL. Therefore, ∂Z is PL and it follows that Z is PL. \square

2.3 PL sheaves on the projective space

Let $\mathbb{V} \hookrightarrow \mathbb{P}$ be the projective compactification of \mathbb{V} . Hence, setting $\mathbb{W} = \mathbb{V} \times \mathbb{R}$,

$$\mathbb{P} \simeq (\mathbb{W} \setminus \{0\})/\mathbb{R}^\times,$$

where \mathbb{R}^\times is the multiplicative group $\mathbb{R} \setminus \{0\}$. Denote by $\pi: \mathbb{W} \setminus \{0\} \rightarrow \mathbb{P}$ the projection and by $\iota: \mathbb{W} \setminus \{0\} \hookrightarrow \mathbb{W}$ the embedding.

We shall say that a subset A of \mathbb{P} is PL if $\iota(\pi^{-1}(A))$ is PL in \mathbb{W} .

Similarly, one defines the category of PL sheaves $D_{\text{PL}}^b(\mathbf{k}_{\mathbb{P}})$ as the full subcategory of $D_{\mathbb{R}^c}^b(\mathbf{k}_{\mathbb{P}})$ consisting of objects F such that $\iota_! \pi^{-1} F \in D_{\text{PL}}^b(\mathbf{k}_{\mathbb{W}})$.

Denote by $j: \mathbb{V} \hookrightarrow \mathbb{P}$ the open embedding and by $H_\infty = \mathbb{P} \setminus j(\mathbb{V})$ the hyperplane at infinity. The next result is easy and its proof is left to the reader.

Proposition 2.9. *The functor $j_!: D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}}) \rightarrow D_{\text{PL}}^b(\mathbf{k}_{\mathbb{P}})$ is well-defined, is fully faithful and its essential image consists of objects F such that $F|_{H_\infty} \simeq 0$.*

2.4 Distance, approximation and stability

The bottleneck distance for persistent modules is a classical subject that we shall not review here, referring to [CSEH07] and [CCSG⁺09, CdSGO16, Cur13, EH08, Ghr08, Les15]. Here, we use a convolution distance for sheaves similar to that of [KS18] and slightly different from the classical ones since it is defined in the derived setting. Note that this “derived” distance has recently been studied with great details in [BG18] in case of dimension one.

Assume that the vector space \mathbb{V} is endowed with a norm $\|\cdot\|$ (see Remark 2.10 below). We define a family of sheaves $\{K_a\}_{a \in \mathbb{R}}$ as follows:

$$(2.4) \quad K_a \simeq \begin{cases} \mathbf{k}_{\{\|x\| \leq a\}} & \text{for } a \geq 0, \\ \mathbf{k}_{\{\|-x\| < -a\}}[\dim \mathbb{V}] & \text{for } a < 0. \end{cases}$$

There are natural morphisms and isomorphisms

$$(2.5) \quad \begin{aligned} \chi_{a,b}: K_b &\rightarrow K_a \text{ for } a \leq b \in \mathbb{R}, \\ K_a \star K_b &\simeq K_{a+b} \text{ for } a, b \in \mathbb{R} \end{aligned}$$

such that $\chi_{a,b} \circ \chi_{b,c} = \chi_{a,c}$ for $a \leq b \leq c$.

Remark 2.10. In [KS18] we have used the Euclidean norm, but the argument works for any norm, since (2.5) remains true. Here a norm $\|\cdot\|: \mathbb{V} \rightarrow \mathbb{R}_{\geq 0}$ satisfies (1) $\|x+y\| \leq \|x\| + \|y\|$, (2) $\|ax\| = a\|x\|$ for $a \geq 0$, and (3) $\|x\| = 0$ implies $x = 0$. Hence norms correspond bijectively with open relatively compact convex neighborhood of 0. Note that we do not ask $\|x\| = \|-x\|$ and that is why we define K_a for $a < 0$ as above, in order that $K_a \star K_{-a} \simeq K_0$.

Definition 2.11. ([KS18, Def. 3.2]) Let $F, G \in D^b(\mathbf{k}_{\mathbb{V}})$ and let $a \geq 0$. One says that F and G are *a-isomorphic* if there are morphisms $f: K_a \star F \rightarrow G$ and $g: K_a \star G \rightarrow F$ which satisfies the following compatibility conditions: the composition $K_{2a} \star F \xrightarrow{K_a \star f} K_a \star G \xrightarrow{g} F$ coincides with the natural morphism $\chi_{0,2a} \star F: K_{2a} \star F \rightarrow F$ and the composition $K_{2a} \star G \xrightarrow{K_a \star g} K_a \star F \xrightarrow{f} G$ coincides with the natural morphism $\chi_{0,2a} \star G: K_{2a} \star G \rightarrow G$.

One sets

$$\text{dist}(F, G) = \inf\left(\{+\infty\} \cup \{a \in \mathbb{R}_{\geq 0}; F \text{ and } G \text{ are } a\text{-isomorphic}\}\right)$$

and calls $\text{dist}(\cdot, \cdot)$ the *convolution distance*.

In loc. cit. we have proved that any object of $D_{\mathbb{R}c}^b(\mathbf{k}_{\mathbb{V}})$ can be approximated with LPL-sheaves. A similar result holds for constructible sheaves on \mathbb{V}_{∞} .

Notation 2.12. Let us denote by $D_{\mathbb{R}c}^b(\mathbf{k}_{\mathbb{V}_{\infty}})$ the full subcategory of $D_{\mathbb{R}c}^b(\mathbf{k}_{\mathbb{V}})$ consisting of objects F such that there exists $G \in D_{\mathbb{R}c}^b(\mathbf{k}_{\mathbb{P}})$ with $F \simeq G|_{\mathbb{V}}$.

Theorem 2.13 (The approximation theorem). *Let $F \in D_{\mathbb{R}c}^b(\mathbf{k}_{\mathbb{V}_{\infty}})$. For each $\varepsilon > 0$ there exists $G \in D_{\mathbb{P}L}^b(\mathbf{k}_{\mathbb{V}})$ such that $\text{dist}(F, G) \leq \varepsilon$ and $\text{supp}(G) \subset \text{supp}(F) + B_{\varepsilon}$, where $B_{\varepsilon} = \{x; \|x\| \leq \varepsilon\}$.*

The proof is the same as in [KS18] after noticing that one can choose the simplicial complex $\mathbf{S} = (S, \Delta)$ (with the notations of loc. cit.) to be finite, thanks to the fact that $F \in D_{\mathbb{R}c}^b(\mathbf{k}_{\mathbb{V}_{\infty}})$.

Recall the stability theorem of [KS18, Th. 3.7], a derived version of a classical theorem (see [CSEH07]).

For a set X and a map $f: X \rightarrow \mathbb{V}$, one sets

$$\|f\| = \sup_{x \in X} \|f(x)\|.$$

Theorem 2.14 (The stability theorem). *Let X be a locally compact space and let $f_1, f_2: X \rightarrow \mathbb{V}$ be two continuous maps. Then, for any $F \in D^b(\mathbf{k}_X)$, we have*

$$\text{dist}(Rf_{1*}F, Rf_{2*}F) \leq \|f_1 - f_2\| \quad \text{and} \quad \text{dist}(Rf_{1!}F, Rf_{2!}F) \leq \|f_1 - f_2\|.$$

2.5 Generators for PL sheaves

Consider a triangulated category \mathcal{D} and a family of objects \mathcal{G} . Consider the full subcategory \mathcal{T} of \mathcal{D} defined as follows. An object $F \in \mathcal{D}$ belongs to \mathcal{T} if there exists a finite sequence F_0, \dots, F_N in \mathcal{D} with $F_0 = 0$, $F_N = F$ and distinguished triangles (d. t. for short) $F_k \rightarrow F_{k+1} \rightarrow G_k[m_k] \xrightarrow{+1}$, $0 \leq k < N$ with $m_k \in \mathbb{Z}$ and $G_k \in \mathcal{G}$.

The next result is well-known from the specialists but we recall its proof for the reader's convenience.

Lemma 2.15. *The subcategory \mathcal{T} of \mathcal{D} is triangulated. It is the smallest triangulated subcategory of \mathcal{D} which contains \mathcal{G} .*

Proof. We may assume from the beginning that \mathcal{G} is an additive category stable by isomorphisms and by shifts. Define the additive subcategory \mathcal{T}_n by induction as follows:

$$\mathcal{T}_0 = \{0\}, X \in \mathcal{T}_n \text{ if and only if there is a d. t. } X_{n-1} \rightarrow X \rightarrow X_1 \xrightarrow{+1} \\ \text{with } X_{n-1} \in \mathcal{T}_{n-1} \text{ and } X_1 \in \mathcal{G}.$$

Clearly, $\mathcal{T}_1 = \mathcal{G}$.

Consider a d. t. $X_n \rightarrow X \xrightarrow{\alpha} X_p \xrightarrow{+1}$ with $X_i \in \mathcal{T}_i$ as above. By the definition of \mathcal{T}_p , there exists a d. t. $X_{p-1} \rightarrow X_p \xrightarrow{\beta} X_1 \xrightarrow{+1}$ with $X_i \in \mathcal{T}_i$, $i = p-1, 1$. Consider a d. t. $Y \rightarrow X \xrightarrow{\beta \circ \alpha} X_1 \xrightarrow{+1}$. By the octahedral axiom we get a d. t. $X_n \rightarrow Y \rightarrow X_{p-1} \xrightarrow{+1}$. By the induction hypothesis, $Y \in \mathcal{T}_{n+p-1}$. Hence $X \in \mathcal{T}_{n+p}$. \square

In this paper, we shall say that \mathcal{G} generates \mathcal{D} if $\mathcal{T} = \mathcal{D}$.

Theorem 2.16. *The triangulated category $D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}})$ is generated by the family $\{\mathbf{k}_P\}$ where P ranges over the family of locally closed convex polyhedra.*

Proof. (i) We denote by \mathcal{G} the family of sheaves isomorphic to some \mathbf{k}_P , P a locally closed convex polyhedron, and denote by \mathcal{T} the triangulated subcategory of $D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}})$ generated by \mathcal{G} .

(ii) We argue by induction on $\dim \mathbb{V}$. The case where $\dim \mathbb{V}$ is 0 is clear.

(iii) Let $F \in D_{\text{PL}}^b(\mathbf{k}_{\mathbb{V}})$. By truncation, we may reduce to the case where F is concentrated in degree 0.

(iv) There exists a finite family $\{H_a\}_{a \in A}$ of affine hyperplanes such that, setting $U = \mathbb{V} \setminus \bigcup_a H_a$, the restriction of F to U is locally constant. Let $U = \bigsqcup_i U_i$ be the decomposition of U into connected component. Each U_i is an open convex polyhedron. Set $Z = \bigcup_a H_a$ and consider the exact sequence $0 \rightarrow F_U \rightarrow F \rightarrow F_Z \rightarrow 0$. The sheaf F_U is a finite direct sum of sheaves of the type \mathbf{k}_{U_i} . Hence $F_U \in \mathcal{T}$ and it remains to show that F_Z belongs to \mathcal{T} .

(v) We argue by induction on $\#A$. If $\#A = 1$, then the result follows from the induction hypothesis on the dimension of \mathbb{V} since we may identify F_{H_a} with a sheaf on the affine space H_a . Let $a \in A$ and define G by the exact sequence $0 \rightarrow G \rightarrow F_Z \rightarrow F_{H_a} \rightarrow 0$. By the induction hypothesis G and F_{H_a} belong to \mathcal{T} and the result follows. \square

3 PL γ -sheaves

3.1 Review on γ -sheaves

In this subsection we shall review some definitions and results extracted from [KS90, KS18]. The so-called γ -topology has been studied with some details in [KS90, § 3.4].

Let \mathbb{V} be a finite-dimensional real vector space. Recall that we denote by $a: \mathbb{V} \rightarrow \mathbb{V}$ the antipodal map $x \mapsto -x$ and by $s: \mathbb{V} \times \mathbb{V} \rightarrow \mathbb{V}$ the map $(x, y) \mapsto x + y$. Hence, for two subsets A, B of \mathbb{V} , one has $A + B = s(A \times B)$.

A subset A of \mathbb{V} is called a cone if $0 \in A$ and $\mathbb{R}_{>0}A \subset A$. A convex cone A is proper if $A \cap A^a = \{0\}$.

Throughout the rest of the paper, we consider a cone $\gamma \subset \mathbb{V}$ and we assume:

(3.1) γ is closed proper convex with non-empty interior.

In § 3.3 we shall make the extra assumption that γ is *polyhedral*, meaning that it is a finite intersection of closed half-spaces.

We say that a subset A of \mathbb{V} is γ -invariant if $A + \gamma = A$. Note that a subset A is γ -invariant if and only if $\mathbb{V} \setminus A$ is γ^a -invariant.

The family of γ -invariant open subsets of \mathbb{V} defines a topology, which is called the γ -topology on \mathbb{V} . One denotes by \mathbb{V}_γ the space \mathbb{V} endowed with the γ -topology and one denotes by

$$(3.2) \quad \varphi_\gamma: \mathbb{V} \rightarrow \mathbb{V}_\gamma$$

the continuous map associated with the identity. Note that the closed sets for this topology are the γ^a -invariant closed subsets of \mathbb{V} .

Definition 3.1. Let A be a subset of \mathbb{V} .

- (a) One says that A is γ -open (resp. γ -closed) if A is open (resp. closed) for the γ -topology.
- (b) One says that A is γ -locally closed if A is the intersection of a γ -open subset and a γ -closed subset.
- (c) One says that A is γ -flat if $A = (A + \gamma) \cap (A + \gamma^a)$.
- (d) One says that a closed set A is γ -proper if the addition map s is proper on $A \times \gamma^a$.

Remark that a closed subset A is γ -proper if and only if $A \cap (x + \gamma)$ is compact for any $x \in \mathbb{V}$.

Proposition 3.2 ([KS18, Prop. 4.4]). *The set of γ -flat open subsets Ω of \mathbb{V} and the set of γ -locally closed subsets Z of \mathbb{V} correspond bijectively by*

$$\begin{aligned} \Omega &\longmapsto (\Omega + \gamma) \cap \overline{\Omega + \gamma^a} \\ \text{Int}(Z) &\longleftarrow Z. \end{aligned}$$

In particular, γ -locally closed subsets are γ -flat.

We shall use the notations:

$$(3.3) \quad \begin{cases} D_{\gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}}) := \{F \in D^b(\mathbf{k}_{\mathbb{V}}); \text{SS}(F) \subset \mathbb{V} \times \gamma^{oa}\}, \\ D_{\mathbb{R}c, \gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}}) := D_{\mathbb{R}c}^b(\mathbf{k}_{\mathbb{V}}) \cap D_{\gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}}), \\ \text{Mod}_{\gamma^{oa}}(\mathbf{k}_{\mathbb{V}}) := \text{Mod}(\mathbf{k}_{\mathbb{V}}) \cap D_{\gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}}), \\ \text{Mod}_{\mathbb{R}c, \gamma^{oa}}(\mathbf{k}_{\mathbb{V}}) := \text{Mod}_{\mathbb{R}c}(\mathbf{k}_{\mathbb{V}}) \cap \text{Mod}_{\gamma^{oa}}(\mathbf{k}_{\mathbb{V}}). \end{cases}$$

We call an object of $D_{\gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$ a γ -sheaf.

It follows from [KS90, Prop. 5.4.14] that for $F, G \in D_{\gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$ and $H \in D_{\gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$, the sheaves $F \otimes G$ and $R\mathcal{H}om(H, F)$ belong to $D_{\gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$.

The next result is implicitly proved in [KS90] and explicitly in [KS18]. (In this statement, the hypothesis that $\text{Int}(\gamma)$ is non empty is not necessary.)

Theorem 3.3. *Let γ be a closed convex proper cone in \mathbb{V} . The functor $R\varphi_{\gamma^*}: D_{\gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}}) \rightarrow D^b(\mathbf{k}_{\mathbb{V}_\gamma})$ is an equivalence of triangulated categories with quasi-inverse φ_γ^{-1} . Moreover, this equivalence preserves the natural t -structures of both categories. In particular, for $F \in D^b(\mathbf{k}_{\mathbb{V}})$, the condition $F \in D_{\gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$ is equivalent to the condition: $\text{SS}(H^j(F)) \subset \mathbb{V} \times \gamma^{oa}$ for any $j \in \mathbb{Z}$.*

Thanks to this theorem, the reader may ignore microlocal sheaf theory, at least in a first reading.

Corollary 3.4 ([KS18, Cor. 2.8]). *Let A be a γ -locally closed subset of \mathbb{V} . Then $\text{SS}(\mathbf{k}_A) \subset \mathbb{V} \times \gamma^{oa}$.*

Proposition 3.5. *Assume (3.1). Let $U = U + \gamma$ be a γ -open set and let $x_0 \in \partial U$. Then there exist a linear coordinate system (x_1, \dots, x_n) on \mathbb{V} , an open neighborhood V of x_0 , an open subset W of \mathbb{V} and a bi-Lipschitz isomorphism $\varphi: V \xrightarrow{\simeq} W$ such that $\varphi(V \cap U) = W \cap \{x \in \mathbb{V}; x_n > 0\}$.*

Proof. The proofs of [GS16, Lem. 2.36, 2.37] (which were formulated for subanalytic open subsets) extend immediately to our situation. \square

Recall the duality functor

$$D'_M(\bullet) = R\mathcal{H}om(\bullet, \mathbf{k}_M).$$

Corollary 3.6. *Let Z be a γ -locally closed subset of \mathbb{V} . Then, $D'_M(\mathbf{k}_Z)$ is concentrated in degree 0. Moreover, $D'_M(\mathbf{k}_Z) \simeq \mathbf{k}_S$ with $\Omega = \text{Int}(Z)$ and $S = \overline{\Omega} + \gamma \cap (\Omega + \gamma^a)$.*

Proof. It follows from Proposition 3.5 that $D'_M(\mathbf{k}_{\Omega+\gamma}) \simeq \mathbf{k}_{\overline{\Omega+\gamma}}$ and $D'_M(\mathbf{k}_{\overline{\Omega+\gamma^a}}) \simeq \mathbf{k}_{\Omega+\gamma^a}$.

Set $A = \Omega + \gamma$ and $B = \overline{\Omega} + \gamma^a$. Then \mathbf{k}_A and \mathbf{k}_B are cohomologically constructible. By Corollary 3.4, $\text{SS}(\mathbf{k}_A) \cap \text{SS}(\mathbf{k}_B) \subset T_{\mathbb{V}}^*\mathbb{V}$. Then $D'_M(\mathbf{k}_A \otimes \mathbf{k}_B) \simeq D'_M(\mathbf{k}_A) \otimes D'_M(\mathbf{k}_B)$ by [KS90, Cor. 6.4.3]. \square

3.2 An application of the stability theorem

Here we give an application of the stability theorem (Theorem 2.14) which did not appear in [KS18]. Of course, this application is well-known for the classical (non-derived) distance.

Let (M, d) be a subanalytic metric space and let K_1 and K_2 be two subanalytic compact subsets. Define for $i = 1, 2$

$$\begin{aligned} f_i(\cdot) &= d(\cdot, K_i), \\ \Gamma_i &= \{(x, t) \in M \times \mathbb{R}; d(x, K_i) = t\}, \quad G_i = \mathbf{k}_{\Gamma_i}, \\ Z_i &= \{(x, t) \in M \times \mathbb{R}; d(x, K_i) \leq t\}, \quad F_i = \mathbf{k}_{Z_i}. \end{aligned}$$

Hence, Γ_i is the graph of f_i and Z_i is the epigraph of f_i .

Lemma 3.7. *One has $d(K_1, K_2) = \|f_1 - f_2\|$.*

Lemma 3.8. *One has $\text{dist}(\mathbf{R}f_{1*}\mathbf{k}_M, \mathbf{R}f_{2*}\mathbf{k}_M) \leq \|f_1 - f_2\|$.*

Proof. This is a particular case of Theorem 2.14. □

Lemma 3.9. *Denote by γ the cone $\{t \leq 0\}$ in \mathbb{R} and still denote by φ_γ the map $M \times \mathbb{R} \rightarrow M \times \mathbb{R}_\gamma$. Then $F_i \simeq \varphi_\gamma^{-1}\mathbf{R}\varphi_{\gamma*}G_i$.*

Let p denote the projection $M \times \mathbb{R} \rightarrow \mathbb{R}$.

Lemma 3.10. *One has $\text{dist}(\mathbf{R}p_*\varphi_\gamma^{-1}\mathbf{R}\varphi_{\gamma*}G_1, \mathbf{R}p_*\varphi_\gamma^{-1}\mathbf{R}\varphi_{\gamma*}G_2) \leq \text{dist}(\mathbf{R}p_*G_1, \mathbf{R}p_*G_2)$.*

Proof. The two functors $\mathbf{R}p_*$ and $\varphi_\gamma^{-1}\mathbf{R}\varphi_{\gamma*}$ commute (with obvious notations). Then the result follows from [KS18, Prop. 3.6]. □

Applying these lemmas, one gets a derived version of a result of [CSEH07].

Theorem 3.11. *One has $\text{dist}(\mathbf{R}p_*F_1, \mathbf{R}p_*F_2) \leq d(K_1, K_2)$.*

Proof. We have

$$\mathbf{R}p_*G_i \simeq \mathbf{R}f_{i*}\mathbf{k}_M.$$

Applying Lemma 3.8, we get

$$\text{dist}(\mathbf{R}p_*G_1, \mathbf{R}p_*G_2) \leq \|f_1 - f_2\|.$$

To conclude, apply Lemma 3.9, 3.10 and 3.7. □

3.3 Review on PL γ -sheaves

From now on, we shall assume that the cone γ satisfies:

(3.4) γ is a closed proper convex polyhedral cone with non-empty interior.

Definition 3.12. Assume (3.4).

- (a) A PL γ -barcode (A, Z) in \mathbb{V} is the data of a finite set of indices A and a family $Z = \{Z_a\}_{a \in A}$ of non-empty, γ -locally closed, convex polyhedra of \mathbb{V} .
- (b) A disjoint γ -barcode is a γ -barcode (A, Z) such that $Z_a \cap Z_b = \emptyset$ for $a \neq b$.
- (c) The support of a γ -barcode (A, Z) , denoted by $\text{supp}(A, Z)$, is the set $\bigcup_{a \in A} \overline{Z_a}$.

Remark 3.13. In [KS18], we defined a PL γ -stratification of a closed set S as a barcode (A, Z) such that $\text{supp}(A, Z) = S$ and $Z_a \cap Z_b = \emptyset$ for $a \neq b$. However, since a PL γ -stratification is not a PL stratification (see Definition 1.3), we prefer here to avoid this terminology and use the notion of a disjoint γ -barcode.

We shall use the notations:

$$(3.5) \quad \begin{cases} D_{\text{PL}, \gamma^{\text{oa}}}^{\text{b}}(\mathbf{k}_{\mathbb{V}}) := D_{\text{PL}}^{\text{b}}(\mathbf{k}_{\mathbb{V}}) \cap D_{\gamma^{\text{oa}}}^{\text{b}}(\mathbf{k}_{\mathbb{V}}), \\ \text{Mod}_{\text{PL}, \gamma^{\text{oa}}}(\mathbf{k}_{\mathbb{V}}) := \text{Mod}(\mathbf{k}_{\mathbb{V}}) \cap D_{\text{PL}, \gamma^{\text{oa}}}^{\text{b}}(\mathbf{k}_{\mathbb{V}}). \end{cases}$$

Note that, in view of (2.2) and Theorem 3.3:

$$(3.6) \quad F \in D_{\text{PL}, \gamma^{\text{oa}}}^{\text{b}}(\mathbf{k}_{\mathbb{V}}) \Leftrightarrow H^j(F) \in \text{Mod}_{\text{PL}, \gamma^{\text{oa}}}(\mathbf{k}_{\mathbb{V}}) \text{ for all } j \in \mathbb{Z}.$$

Proposition 3.14. Assume (3.4). If $F \in D_{\text{PL}}^{\text{b}}(\mathbf{k}_{\mathbb{V}})$ then $\varphi_{\gamma}^{-1} \text{R}\varphi_{\gamma*} F \in D_{\text{PL}, \gamma^{\text{oa}}}^{\text{b}}(\mathbf{k}_{\mathbb{V}})$.

Proof. By Theorem 3.3, it remains to prove that $\varphi_{\gamma}^{-1} \text{R}\varphi_{\gamma*} F$ is PL. Denote by $Z(\gamma)$ the set $\{(x, y) \in \mathbb{V} \times \mathbb{V}; y - x \in \gamma\}$ and denote by q_1 and q_2 the first and second projections defined on $\mathbb{V} \times \mathbb{V}$. Then (see [KS90, Prop. 3.5.4]):

$$\varphi_{\gamma}^{-1} \text{R}\varphi_{\gamma*} F \simeq \text{R}q_{1*}(\mathbf{k}_{Z(\gamma)} \otimes q_2^{-1} F)$$

and the result follows from Corollary 2.6. \square

Recall Notation 2.12.

Corollary 3.15. Let $F \in D_{\mathbb{R}\mathbf{c}, \gamma^{\text{oa}}}^{\text{b}}(\mathbf{k}_{\mathbb{V}_{\infty}})$. For each $\varepsilon > 0$ there exists $G \in D_{\text{PL}, \gamma^{\text{oa}}}^{\text{b}}(\mathbf{k}_{\mathbb{V}})$ such that $\text{dist}(F, G) \leq \varepsilon$.

Proof. We shall apply Theorem 2.13. There exists $G' \in D_{\text{PL}}^{\text{b}}(\mathbf{k}_{\mathbb{V}})$ such that $\text{dist}(F, G') \leq \varepsilon$. Then, $G := \varphi_{\gamma}^{-1} \text{R}\varphi_{\gamma*} G' \in D_{\text{PL}, \gamma^{\text{oa}}}^{\text{b}}(\mathbf{k}_{\mathbb{V}})$ by Proposition 3.14. Moreover, by [KS18, Prop. 3.6]:

$$\text{dist}(\varphi_{\gamma}^{-1} \text{R}\varphi_{\gamma*} F, \varphi_{\gamma}^{-1} \text{R}\varphi_{\gamma*} G') \leq \text{dist}(F, G') \leq \varepsilon.$$

Since F is a γ -sheaf, one has $\varphi_{\gamma}^{-1} \text{R}\varphi_{\gamma*} F \simeq F$. \square

The three theorems below are the main results of [KS18]. We recall them for the reader's convenience.

Theorem 3.16 ([KS18, Th. 4.10]). *Assume (3.4) and let $F \in D_{\mathbb{R}C, \gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$. Then for each $x \in \mathbb{V}$, there exists an open neighborhood U of x such that $F|_{(x+\gamma^a) \cap U}$ is constant.*

Theorem 3.17 ([KS18, Th. 4.14]). *Assume (3.4) and let $F \in D_{\mathbb{R}C, \gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$. Let Ω be a γ -flat open set and let $Z = (\Omega + \gamma) \cap \overline{\Omega + \gamma^a}$, a γ -locally closed subset. Assume that $F|_{\Omega}$ is locally constant. Then $F|_Z$ is locally constant.*

Theorem 3.18 ([KS18, Lem. 4.16, Th. 4.17]). *Assume (3.4) and let $F \in D_{\text{PL}, \gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$. Then there exists a disjoint γ -barcode (A, Z) with $\text{supp}(A, Z) = \text{supp}(F)$ and such that $F|_{Z_a}$ is constant for each $a \in A$. Moreover, $F_x \simeq 0$ for $x \notin \bigsqcup_{a \in A} Z_a$.*

(In fact, Theorem 3.18 was proved for LPL sheaves but the proof can easily be adapted to PL sheaves.)

3.4 Generators for PL γ -sheaves

In [KS18] we have constructed a category \mathbf{Bar}_{γ} whose objects are the γ -barcodes and a fully faithful functor

$$(3.7) \quad \Psi: \mathbf{Bar}_{\gamma} \rightarrow \text{Mod}_{\text{PL}, \gamma^{oa}}(\mathbf{k}_{\mathbb{V}}), \quad Z = \{Z_a\}_{a \in A} \mapsto \bigoplus_{a \in A} \mathbf{k}_{Z_a}.$$

However, as shown in [KS18, Ex. 2.14, 2.15], the functor Ψ is not essentially surjective as soon as $\dim \mathbb{V} > 1$.

Definition 3.19. An object of $\text{Mod}_{\text{PL}, \gamma^{oa}}(\mathbf{k}_{\mathbb{V}})$ is a barcode γ -sheaf if it is in the essential image of Ψ .

In [KS18] we made the following conjecture.

Conjecture 3.20. Let $F \in D_{\text{PL}, \gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$ and assume that F has compact support. Then there exists a bounded complex $F^{\bullet} \in C^b(\text{Mod}_{\text{PL}, \gamma^{oa}}(\mathbf{k}_{\mathbb{V}_{\gamma}}))$ whose image in $D_{\text{PL}, \gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$ is isomorphic to F and such that each component F^j of F^{\bullet} is a barcode γ -sheaf with compact support.

As usual, for an additive category \mathcal{C} , $C^b(\mathcal{C})$ denotes the category of bounded complexes of objects of \mathcal{C} .

In this subsection, we shall prove a weaker form of this conjecture, namely:

Theorem 3.21. *The triangulated category $D_{\text{PL}, \gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$ is generated by the family $\{\mathbf{k}_P\}_P$ where P ranges over the family of γ -locally closed convex polyhedra.*

In particular, the category $D_{\text{PL}, \gamma^{oa}}^b(\mathbf{k}_{\mathbb{V}})$ is generated by the barcodes γ -sheaves.

Proof. Let $F \in \text{Mod}_{\text{PL}, \gamma^{\text{oa}}}(\mathbf{k}_{\mathbb{V}})$. There exists $\{\xi_k\}_{1 \leq k \leq l}$ in γ^{0a} and $\{c_j\}_{0 \leq j \leq N}$ in \mathbb{R} with $-\infty = c_0 < c_1 < \dots < c_{N-1} < c_N = +\infty$ such that, setting

$$H_{k,j} = \{x \in \mathbb{V}; \langle x, \xi_k \rangle = c_j\}, \quad U := \mathbb{V} \setminus \bigsqcup_{k,j} H_{k,j},$$

the sheaf $F|_U$ is locally constant.

For $n = (n_1, \dots, n_l)$ with $0 \leq n_k < N$, define

$$Z_n = \bigcap_{k=1}^l \{x; c_{n_k} \leq \langle x, \xi_k \rangle < c_{1+n_k}\}, \quad \Omega_n = \bigcap_{k=1}^l \{x; c_{n_k} < \langle x, \xi_k \rangle < c_{1+n_k}\}.$$

Then $Z_n = \overline{\Omega_n + \gamma^a} \cap (\Omega_n + \gamma)$ and Z_n is γ -locally closed.

Since F_{Ω_n} is constant, F_{Z_n} is constant by Theorem 3.17.

Now we have $\mathbb{V} = \bigsqcup_{n \in [0, N-1]^l} Z_n$. Set $A = \{n \in [0, N-1]^l; F|_{Z_n} \not\cong 0\}$. Then $\text{supp}(F) = \bigcup_{n \in A} \overline{Z_n}$.

Lemma 3.22. *There exists $n \in A$ such that Z_n is open in $\text{supp}(F)$.*

Proof of the lemma. We order the set of n 's by $n \leq n'$ if $n_j \leq n'_j$ for all $j \in [1, \dots, l]$. Let n be a minimal element of A . Then Z_n is open in $\text{supp}(F)$. Indeed,

$$\begin{aligned} Z_n &= \text{supp}(F) \cap Z_n = \text{supp}(F) \cap \bigcap_k \{x; c_{n_k} \leq \langle x, \xi_k \rangle < c_{n_k+1}\} \\ &= \text{supp}(F) \cap \bigcap_k \{x; \langle x, \xi_k \rangle < c_{n_k+1}\}. \end{aligned}$$

Note that the last equality is true since otherwise there exists $n' < n$ in A such that $\text{supp}(F) \cap Z_{n'} \neq \emptyset$, and n would not be minimal. \square

Now we can complete the proof of Theorem 3.21.

Let us take $n \in A$ such that $Z_n \subset \text{supp}(F)$ is open in $\text{supp}(F)$. Then we have an exact sequence

$$0 \rightarrow \mathbf{k}_{Z_n} \otimes F(Z_n) \rightarrow F \rightarrow F'' \rightarrow 0$$

and $\text{supp } F'' \subset \text{supp}(F) \setminus Z_n$. Then the proof goes by induction on $\#A$. \square

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