THE CR KILLING OPERATOR AND BERNSTEIN–GELFAND–GELFAND CONSTRUCTION IN CR GEOMETRY

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ABSTRACT. We elaborate the tractor calculus for compatible almost CR structures (also known as strictly pseudoconvex partially integrable almost CR structures) on contact manifolds, and as an application, express the first BGG invariant differential operator D_0 explicitly in some cases, i.e., for some tractor connections. An interesting outcome is the fact that the "modified" adjoint tractor connection $\tilde{\nabla}$ governing infinitesimal deformations of parabolic geometries generates what we call the CR Killing operator as its first BGG operator, and actually, it does not agree with the first BGG operator of the normal (unmodified) adjoint tractor connection. The relationship between the CR Killing operator and analysis of ACHE (asymptotically complex hyperbolic Einstein) metrics, or more specifically the CR obstruction tensor, is also discussed.

1. INTRODUCTION

Theory of parabolic geometries, as partly summarized in the standard reference of Cap–Slovák [13], has proven to be a useful tool in studying certain kinds of differential-geometric structures. The fundamental idea of the theory is to single out one preferred Cartan connection among the ones admitted by the underlying geometric structure by introducing a normality condition described in the Lie-theoretic language, thereby constructing preferable linear connections of naturally defined vector bundles (called tractor bundles), which fit together well with Lie algebra homology/cohomology theory. In this article, we describe this approach in detail in the case of CR geometry, and in particular, how a specific linear differential operator D, which we suggest calling the CR Killing operator, can be put in its context.

As pointed out by Cap–Schichl [12] and perhaps also intended by earlier authors, the scope of the approach toward CR geometry from the theory of parabolic geometries is not limited to CR structures in the classical sense; the formal integrability condition can be relaxed. Stated in a more precise language, the category of normal regular parabolic geometries of type (G, P), where G = PSU(n + 1, 1) and P is its parabolic subgroup that consists of all the elements preserving some fixed null complex line in $\mathbb{C}^{n+1,1}$, is equivalent to the category of so-called strictly pseudoconvex partially integrable almost CR structures on contact manifolds, or compatible almost CR structures by the term coined in [30]. The subtleties about the CR Killing operator that we are going to discuss become visible only by taking those non-integrable CR structures into consideration.

We define the CR Killing operator

(1.1)
$$D: \operatorname{Re} \mathcal{E}(1,1) \to \operatorname{Re}(\mathcal{E}_{(\alpha\beta)}(1,1) \oplus \mathcal{E}_{(\overline{\alpha\beta})}(1,1))$$

on a contact manifold equipped with a compatible almost CR structure by

(1.2)
$$Df = (i\nabla_{(\alpha}\nabla_{\beta)}f - A_{\alpha\beta}f - iN_{(\alpha\beta)\gamma}\nabla^{\gamma}f, -i\nabla_{(\overline{\alpha}}\nabla_{\overline{\beta})}f - A_{\overline{\alpha}\overline{\beta}}f + iN_{(\overline{\alpha}\overline{\beta})\overline{\gamma}}\nabla^{\gamma}f)$$

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in terms of any Tanaka–Webster connection, where the necessary notation to interpret (1.1) and (1.2) is recalled in the next section. One can verify that the operator given by (1.2) does not depend on a particular choice of the Tanaka–Webster connection (i.e., a choice of a contact form), or in other words, that it is determined purely by the compatible almost CR structure. In fact, as we will see in Section 3, this operator has a CR-geometric meaning: it describes trivial infinitesimal deformations of compatible almost CR structures induced by contact Hamiltonian vector fields.

As already mentioned, one major purpose of this article is to illustrate that the operator (1.2) also pops up from the theory of parabolic geometries. It is actually what is called the first BGG (Bernstein–Gelfand–Gelfand) operator associated with the "modified" adjoint tractor connection introduced by Čap in [9].

Theorem 1.1. The first BGG operator $D_0^{\tilde{\nabla}}$ of the modified adjoint tractor connection $\tilde{\nabla}$ equals the CR Killing operator D.

Actually, it is also very important to note that, for general non-integrable compatible almost CR structures, the "unmodified" normal adjoint tractor connection ∇ does not play the same role; using the modified connection $\tilde{\nabla}$ is really necessary. The author believes that this observation gives some insight toward the idea of "holographic" reconstruction of normal parabolic geometries associated with compatible almost CR structures on the conformal infinity of ACHE (asymptotically complex hyperbolic Einstein) spaces.

In order to compute the first BGG operators D_0^{∇} and $D_0^{\overline{\nabla}}$ and to show that the latter agrees with D, we derive the formulae of ∇ and $\overline{\nabla}$ relative to an arbitrarily chosen exact Weyl structure (which is equivalent to a contact form; see Section 6.3). The derivation is given starting mostly from scratch. The necessary general background is summarized in Section 4, which contains an account of the correspondence of normal regular parabolic geometries and underlying infinitesimal flag structures and a sketch of the theory of tractor connections and BGG operators. Section 5 is devoted to Lie algebra homology computations that we need to specify the normality condition of the CR Cartan connection and also to invoke the BGG construction later. In Section 6, we first recall the general notion of Weyl structures and Weyl forms and how they are used to describe tractor connections. They are followed by a description of frame bundles associated with CR geometry, and in the latter part of this section, the determination of CR normal Weyl forms is given. Finally, in Section 7, we obtain the promised formulae of the adjoint tractor connections and their associated first BGG operators. Here we also discuss the case of the standard tractor connection; for this purpose, in Section 6, we also consider the frame bundle corresponding to the group $G^{\sharp} = SU(n + 1, 1)$, which is an (n + 2)-sheeted covering of G = PSU(n + 1, 1).

In the literature, CR tractor bundles over integrable CR structures have been discussed in several ways. The most explicit, hands-on approach is taken in a work of Gover–Graham [20], which gives the formula of the standard (co)tractor connection relative to exact Weyl structures and actually uses it as the definition of the connection, without referencing to normal Cartan connections or normal Weyl forms. Another description of standard tractors using the ambient metric construction of Fefferman [19] is sketched by Čap [7]; an analogous theory in the case of conformal geometry is detailed in a work of Čap–Gover [10]. Yet another, closely related approach via Fefferman's conformal circle bundle over CR manifolds ([19], see also Lee [26]) is also mentioned in [7] and extensively used by Čap–Gover [11]. Herzlich [24] gives a realization of the standard tractor bundle as the bundle of 1-jets of CR-holomorphic sections of a certain complex line bundle, which resembles the work of Bailey–Eastwood–Gover [2] in conformal geometry.

However, tractor bundles over non-integrable compatible almost CR structures have not been investigated well, which are, as our observation reveals, also worthy of attention. Note also that, in the terminology of the general theory of parabolic geometries, integrable CR structures comprise the subclass of torsion-free geometries of the class of |2|-graded geometries corresponding to compatible almost CR structures. The investigation given in this paper might serve as important working example in the general theory, especially regarding the role played by the torsion of parabolic geometries.

In addition to this, we also believe that this article fixes a lack of detailed references in the integrable case on how the CR standard tractor connection of Gover–Graham [20] can be reconstructed based on the general theory of parabolic geometries.

To conclude the introduction, we briefly discuss possible relationships between CR tractor bundles and other constructions for compatible almost CR structures. For integrable CR structures, the standard tractor bundle can be recovered by the ambient metric construction as we already mentioned; by contrast, there is no plausible notion of the ambient metric for general compatible almost CR structures. But here we want to recall the related notion of complete Kähler-Einstein spaces in the integrable case, whose boundaries at infinity ("conformal infinity") carry integrable CR structures and the total spaces of whose canonical bundle, with zero section removed, carry the ambient metrics (see [19] or an article of Fefferman–Graham [17]). These complete Kähler-Einstein spaces generalize to ACHE spaces of Biquard [3], whose conformal infinities are equipped with compatible almost CR structures. Consequently, a natural hope may be that ACHE spaces can be used to recover the standard tractor bundles associated with compatible almost CR structures.

Our observation in this paper sheds a doubt over this naïve idea. ACHE spaces have some indirect relationship with the CR Killing operator via the CR obstruction tensor introduced by the author [28] as we recall in Section 3, and so there should be some nice way to reconstruct the CR Killing operator using ACHE metrics. But as we will see, the CR Killing operator is related to the modified adjoint tractor connection $\tilde{\nabla}$, which has little to do with the standard tractor bundle. Therefore, a more natural expectation might be as this: there is a way to reconstruct the adjoint tractor bundle $\mathcal{A}M$ of compatible almost CR structures J from ACHE spaces, and when J is integrable, the realization of $\mathcal{A}M$ as a subbundle of End(\mathcal{V}) via the standard tractor bundle \mathcal{V} (see Section 7.2) can be seen as its specialization. The author wants to come back to such a holographic reconstruction of $\mathcal{A}M$ using ACHE spaces in the future. In fact, another article [30] by the author is also an attempt toward this idea.

2. Preliminaries

We summarize basic matters in pseudohermitian geometry of compatible almost CR structures by largely following [28, Section 3], supplementing them with some new formulae and minor notational modifications.

2.1. **Basic definitions.** Throughout this article, we assume that we are given a contact manifold (M, H) of dimension 2n + 1 that is cooriented, i.e., associated with a fixed orientation of the line bundle H^{\perp} of 1-forms annihilating H. By a *contact form* we mean a nowhere-vanishing section of the bundle H^{\perp} that is positive with respect to the given orientation; hence any two contact forms are related as $\hat{\theta} = e^u \theta$, where $u \in C^{\infty}(M)$. Any choice of θ determines the direct sum decomposition

$$(2.1) TM = H \oplus \mathbb{R}T,$$

where T, the Reeb vector field, is characterized by $\theta(T) = 1$ and $T \sqcup d\theta = 0$.

Let J be an almost CR structure on a contact manifold (M, H), by which we mean that J is a complex structure of H. The *compatibility* of the almost CR structure J, which we always assume, means that

(2.2)
$$h(X,Y) = d\theta(X,JY), \qquad X, Y \in H$$

is a positive-definite Hermitian form on H, called the *Levi form*^{*}. The compatibility condition is irrelevant to the choice of θ because $\hat{\theta} = e^u \theta$ implies $d\hat{\theta}(X, JY) = e^u d\theta(X, JY)$. We sometimes call (H, J), instead of J, a compatible almost CR structure.

Remark 2.1. It is well known that the formal integrability condition of J implies that (2.2) is a Hermitian form. Then the nondegeneracy of (2.2) is automatic because of the contact condition, and the positive-definiteness is referred to as *strict pseudoconvexity*. Therefore, the notion of compatible almost CR structures is a generalization of that of strictly pseudoconvex (integrable) CR structures. The point of this Section 2 is that pseudohermitian geometry does not change much in the broader class. Our "compatible almost CR structures" have been more often called "strictly pseudoconvex partially integrable almost CR structures" (e.g., in Čap–Schichl [12]) in view of the fact that (2.2) being a Hermitian form is equivalent to a weaker formal integrability. We also note that a compatible almost CR structure (H, J) together with a fixed contact form θ is equivalent to a *contact metric structure* in the sense of Blair [5].

A compatible almost CR structure (H, J) naturally comes with the decomposition

of the complexification of H into the $(\pm i)$ -eigenspaces of J (the compatibility of J is actually irrelevant here). In actual computations, we often need to take a local frame $\{Z_{\alpha}\}$ of $H^{1,0}$. By doing so, at the same time, we obtain a local frame $\{Z_{\overline{\alpha}}\}$ of $H^{0,1}$, which is the complex conjugate of $\{Z_{\alpha}\}$.

When θ is moreover fixed, we have the *admissible coframe* $\{\theta^{\alpha}\}$ associated with any fixed local frame $\{Z_{\alpha}\}$, which is the set of complex 1-forms satisfying $\theta^{\alpha}(Z_{\beta}) = \delta_{\beta}^{\alpha}$ and $\theta^{\alpha}(Z_{\overline{\beta}}) = \theta^{\alpha}(T) = 0$. Its complex conjugate is denoted by $\{\theta^{\overline{\alpha}}\}$. Then (2.2) and $T \sqcup d\theta = 0$ imply that

(2.4)
$$d\theta = ih_{\alpha\overline{\beta}}\theta^{\alpha} \wedge \theta^{\overline{\beta}},$$

where $h_{\alpha\overline{\beta}} = h(Z_{\alpha}, Z_{\overline{\beta}})$ is pointwisely a positive-definite Hermitian matrix.

A section of $H^{1,0}$ can be expressed locally by symbols with an index upstairs (e.g., v^{α}) in terms of any fixed local frame $\{Z_{\alpha}\}$. For this reason, the bundle $H^{1,0}$ itself is denoted by \mathcal{E}^{α} in the sequel, where α is an "abstract index." In general, any tensor bundle (i.e., a tensor product of $H^{1,0}$, $H^{0,1}$, $(H^{1,0})^*$, $(H^{1,0})^*$ and its geometrically natural subbundle) will be denoted by \mathcal{E} associated with the same indices used for expressing their sections locally, and if applicable, some additional symbols representing a particular type of subbundles. For example, the Levi form $h_{\alpha\overline{\beta}}$ is a section of $\mathcal{E}_{\alpha\overline{\beta}} = (H^{1,0})^* \otimes (H^{1,0})^*$ (actually $h_{\alpha\overline{\beta}}$ has the Hermitian symmetry and so is a section of the Hermitian symmetric part of $\mathcal{E}_{\alpha\overline{\beta}}$, which has no commonly accepted notation). The Tanaka–Webster torsion tensor $A_{\alpha\beta}$ (defined in Section 2.3) is a section of $\mathcal{E}_{\alpha\beta} = (H^{1,0})^* \otimes (H^{1,0})^*$, and since $A_{\alpha\beta} = A_{\beta\alpha}$, it is further said that it is a section of $\mathcal{E}_{(\alpha\beta)}$, where (\cdots) denotes the symmetrization with respect to the enclosed indices. Likewise, $[\cdots]$

^{*}We assume for brevity that the Levi form h is positive definite, but everything in this article can be immediately generalized to the case in which h has arbitrary (nondegenerate) signature as well.

denotes the skew-symmetrization. Note also that the symmetry property $A_{\alpha\beta} = A_{\beta\alpha}$ can also be expressed as $A_{\alpha\beta} = A_{(\alpha\beta)}$.

Furthermore, we observe the well-accepted custom in the field that the space of (possibly local) sections, or the sheaf of germs of local sections, of a tensor bundle is denoted by the same symbol assigned to the tensor bundle itself. The distinction will be clearly made by context.

Next, we introduce the *density bundles* $\mathcal{E}(w, w')$, where w and w' are integers^{*}. The *canonical bundle* \mathcal{K} over (M, H, J) is the complex line bundle $\bigwedge^{n+1}(H^{0,1})^{\perp}$; \mathcal{K} is generated by $\theta \wedge \theta^1 \wedge \cdots \wedge \theta^n$ for any choice of θ and an admissible coframe $\{\theta^{\alpha}\}$. Working locally if necessary, we fix an (n+2)-nd root of \mathcal{K} and write its dual $\mathcal{E}(1,0)$. Then we define

$$\mathcal{E}(w, w') = (\mathcal{E}(1, 0))^{\otimes w} \otimes (\overline{\mathcal{E}(1, 0)})^{\otimes w'}, \qquad w, w' \in \mathbb{Z}$$

and its sections are called (w, w')-densities. Moreover, we write $\mathcal{E}_{\alpha\overline{\beta}}{}^{\sigma\overline{\tau}}(w, w') = \mathcal{E}_{\alpha\overline{\beta}}{}^{\sigma\overline{\tau}} \otimes \mathcal{E}(w, w')$, etc., and sections of such bundles are referred to as weighted tensors.

Particularly important density bundles are those of the form $\mathcal{E}(w, w)$, for they are independent of the choice of $\mathcal{E}(1,0)$, and as a consequence, globally defined. In other words, although tensors weighted by general $\mathcal{E}(w, w')$ should be considered as an object defined on $(M, H, J, \mathcal{E}(1,0))$, those weighted by $\mathcal{E}(w, w)$ can be understood as an object on (M, H, J). Some readers may feel comfortable by regarding tensors weighted by $\mathcal{E}(w, w')$, $w \neq w'$, as intermediate objects and those weighted by $\mathcal{E}(w, w)$ as "actual" objects.

Any choice of a contact form θ determines a trivialization of $\mathcal{E}(w, w)$ uniquely. To see this, let $\zeta = \theta \wedge \theta^1 \wedge \cdots \wedge \theta^n$ be a section of $\mathcal{K} = \mathcal{E}(-n-2,0)$, where $\{\theta^{\alpha}\}$ is some unitary admissible coframe with respect to the Levi form h, possibly only locally defined. Then ζ is pointwisely well-defined up to phase (and it is volume-normalized with respect to θ in the sense of Lee [26, Section 3]). If ξ is a section of $\mathcal{E}(1,0)$ satisfying $\xi^{-n-2} = \zeta$, then $|\xi|^{2w}$ is a globally defined section of $\mathcal{E}(w,w)$ that depends only on θ . The mentioned trivialization of $\mathcal{E}(w,w)$ can be given by $|\xi|^{2w}$.

Remark 2.2. For any change $\hat{\theta} = e^u \theta$ of contact forms, the (w, w)-density $|\xi|^{2w}$ scales as $|\hat{\xi}|^{2w} = e^{-wu} |\xi|^{2w}$. Therefore, if f and \hat{f} are the trivializations of the same (w, w)-density with respect to θ and $\hat{\theta}$, respectively, then $\hat{f} = e^{wu} f$. An intuitive understanding of $\mathcal{E}(w, w)$ is that it is the bundle of scalar-valued quantities that rescales like $\hat{f} = e^{wu} f$ for the change $\hat{\theta} = e^u \theta$.

We have $|\hat{\xi}|^2 = e^{-u} |\xi|^2$ in particular. Consequently, the weighted contact form

$$\boldsymbol{ heta} = heta \otimes |\xi|^2$$

is independent of θ , which also implies that there is a canonical identification $H^{\perp} \cong \mathcal{E}(-1, -1)$. The weighted Levi form

$$\boldsymbol{h}_{\alpha\overline{\beta}} = h_{\alpha\overline{\beta}} \otimes |\boldsymbol{\xi}|^2 \in \mathcal{E}_{\alpha\overline{\beta}}(1,1)$$

and its inverse

$$\boldsymbol{h}^{\alpha\overline{\beta}} = h^{\alpha\overline{\beta}} \otimes |\xi|^{-2} \in \mathcal{E}^{\alpha\overline{\beta}}(-1,-1)$$

are also independent of θ .

Notation 2.3. Whenever some fixed θ is taken, possibly implicitly, for any tensor weighted by $\mathcal{E}(w, w)$, we use the same symbol to express itself and its trivialization with respect to θ (in order to reduce the use of boldface letters). The distinction is made by context.

^{*}The definition of $\mathcal{E}(w, w')$ can immediately be generalized to $w, w' \in \mathbb{C}$ satisfying $w - w' \in \mathbb{Z}$, which we do not need. See Gover–Graham [20, p. 4].

Based on the above notational convention, we could have used the symbol $h_{\alpha\overline{\beta}}$ for the weighted Levi form instead of $h_{\alpha\overline{\beta}}$ (and keep the unweighted one denoted by $h_{\alpha\overline{\beta}}$ as well), and even could have used θ for the weighted contact form. We try to take this way from now on as much as possible.

2.2. The Nijenhuis tensor. The non-integrability of a compatible almost CR structure J is measured by the Nijenhuis tensor N, which is a section of $\mathcal{E}_{[\alpha\beta]}^{\overline{\gamma}}$, defined by*

$$[Z_{\alpha}, Z_{\beta}] = -N^{\overline{\gamma}}_{\alpha\beta} Z_{\overline{\gamma}} \mod H^{1,0}$$

or equivalently,

(2.5)
$$d\theta^{\overline{\gamma}} = \frac{1}{2} N^{\overline{\gamma}}_{\alpha\beta} \theta^{\alpha} \wedge \theta^{\beta} \mod \theta^{\overline{\alpha}}, \theta, \qquad N^{\overline{\gamma}}_{(\alpha\beta)} = 0.$$

Moreover, N can be understood as a real tensor by setting

$$N^{\gamma}_{\ \overline{\alpha}\overline{\beta}} = \overline{N^{\overline{\gamma}}_{\ \alpha\beta}},$$

the practice we repeatedly apply to various tensors in the sequel, sometimes without mentioning. The index upstairs of $N^{\overline{\gamma}}_{\alpha\beta}$ can be lowered using the weighted Levi form as

(2.6)
$$N_{\gamma\alpha\beta} = h_{\gamma\overline{\sigma}} N^{\overline{\sigma}}_{\ \alpha\beta}$$

Therefore, $N_{\gamma\alpha\beta}$ is a section of $\mathcal{E}_{\gamma[\alpha\beta]}(1,1)$. Given a fixed contact form θ , $h_{\gamma\overline{\sigma}}$ on the right-hand side can also be understood as the unweighted Levi form, $N_{\gamma\alpha\beta}$ on the left as the trivialization of its weighted version, and (2.6) is justified as an equality between sections of $\mathcal{E}_{\gamma[\alpha\beta]}$ as well.

It can be shown that the index-lowered Nijenhuis tensor $N_{\gamma\alpha\beta}$ has a symmetry, in addition to the obvious $N_{\gamma(\alpha\beta)} = 0$, that

(2.7)
$$N_{\alpha\beta\gamma} + N_{\beta\gamma\alpha} + N_{\gamma\alpha\beta} = 0,$$

by differentiating (2.4) and using (2.5).

For convenience, we write

$$N_{\alpha\beta\gamma}^{\mathrm{sym}} = N_{(\alpha\beta)\gamma}, \qquad N_{\alpha\beta\gamma}^{\mathrm{skew}} = N_{[\alpha\beta]\gamma}.$$

Note that (2.7) implies

$$N_{\alpha\beta\gamma}^{\rm skew} = \frac{1}{2}(N_{\alpha\beta\gamma} - N_{\beta\alpha\gamma}) = -\frac{1}{2}N_{\gamma\alpha\beta}.$$

Moreover, if we define $|N|^2 = N_{\alpha\beta\gamma}N^{\alpha\beta\gamma}$ and $|N^{\text{sym}}|^2$, $|N^{\text{skew}}|^2$ in a similar manner, then we have

(2.8)
$$|N^{\text{skew}}|^2 = \frac{1}{4}|N|^2, \qquad |N^{\text{sym}}|^2 = |N|^2 - |N^{\text{skew}}|^2 = \frac{3}{4}|N|^2.$$

Furthermore, when θ is fixed, we write

$$(\nabla^* N)^{\text{sym}}_{\alpha\beta} = -\nabla^{\gamma} N_{(\alpha\beta)\gamma}, \qquad (\nabla^* N)^{\text{skew}}_{\alpha\beta} = -\nabla^{\gamma} N_{[\alpha\beta]\gamma}$$

using the Tanaka–Webster connection ∇ defined in the next subsection.

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^{*}We use a different convention on the sign and the order of the indices compared to [28, p. 2137].

2.3. The Tanaka–Webster connection. The Tanaka–Webster connection of a manifold M with a compatible almost CR structure (H, J) associated with a choice of a contact form θ is the connection of TM characterized by the fact that it preserves the splitting (2.1), makes T, J, h parallel, and satisfies some torsion condition (see [28, Proposition 3.1] for the detailed characterization). Note that the connection also preserves the complex splitting (2.3) because J is parallel. Therefore, upon fixing a local frame $\{Z_{\alpha}\}$ of $H^{1,0}$, the Tanaka–Webster connection ∇ is described by the connection forms $\omega_{\alpha}{}^{\beta}$ and their complex conjugates $\omega_{\overline{\alpha}}{}^{\overline{\beta}}$. Since $\nabla h = 0$ (where h is the unweighted Levi form), we have

(2.9)
$$\omega_{\alpha\overline{\beta}} + \omega_{\overline{\beta}\alpha} = dh_{\alpha\overline{\beta}}.$$

The torsion condition for ∇ implies that

(2.10)
$$d\theta^{\gamma} = \theta^{\alpha} \wedge \omega_{\alpha}^{\ \gamma} + A_{\overline{\alpha}}^{\ \gamma} \theta \wedge \theta^{\overline{\alpha}} + \frac{1}{2} N_{\overline{\alpha}\overline{\beta}}^{\gamma} \theta^{\overline{\alpha}} \wedge \theta^{\overline{\beta}}$$

holds for some uniquely determined tensor $A_{\overline{\alpha}}^{\gamma} \in \mathcal{E}_{\overline{\alpha}}^{\gamma}(-1,-1)$, which is called the *Tanaka–Webster torsion tensor*. It is known that $A_{\alpha\beta} = A_{\beta\alpha}$.

The Tanaka–Webster connection induces a connection of the canonical bundle \mathcal{K} , and hence that of $\mathcal{E}(w, w')$, all of which are denoted by ∇ . Let $\zeta = \theta \wedge \theta^1 \wedge \cdots \wedge \theta^n$ be a section of \mathcal{K} , where $\{\theta^{\alpha}\}$ is some unitary admissible coframe with respect to θ . Then we have $\nabla \zeta = -\omega_{\gamma}^{\gamma} \otimes \zeta$. Consequently, if ξ is a section of $\mathcal{E}(1,0)$ satisfying $\xi^{-n-2} = \zeta$, then considering (2.9) we obtain

(2.11)
$$\nabla(\xi^w \otimes \overline{\xi}^{w'}) = \frac{w - w'}{n+2} \omega_{\gamma}^{\gamma} \otimes (\xi^w \otimes \overline{\xi}^{w'}).$$

In particular, $|\xi|^{2w} = \xi^w \otimes \overline{\xi}^w$ is a parallel section of $\mathcal{E}(w, w)$, and hence the trivialization of weighted tensors using $|\xi|^{2w}$ is compatible with covariant differentiation. As a result, the weighted contact form and the weighted Levi form are also parallel.

We express the curvature form $\Pi_{\alpha}{}^{\beta} = d\omega_{\alpha}{}^{\beta} - \omega_{\alpha}{}^{\gamma} \wedge \omega_{\gamma}{}^{\beta}$ as

$$(2.12) \quad \Pi_{\alpha}{}^{\beta} = R_{\alpha}{}^{\beta}{}_{\sigma\overline{\tau}}\theta^{\sigma} \wedge \theta^{\overline{\tau}} + W_{\alpha}{}^{\beta}{}_{\gamma}\theta^{\gamma} \wedge \theta + W_{\alpha}{}^{\beta}{}_{\overline{\gamma}}\theta^{\overline{\gamma}} \wedge \theta + \frac{1}{2}V_{\alpha}{}^{\beta}{}_{\sigma\tau} \theta^{\sigma} \wedge \theta^{\tau} + \frac{1}{2}V_{\alpha}{}^{\beta}{}_{\overline{\sigma\tau}} \theta^{\overline{\sigma}} \wedge \theta^{\overline{\tau}},$$

where $V_{\alpha \ (\sigma\tau)}^{\ \beta} = V_{\alpha \ (\overline{\sigma\tau})}^{\ \beta} = 0$. Among the components on the right-hand side, $R_{\alpha \ \sigma\overline{\tau}}^{\ \beta}$ is called the *Tanaka–Webster curvature tensor*, and it satisfies

$$(2.13) R_{\alpha\overline{\beta}\sigma\overline{\tau}} = R_{\overline{\beta}\alpha\overline{\tau}\sigma}, R_{\alpha\ \sigma\overline{\tau}}^{\ \beta} - R_{\sigma\ \alpha\overline{\tau}}^{\ \beta} = -N_{\alpha\sigma}^{\overline{\gamma}}N_{\sigma\overline{\tau}\gamma}^{\beta}.$$

The other components are given in terms of N and A as follows^{*}:

Moreover, we define

$$R_{\alpha\overline{\beta}} = R_{\gamma\ \alpha\overline{\beta}}^{\ \gamma}, \qquad R_{\alpha\overline{\beta}}' = R_{\alpha\overline{\beta}\gamma}^{\ \gamma}, \qquad R_{\alpha\overline{\beta}}'' = R_{\alpha\ \gamma\overline{\beta}}^{\ \gamma}$$

and

$$R = R_{\gamma}^{\gamma}, \qquad R' = R'_{\gamma}^{\gamma} (= R), \qquad R'' = R''_{\gamma}^{\gamma}.$$

Then it follows from (2.13) that

(2.14)
$$R'_{\alpha\overline{\beta}} = R_{\alpha\overline{\beta}} + 2N_{(\alpha\lambda)\mu}N^{\mu\lambda}_{\overline{\beta}}, \qquad R''_{\alpha\overline{\beta}} = R_{\alpha\overline{\beta}} - N_{\lambda\mu\alpha}N^{\mu\lambda}_{\overline{\beta}}$$

^{*}Two vertical bars within (\cdots) (resp. $[\cdots]$) indicate that the indices between them are excluded from the symmetrization (resp. the skew-symmetrization).

and

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$$R'' = R - N_{\lambda\mu\nu}N^{\mu\lambda\nu} = R - |N^{\text{sym}}|^2 + |N^{\text{skew}}|^2 = R - \frac{1}{2}|N|^2$$

by (2.8). Note also that $R_{\alpha\overline{\beta}} = R_{\overline{\beta}\alpha}$, $R'_{\alpha\overline{\beta}} = R'_{\overline{\beta}\alpha}$ immediately follow from the definitions and $R''_{\alpha\overline{\beta}} = R''_{\overline{\beta}\alpha}$ holds because of the second equality in (2.14).

As in Gover–Graham [20, p. 6], we define the CR Schouten tensor $P_{\alpha\overline{\beta}}$ by

$$P_{\alpha\overline{\beta}} = \frac{1}{n+2} \left(R_{\alpha\overline{\beta}} - \frac{1}{2(n+1)} Rh_{\alpha\overline{\beta}} \right),$$

and $P'_{\alpha\overline{\beta}}$ (resp. $P''_{\alpha\overline{\beta}}$) will denote the similarly defined quantity with $R_{\alpha\overline{\beta}}$ replaced with $R'_{\alpha\overline{\beta}}$ (resp. $R''_{\alpha\overline{\beta}}$) and R replaced with R' (resp. R'') (but note that R' = R). Then (2.14) implies

$$\begin{split} P'_{\alpha\overline{\beta}} &= P_{\alpha\overline{\beta}} + \frac{2}{n+2} N_{(\alpha\lambda)\mu} N^{\mu\lambda}{}_{\overline{\beta}}, \\ P''_{\alpha\overline{\beta}} &= P_{\alpha\overline{\beta}} - \frac{1}{n+2} N_{\lambda\mu\alpha} N^{\mu\lambda}{}_{\overline{\beta}} + \frac{1}{4(n+1)(n+2)} |N|^2 h_{\alpha\overline{\beta}}. \end{split}$$

We define $P = P_{\gamma}^{\gamma}$, $P' = P'_{\gamma}^{\gamma}$, and $P'' = P''_{\gamma}^{\gamma}$, which are related by

(2.15)
$$P' = P, \qquad P'' = P - \frac{1}{4(n+1)} |N|^2.$$

We will later need the following transformation law, taken from [28, Proposition 3.6], for changes of contact forms.

Proposition 2.4. Let θ and $\hat{\theta} = e^u \theta$ be two contact forms, where $u \in C^{\infty}(M)$. Then, for any local frame $\{Z_{\alpha}\}$ and the dual admissible coframe $\{\theta^{\alpha}\}$ with respect to θ , the Tanaka–Webster connection forms $\hat{\omega}_{\alpha}^{\ \beta}$ for $\hat{\theta}$ with respect to $\{Z_{\alpha}\}$ are expressed in terms of those for θ by

$$\hat{\omega}_{\alpha}{}^{\beta} = \omega_{\alpha}{}^{\beta} + (u_{\alpha}\theta^{\beta} - u^{\beta}\theta_{\alpha}) + \delta_{\alpha}{}^{\beta}u_{\gamma}\theta^{\gamma} + i(u^{\beta}{}_{\alpha} + u_{\alpha}u^{\beta} + \delta_{\alpha}{}^{\beta}u_{\gamma}u^{\gamma})\theta,$$

where the indices following u denotes the Tanaka–Webster covariant differentiation with respect to θ . Moreover,

$$\begin{split} \hat{A}_{\alpha\beta} &= A_{\alpha\beta} + i u_{(\alpha\beta)} - i u_{\alpha} u_{\beta} + i N_{(\alpha\beta)\gamma} u^{\gamma}, \\ \hat{P}_{\alpha\overline{\beta}} &= P_{\alpha\overline{\beta}} - \frac{1}{2} (u_{\alpha\overline{\beta}} + u_{\overline{\beta}\alpha}) - \frac{1}{2} u_{\gamma} u^{\gamma} h_{\alpha\overline{\beta}}, \end{split}$$

where the unhatted (resp. hatted) quantities are associated with θ (resp. $\hat{\theta}$).

It follows from (2.10), (2.11), and (2.12) that commutation of covariant derivatives on densities is given as follows, generalizing Gover–Graham [20, Proposition 2.2].

Proposition 2.5. For $f \in \mathcal{E}(w, w')$,

$$\begin{split} \nabla_{\alpha}\nabla_{\overline{\beta}}f - \nabla_{\overline{\beta}}\nabla_{\alpha}f &= -ih_{\alpha\overline{\beta}}\nabla_{0}f + \frac{w - w'}{n + 2}R_{\alpha\overline{\beta}}f, \\ \nabla_{\alpha}\nabla_{\beta}f - \nabla_{\beta}\nabla_{\alpha}f &= -N^{\overline{\gamma}}_{\alpha\beta}\nabla_{\overline{\gamma}}f + \frac{w - w'}{n + 2} \cdot 2V_{\gamma} \stackrel{\gamma}{}_{\alpha\beta}f = -N^{\overline{\gamma}}_{\alpha\beta}\nabla_{\overline{\gamma}}f - \frac{w - w'}{n + 2}(\nabla^{\gamma}N_{\gamma\alpha\beta})f, \\ \nabla_{\alpha}\nabla_{0}f - \nabla_{0}\nabla_{\alpha}f &= A_{\alpha}^{\overline{\gamma}}\nabla_{\overline{\gamma}}f + \frac{w - w'}{n + 2}W_{\gamma} \stackrel{\gamma}{}_{\alpha}f = A_{\alpha}^{\overline{\gamma}}\nabla_{\overline{\gamma}}f + \frac{w - w'}{n + 2}(\nabla^{\gamma}A_{\alpha\gamma} - N_{\lambda\mu\alpha}A^{\lambda\mu})f, \end{split}$$

where ∇_0 is the θ -component of the covariant derivative.

The following transformation law of the connection on densities is given by the same formulae as [20, Proposition 2.3].

Proposition 2.6. Let θ and $\hat{\theta} = e^u \theta$ be two contact forms. Then, for $f \in \mathcal{E}(w, w')$,

$$\hat{\nabla}_{\alpha}f = \nabla_{\alpha}f + wu_{\alpha}f,$$
$$\hat{\nabla}_{\overline{\alpha}}f = \nabla_{\overline{\alpha}}f + w'u_{\overline{\alpha}}f$$

$$\hat{\nabla}_0 f = \nabla_0 f - i u^{\gamma} \nabla_{\gamma} f + i u^{\overline{\gamma}} \nabla_{\overline{\gamma}} f + \frac{1}{n+2} ((w+w')u_0 + i w u^{\gamma}{}_{\gamma} - i w' u_{\gamma}{}^{\gamma} - i (w-w')u_{\gamma} u^{\gamma}) f,$$

where the last equality should be understood as an identity in $\mathcal{E}(w-1, w'-1)$. If \mathbf{T} and $\hat{\mathbf{T}}$ denote the weighted Reeb vector field for θ and for $\hat{\theta}$, respectively, then $\nabla_0 f$ in the right-hand side (resp. $\hat{\nabla}_0 f$ in the left-hand side) means $\nabla_{\mathbf{T}} f$ (resp. $\hat{\nabla}_{\hat{\mathbf{T}}} f$).

Proof. We prove the case (w, w') = (-n-2, 0), i.e., the case of the canonical bundle \mathcal{K} ; then the general case follows immediately. It suffices to consider $\nabla \zeta$ and $\hat{\nabla} \zeta$ for some nowhere-vanishing local section ζ of \mathcal{K} . Moreover, without loss of generality, we can use a unitary local frame $\{Z_{\alpha}\}$ with respect to θ to show the formulae. So we let $\zeta = \theta \wedge \theta^1 \wedge \cdots \wedge \theta^n$ by using the dual admissible coframe of such a unitary frame $\{Z_{\alpha}\}$, and let $\omega_{\alpha}{}^{\beta}$ and $\hat{\omega}_{\alpha}{}^{\beta}$ be as in Proposition 2.4. Then we already know that

$$\nabla \zeta = -\omega_{\gamma}^{\gamma} \otimes \zeta.$$

On the other hand, we can take $\{e^{-u/2}Z_{\alpha}\}$ as a unitary frame with respect to $\hat{\theta}$. The associated admissible coframe $\{\tilde{\theta}^{\alpha}\}$ with respect to $\hat{\theta}$ is given by $\tilde{\theta}^{\alpha} = e^{u/2}\hat{\theta}^{\alpha} \equiv e^{u/2}\theta^{\alpha} \mod \theta$, and hence $\hat{\zeta} = \hat{\theta} \wedge \tilde{\theta}^{1} \wedge \cdots \wedge \tilde{\theta}^{n}$, which equals $e^{(1+n/2)u}\zeta$, satisfies

$$\hat{\nabla}\hat{\zeta} = -\tilde{\omega}_{\gamma}{}^{\gamma}\otimes\hat{\zeta}, \quad \text{which implies} \quad \hat{\nabla}\zeta = -\tilde{\omega}_{\gamma}{}^{\gamma}\otimes\zeta - \left(1+\frac{n}{2}\right)du\otimes\zeta$$

where $\tilde{\omega}_{\alpha}{}^{\beta}$ is the connection forms of $\hat{\nabla}$ with respect to $\{e^{-u/2}Z_{\alpha}\}$. Since $\tilde{\omega}_{\alpha}{}^{\beta}$ and $\hat{\omega}_{\alpha}{}^{\beta}$ are related by $\tilde{\omega}_{\alpha}{}^{\beta} = \hat{\omega}_{\alpha}{}^{\beta} - (1/2)\delta_{\alpha}{}^{\beta}du$, we conclude that

$$\hat{\nabla}\zeta = -\hat{\omega}_{\gamma}{}^{\gamma}\otimes\zeta - du\otimes\zeta.$$

Then it follows from Proposition 2.4 that

$$\hat{\nabla}\zeta = \nabla\zeta - \left((n+2)u_{\gamma}\theta^{\gamma} + (u_0 + iu^{\gamma}{}_{\gamma} + i(n+1)u_{\gamma}u^{\gamma})\theta\right) \otimes \zeta_{\gamma}$$

which implies the formulae to be shown in view of the fact that $\hat{T} = T - iu^{\gamma} Z_{\gamma} + iu^{\overline{\gamma}} Z_{\overline{\gamma}}$.

3. The CR Killing operator

The formula (1.2) of the CR Killing operator D now makes sense thanks to various definitions introduced in Section 2. It can be checked by using Propositions 2.4 and 2.6 that the right-hand side of (1.2) is independent of the choice of a contact form θ . Moreover we want to note that, in view of Proposition 2.5, D can also be expressed as

$$(3.1) Df = (i\nabla_{\alpha}\nabla_{\beta}f - A_{\alpha\beta}f - iN_{\beta\alpha\gamma}\nabla^{\gamma}f, -i\nabla_{\overline{\alpha}}\nabla_{\overline{\beta}}f - A_{\overline{\alpha}\overline{\beta}}f + iN_{\overline{\beta}\overline{\alpha}\overline{\gamma}}\nabla^{\overline{\gamma}}f).$$

For integrable CR structures (i.e., if N = 0), the operator D reduces to

$$Df = (i\nabla_{(\alpha}\nabla_{\beta)}f - A_{\alpha\beta}f, -i\nabla_{(\overline{\alpha}}\nabla_{\overline{\beta})}f - A_{\overline{\alpha}\overline{\beta}}f).$$

This operator essentially appears in the literature. The "new" CR differential complex of Akahori–Garfield–Lee [1] contains the mapping $f \mapsto \nabla_{(\overline{\alpha}} \nabla_{\overline{\beta})} f - iA_{\overline{\alpha}\overline{\beta}} f$ (acting on complex-valued functions) as the first operator, and it is known that it describes the infinitesimal action

of Kuranishi's "wiggle," i.e., internal moves of embedded CR manifolds within a complex manifold. The same operator is revisited in Hirachi–Marugame–Matsumoto [25] from the viewpoint of Fefferman's ambient metric construction.

In this section, we first give the derivation of the CR Killing operator D as what describes trivial infinitesimal changes of compatible almost CR structures caused by contact Hamiltonian vector fields. Then we discuss the fact that D also appears in the context of asymptotic expansion of ACHE metrics (asymptotically complex hyperbolic Einstein metrics) and the CR obstruction tensor, whose basic theory is developed in the author's previous papers [28,29].

3.1. Trivial infinitesimal deformations. Let $f \in \operatorname{Re} \mathcal{E}(1,1)$. Given a fixed contact form θ , f is trivialized in the manner discussed in Section 2.1 and identified with a smooth real-valued function. We define the associated *contact Hamiltonian vector field* X_f on M by

$$\begin{cases} \theta(X_f) = f, \\ d\theta(X_f, Y) = -df(Y), \qquad Y \in H. \end{cases}$$

The vector field X_f is irrelevant to the choice of θ . Indeed, if $\hat{\theta} = e^u \theta$, then since the corresponding trivialization of the density is given by $\hat{f} = e^u f$, we have $\hat{\theta}(X_f) = e^u f = \hat{f}$ and

$$d\theta(X_f, Y) = e^u (d\theta + du \wedge \theta)(X_f, Y) = -e^u (df(Y) + f \, du(Y)) = -df(Y) \quad \text{for } Y \in H.$$

In terms of the Reeb vector field T associated with θ , one can explicitly write

(3.2)
$$X_f = fT + i(\nabla^{\alpha} f)Z_{\alpha} - i(\nabla^{\overline{\alpha}} f)Z_{\overline{\alpha}}$$

where the indices α and $\overline{\alpha}$ are raised by the unweighted Levi form.

By Cartan's formula, it follows that the Lie derivative \mathcal{L}_{X_f} satisfies

(3.3)
$$\mathcal{L}_{X_f}\theta = d(\theta(X_f)) + d\theta(X_f, \cdot) = (Tf)\theta,$$

which implies that X_f is a contact vector field. Moreover, the restriction of $d\theta$ to H rescales conformally, with the same conformal factor as the one for θ , as we can see by

(3.4)
$$\mathcal{L}_{X_f} d\theta = d(d\theta(X_f, \cdot)) = -d(df - (Tf)\theta) \equiv (Tf)d\theta \mod \theta.$$

These computations also imply that the compatibility of J is preserved by the flow Fl_t generated by X_f . Indeed, (3.3) and (3.4) imply that $\operatorname{Fl}_t^*(d\theta) \equiv d\theta_t \mod \theta$, where $\theta_t = \operatorname{Fl}_t^* \theta$. Consequently, if we pull back the symmetric form $d\theta(\cdot, J \cdot)$ on H by the flow, then we get $d\theta_t(\cdot, J_t \cdot)$ on H, where $J_t = (\operatorname{Fl}_t^{-1})_* \circ J \circ (\operatorname{Fl}_t)_*$. Therefore, the latter bilinear form is symmetric and positive definite, which implies that J_t satisfies the compatibility condition. Thus we get a family J_t of compatible almost CR structures on the same underlying contact manifold (M, H).

In general, if J is a compatible almost CR structure on (M, H) sufficiently close to J pointwisely, then we can define the *deformation tensor* φ as the bundle homomorphism $H^{1,0} \to H^{0,1}$ such that

$$\tilde{T}^{1,0}M = \bigsqcup_{p \in M} \{ Z + \varphi_p(Z) \mid Z \in H_p^{1,0} \}.$$

The homomorphism φ can be expressed as $\varphi_{\alpha}^{\overline{\beta}}$ in index notation. We set $\varphi_{\overline{\alpha}}^{\beta} = \overline{\varphi_{\alpha}^{\overline{\beta}}}$ so that φ is understood to be a real tensor.

We apply this general definition to our $J_t = (\operatorname{Fl}_t^{-1})_* \circ J \circ (\operatorname{Fl}_t)_*$ and let φ_t be the deformation tensor of J_t . We set

$$\psi = \left. \frac{d\varphi_t}{dt} \right|_{t=0},$$

i.e., ψ is the "derivative" of our family of almost CR structures J_t taken in terms of the deformation tensor. If we simply regard J_t itself as a tensor and differentiate it, then the derivative at t = 0, which is nothing but the Lie derivative of J, can be computed as follows. For $Z \in H^{1,0}$,

$$J_t Z = J_t ((Z + t\psi(Z)) - t\psi(Z)) = i(Z + t\psi(Z)) + it\psi(Z) + O(t^2) = iZ + 2it\psi(Z) + O(t^2),$$

and hence

(3.5)
$$\mathcal{L}_{X_f}J = \lim_{t \to 0} \frac{J_t - J}{t} = -2J \circ \psi.$$

It is immediate from the definition that ψ can be seen as an element of $\operatorname{Re}(\mathcal{E}_{\alpha\beta}(1,1)\oplus\mathcal{E}_{\overline{\alpha\beta}}(1,1))$ by lowering the upper index by the weighted Levi form. In addition, the compatibility of J_t and (3.5) imply that $d\theta(\cdot, J \circ \psi(\cdot))$ is symmetric on H, by which we can conclude that

$$\psi \in \operatorname{Re}(\mathcal{E}_{(\alpha\beta)}(1,1) \oplus \mathcal{E}_{(\overline{\alpha}\overline{\beta})}(1,1))$$

The following proposition claims that the assignment $f \mapsto \psi$ actually equals the operator D defined by (1.2).

Proposition 3.1. The infinitesimal deformation tensor ψ associated with the contact Hamiltonian vector field X_f is given by $\psi = Df$.

Proof. Let $\{Z_{\alpha}\}$ be a local frame of $H^{1,0}$. Note first that

$$(\mathcal{L}_{X_f}J)(Z_{\alpha}) = [X_f, iZ_{\alpha}] - J[X_f, Z_{\alpha}] = 2i[X_f, Z_{\alpha}]_{0,1},$$

where the subscript "0,1" denotes the projection from $\mathbb{C}H = H^{1,0} \oplus H^{0,1}$ onto the second summand. On the other hand, (3.5) implies $(\mathcal{L}_{X_f}J)(Z_{\alpha}) = 2i\psi(Z_{\alpha})$, by which we conclude that $\psi(Z_{\alpha}) = [X_f, Z_{\alpha}]_{0,1}$, or equivalently,

$$\psi_{\alpha}{}^{\overline{\beta}} = \theta^{\overline{\beta}}([X_f, Z_{\alpha}]).$$

The right-hand side can be rewritten as

$$\theta^{\overline{\beta}}([X_f, Z_\alpha]) = -d\theta^{\overline{\beta}}(X_f, Z_\alpha) - Z_\alpha(\theta^{\overline{\beta}}(X_f)) = -d\theta^{\overline{\beta}}(X_f, Z_\alpha) + iZ_\alpha \nabla^{\overline{\beta}} f,$$

where the second equality follows by (3.2). Furthermore, it follows from (2.10) and (3.2) that

$$d\theta^{\overline{\beta}}(X_f, Z_\alpha) = \left(\theta^{\overline{\gamma}} \wedge \omega_{\overline{\gamma}}^{\overline{\beta}} - A_{\gamma}^{\overline{\beta}} \theta^{\gamma} \wedge \theta + \frac{1}{2} N^{\overline{\beta}}_{\gamma\sigma} \theta^{\gamma} \wedge \theta^{\sigma}\right) (X_f, Z_\alpha)$$
$$= \theta^{\overline{\gamma}}(X_f) \omega_{\overline{\gamma}}^{\overline{\beta}}(Z_\alpha) + A_\alpha^{\overline{\beta}} \theta(X_f) + N^{\overline{\beta}}_{\gamma\alpha} \theta^{\gamma}(X_f)$$
$$= -i\omega_{\overline{\gamma}}^{\overline{\beta}}(Z_\alpha) \nabla^{\overline{\gamma}} f + A_\alpha^{\overline{\beta}} f + i N^{\overline{\beta}}_{\gamma\alpha} \nabla^{\gamma} f,$$

which implies $\psi_{\alpha}{}^{\overline{\beta}} = i \nabla_{\alpha} \nabla^{\overline{\beta}} f - A_{\alpha}{}^{\overline{\beta}} f - i N^{\overline{\beta}}{}_{\alpha\gamma} \nabla^{\gamma} f$. This means $\psi = Df$ because of (3.1).

3.2. As an operator whose adjoint annihilates the CR obstruction tensor. The CR obstruction tensor $\mathcal{O}_{\alpha\beta} \in \mathcal{E}_{(\alpha\beta)}(-n,-n)$ of a contact manifold (M,H) with a compatible almost CR structure J is introduced in [28] when dim $M = 2n + 1 \geq 5$. Recall that $\mathcal{O}_{\alpha\beta}$ vanishes when J is integrable. In this paper, we prefer regarding \mathcal{O} as a section of $\operatorname{Re}(\mathcal{E}_{(\alpha\beta)}(-n,-n) \oplus \mathcal{E}_{(\overline{\alpha\beta})}(-n,-n))$ by setting $\mathcal{O} = (\mathcal{O}_{\alpha\beta}, \mathcal{O}_{\overline{\alpha\beta}})$, where $\mathcal{O}_{\overline{\alpha\beta}} = \overline{\mathcal{O}_{\alpha\beta}}$. Then it is known [28, Theorem 1.2 (3)] that

$$(3.6) D^*\mathcal{O} = 0,$$

where

$$D^*$$
: $\operatorname{Re}(\mathcal{E}_{(\alpha\beta)}(-n,-n) \oplus \mathcal{E}_{(\overline{\alpha\beta})}(-n,-n)) \to \operatorname{Re}\mathcal{E}(-n-2,-n-2)$

is the formal adjoint of the CR Killing operator (1.2).

The CR obstruction tensor is an analog of the Fefferman–Graham conformal obstruction tensor [17, 18], which we write \mathcal{O}_{ij} , defined for conformal manifolds of even dimension ≥ 4 . To define \mathcal{O}_{ij} , one considers the asymptotic Dirichlet problem for the Einstein equation for AH metrics (asymptotically hyperbolic metrics) with Dirichlet data given by a conformal manifold (M, [g]); then \mathcal{O}_{ij} is the obstruction to the existence of formal power series solutions to this problem. In view of the fact that any AH Einstein metric admits a so-called polyhomogeneous expansion [16,4] at boundary at infinity in an appropriate gauge, one can also say that \mathcal{O}_{ij} is the first logarithmic term coefficient of the expansion of an AH Einstein metric g_+ with prescribed conformal infinity (M, [g]), assuming that such an metric exists (note that \mathcal{O}_{ij} itself can always be defined for any conformal manifold, no matter g_+ exists or not).

In the standard notation in conformal geometry, \mathcal{O}_{ij} is a symmetric section of the weighted tensor bundle $\mathcal{E}_{ij}[-n+2]$, and the trace of \mathcal{O}_{ij} always vanishes; so we may write $\mathcal{O}_{ij} \in \mathcal{E}_{(ij)_0}[-n+2]$. In 4 dimensions, \mathcal{O}_{ij} is also known as the Bach tensor B_{ij} , which is explicitly given by

$$B_{ij} = \nabla^k C_{ijk} + P^{kl} W_{ikjl},$$

where P, C, and W are the Schouten, the Cotton, and the Weyl tensor, respectively, of any fixed representative metric g of the conformal class [g] (see [18] for details). It is easy to see that \mathcal{O}_{ij} can also be expressed in general dimensions by a universal formula given in terms of the curvature tensor and its covariant derivatives, although deriving the concrete formula is quite a hard task.

Likewise, the CR obstruction tensor $\mathcal{O}_{\alpha\beta}$ of (M, H, J) is the obstruction to the existence of formal power series solutions to the asymptotic Dirichlet problem for the Einstein equation for ACH metrics with conformal infinity (M, H, J). If a contact form θ is fixed, then $\mathcal{O}_{\alpha\beta}$ can be universally expressed in terms of the Tanaka–Webster local invariants, although the concrete formula is currently lacking in any dimensions ≥ 5 .

Remark 3.2. Originally, the definition of the conformal obstruction tensor \mathcal{O}_{ij} is given in [17] using the ambient metrics, whose formal expansion theory is basically parallel with that of AH Einstein metrics. On the other hand, the ambient metric approach in CR geometry is only partly available. For integrable CR structures the notion of ambient metrics exists (and it is actually the origin of the notion; see Fefferman [19]), but the ambient metric is not yet known for general compatible almost CR structures, and the CR obstruction tensor $\mathcal{O}_{\alpha\beta}$ can be currently only defined via ACH Einstein metrics.

Equality (3.6) follows from the (contracted) second Bianchi identity satisfied by the Ricci tensor of ACH Einstein metrics. More precisely, to show (3.6), we use an ACH metric g_+ with the prescribed conformal infinity having a power series asymptotic expansion such that its Ricci tensor $\operatorname{Ric}(g_+)$ is asymptotic to λg_+ , where λ is a negative constant, to a certain sufficiently high order. Then the first non-vanishing coefficient of the power series expansion of $\operatorname{Ric}(g_+) - \lambda g_+$ contains the CR obstruction tensor \mathcal{O} , and the second Bianchi identity implies some equality satisfied by \mathcal{O} , which is (3.6), actually.

If we employ the same procedure in conformal geometry, the equality that we obtain is the well-known (e.g., [18, Theorem 3.8 (2)]) divergence-freeness of the conformal obstruction tensor

(3.7)
$$\nabla^j \mathcal{O}_{ij} = 0$$

The divergence operator here can be naturally understood as the formal adjoint of the conformal Killing operator

$$K: \mathcal{E}_i[2] \to \mathcal{E}_{(ij)_0}[2], \qquad v_i \mapsto \nabla_{(i}v_{j)_0}.$$

The parallelism of K and D is the reason why we suggest the name "the CR Killing operator" for the operator D.

Taking advantage of this opportunity, we want to present that there is another way to show (3.7) in conformal geometry or (3.6) in CR geometry, which is based on the variational formula of the total integral of the *Q*-curvature [21, 29]. In conformal geometry, we argue as follows. Recall that the conformal Killing operator K describes the trivial infinitesimal deformation of conformal structure induced by vector fields in $\mathcal{E}^i \cong \mathcal{E}_i[2]$. Consequently, it follows from the variational formula that

$$0 = \int_M \langle Kv, \mathcal{O} \rangle = \int_M \langle v, K^* \mathcal{O} \rangle \quad \text{for any } v = v_i \in \mathcal{E}_i[2],$$

which implies that $K^*\mathcal{O} = 0$. The same argument works in CR geometry as well, because the CR Killing operator D describes trivial infinitesimal deformations of compatible almost CR structure as we saw in Proposition 3.1.

4. PARABOLIC GEOMETRIES, TRACTOR CONNECTIONS, BGG OPERATORS

In this section, we summarize some general notions and results from the theory of parabolic geometries that we use in the subsequent developments. For more background and details, see the extensive reference of Čap–Slovák [13] and, for various specific aspects, Yamaguchi [33], Sharpe [31], Calderbank–Diemer [6], for example.

4.1. Cartan geometries. Let G be a Lie group and H a closed subgroup. Their Lie algebras are denoted by \mathfrak{g} and \mathfrak{h} , respectively. Then a *Cartan geometry* of type (G, H) is a smooth manifold M of the same dimension as G/H equipped with a principal H-bundle $\mathcal{G} \to M$ and an H-equivariant \mathfrak{g} -valued 1-form ω on \mathcal{G} satisfying the following conditions:

- (i) $\omega(\zeta_X) = X$ for each $X \in \mathfrak{h}$, where ζ_X is the fundamental vector field;
- (ii) $\omega_u \colon T_u \mathcal{G} \to \mathfrak{g}$ is a linear isomorphism for all $u \in \mathcal{G}$.

The 1-form ω is called a *Cartan connection*. Note that ω_u induces an isomorphism $T_{\pi(u)}M \cong \mathfrak{g}/\mathfrak{h}$ for each $u \in \mathcal{G}$, where π is the projection $\mathcal{G} \to M$, and thus TM is identified with the associated vector bundle $\mathcal{G} \times_H \mathfrak{g}/\mathfrak{h}$.

The curvature form of a Cartan geometry (\mathcal{G}, ω) is the g-valued 2-form K on \mathcal{G} defined by

$$K = d\omega + \frac{1}{2}[\omega \wedge \omega].$$

An equivalent notion is the curvature function $\kappa \colon \mathcal{G} \to \bigwedge^2 \mathfrak{g}^* \otimes \mathfrak{g}$, which is defined by

$$\kappa(u)(X,Y) = K_u(\omega_u^{-1}(X), \omega_u^{-1}(Y)), \qquad X, Y \in \mathfrak{g}$$

It follows from the definition that K is a horizontal H-equivariant 2-form, and hence κ can also be seen as a function with values in $\bigwedge^2 (\mathfrak{g}/\mathfrak{h})^* \otimes \mathfrak{g}$.

The torsion form of a Cartan geometry (\mathcal{G}, ω) is defined to be $\pi_{\mathfrak{g}} \circ K$, where $\pi_{\mathfrak{g}} \colon \mathfrak{g} \to \mathfrak{g}/\mathfrak{h}$ is the natural projection. The geometry (\mathcal{G}, ω) is called *torsion-free* when the torsion form vanishes, or equivalently, the curvature form K takes values in \mathfrak{h} .

4.2. Parabolic geometries. Now let G be a (real or complex) semisimple Lie group, and suppose that its Lie algebra \mathfrak{g} is given a |k|-grading

(4.1)
$$\mathfrak{g} = \mathfrak{g}_{-k} \oplus \mathfrak{g}_{-k+1} \oplus \cdots \oplus \mathfrak{g}_{k-1} \oplus \mathfrak{g}_k,$$

i.e., a direct sum decomposition of \mathfrak{g} such that $[\mathfrak{g}_i, \mathfrak{g}_j] \subset \mathfrak{g}_{i+j}$ and $\mathfrak{g}_- = \mathfrak{g}_{-k} \oplus \cdots \oplus \mathfrak{g}_{-1}$ is generated by \mathfrak{g}_{-1} . It is known that the subalgebra \mathfrak{g}_0 is reductive, and there exists a unique element E in the center of \mathfrak{g}_0 such that $\mathrm{ad}(E) = i$ id on \mathfrak{g}_i for all i, which is called the *grading element* (see [33, Section 3]).

Associated with the above |k|-grading is the filtration

(4.2)
$$\mathfrak{g} = \mathfrak{g}^{-k} \supset \mathfrak{g}^{-k+1} \supset \cdots \supset \mathfrak{g}^{k-1} \supset \mathfrak{g}^k \supset \{0\},$$

where $\mathfrak{g}^i = \bigoplus_{i \leq j} \mathfrak{g}_j$. In particular, \mathfrak{g}^0 is also denoted by \mathfrak{p} . A closed subgroup P of G is called a *parabolic subgroup* admitted by the |k|-grading (4.1) if its Lie algebra equals \mathfrak{p} and the adjoint action of any $p \in P$ preserves each \mathfrak{g}^i .

Definition 4.1. A *parabolic geometry* is a Cartan geometry of type (G, P), where G is a semisimple Lie group and P is its parabolic subgroup.

The Levi subgroup $G_0 \subset P$ is defined by

$$G_0 = \{ p \in P \mid \operatorname{Ad}(p)(\mathfrak{g}_i) \subset \mathfrak{g}_i \text{ for all } i \}.$$

In view of the fact that the elements $X \in \mathfrak{g}_0$ are characterized by the property $\operatorname{ad}(X)(\mathfrak{g}_i) \subset \mathfrak{g}_i$ for all *i* [13, Lemma 3.1.3], it follows that the Lie algebra of G_0 equals \mathfrak{g}_0 .

Among the *P*-modules \mathfrak{g}^j in the filtration (4.2), not only $\mathfrak{p} = \mathfrak{g}^0$ but also $\mathfrak{p}_+ = \mathfrak{g}^1$ is particularly important for us, because there is an isomorphism $\mathfrak{p}_+ \cong (\mathfrak{g}/\mathfrak{p})^*$ of *P*-modules induced by the Killing form of \mathfrak{g} . On the other hand, $\mathfrak{g}/\mathfrak{p}$ is isomorphic to \mathfrak{g}_- as a G_0 -module, but \mathfrak{g}_- does not carry a natural *P*-module structure. It is known that the mapping $G_0 \times \mathfrak{p}_+ \to P$ defined by $(g_0, Z) \mapsto g_0 e^Z$ is a diffeomorphism [13, Theorem 3.1.3], and consequently, if we define $P_+ = \exp \mathfrak{p}_+$, then *P* is the semidirect product $G_0 \ltimes P_+$.

Recall that the curvature function κ of a parabolic geometry (\mathcal{G}, ω) takes values in $\bigwedge^2(\mathfrak{g}/\mathfrak{p})^* \otimes \mathfrak{g}$. As a *P*-module, $\bigwedge^2(\mathfrak{g}/\mathfrak{p})^* \otimes \mathfrak{g}$ is isomorphic to $\bigwedge^2 \mathfrak{p}_+ \otimes \mathfrak{g}$, and this is the chain space $C_2(\mathfrak{p}_+, \mathfrak{g})$ in the Lie algebra homology complex for \mathfrak{p}_+ with values in \mathfrak{g} . Let \mathbb{W} be a \mathfrak{g} -module in general and consider the chain space $C_k(\mathfrak{p}_+, \mathbb{W}) = \bigwedge^k \mathfrak{p}_+ \otimes \mathbb{W}$. Then the boundary operator, which is traditionally denoted by ∂^* and called the *Kostant codifferential*, acting on $C_k(\mathfrak{p}_+, \mathbb{W})$ is defined by the following formula of the action on decomposable elements, where $Z_1, ..., Z_k \in \mathfrak{p}_+, w \in \mathbb{W}$, and $\check{}$ indicates the omission:

(4.3)
$$\partial^* (Z_1 \wedge \dots \wedge Z_k \otimes w) = \sum_i (-1)^{i+1} Z_1 \wedge \dots \wedge \check{Z}_i \wedge \dots \wedge Z_k \otimes (Z_i \cdot w) + \sum_{i < j} (-1)^{i+j} [Z_i, Z_j] \wedge Z_1 \wedge \dots \wedge \check{Z}_i \wedge \dots \wedge \check{Z}_j \wedge \dots \wedge Z_k \otimes w.$$

Also, by identifying C_k with $\bigwedge^k \mathfrak{g}^*_- \otimes \mathbb{W}$ as a G_0 -module, we define $\partial \colon C_k \to C_{k+1}$ by

(4.4)
$$\partial \varphi(X_1, \dots, X_{k+1}) = \sum_i (-1)^{i+1} X_i \cdot \varphi(X_1, \dots, \check{X}_i, \dots, X_{k+1}) + \sum_{i < j} (-1)^{i+j} \varphi([X_i, X_j], X_1, \dots, \check{X}_i, \dots, \check{X}_j, \dots, X_{k+1}),$$

where $X_0, ..., X_k \in \mathfrak{g}_-$. The Lie algebra homology $H_k(\mathfrak{p}_+, \mathbb{W})$ and cohomology $H^k(\mathfrak{g}_-, \mathbb{W})$ are defined by

$$H_k(\mathfrak{p}_+, \mathbb{W}) := \frac{\ker(\partial^* \colon C_k \to C_{k-1})}{\operatorname{im}(\partial^* \colon C_{k+1} \to C_k)} \quad \text{and} \quad H^k(\mathfrak{g}_-, \mathbb{W}) := \frac{\ker(\partial \colon C_k \to C_{k+1})}{\operatorname{im}(\partial \colon C_{k-1} \to C_k)},$$

where we understand that $C_{-1} = 0$ as usual.

Definition 4.2. A parabolic geometry (\mathcal{G}, ω) is said to be *normal* if its curvature function satisfies $\partial^* \kappa = 0$.

When $\mathbb{W} = \mathfrak{g}$, the chain space $C_k(\mathfrak{p}_+, \mathfrak{g})$ carries a natural G_0 -invariant grading, with respect to which $C_k(\mathfrak{p}_+, \mathfrak{g})_l$ is the set of elements in $C_k(\mathfrak{p}_+, \mathfrak{g}) = \bigwedge^k \mathfrak{p}_+ \otimes \mathfrak{g}$ that are expressible as a sum of elements in $\mathfrak{g}_{i_1} \wedge \cdots \wedge \mathfrak{g}_{i_k} \otimes \mathfrak{g}_j$ with $i_1 + \cdots + i_k + j = l$; elements of $C_k(\mathfrak{p}_+, \mathfrak{g})_l$ are said to be of *homogeneity l*. The associated *P*-invariant filtration is defined by setting $C_k(\mathfrak{p}_+, \mathfrak{g})^l = \bigoplus_{l \leq m} C_k(\mathfrak{p}_+, \mathfrak{g})_m$.

Similarly, any $\overline{\mathfrak{g}}$ -module \mathbb{W} admits a \mathfrak{g}_0 -invariant eigendecomposition with respect to the action of the grading element E corresponding to real eigenvalues, and hence the set of homogeneity l elements and the \mathfrak{p} -invariant filtration of $C_k(\mathfrak{p}_+, \mathbb{W})$ are naturally defined. These are further inherited by the homology $H_k(\mathfrak{p}_+, \mathbb{W})$ because (4.3) shows that ∂^* preserves the homogeneity degree. Also, the notion of homogeneity l elements of $H^k(\mathfrak{g}_-, \mathbb{W})$ makes sense because (4.4) implies that ∂ preserve the homogeneity degree.

4.3. Tractor bundles and connections. Let (\mathcal{G}, ω) be a Cartan geometry of type (G, H). As $\mathcal{G} \to M$ is a principal *H*-bundle, any *H*-module gives rise to the associated vector bundle over the space *M*. If \mathbb{W} is moreover a *G*-module, then the associated vector bundle $\mathcal{W} = \mathcal{G} \times_H \mathbb{W}$, which is called the *tractor bundle*, naturally carries a linear connection.

We describe this in a slightly generalized situation. Suppose that \mathbb{W} is a (\mathfrak{g}, H) -module, i.e., that \mathbb{W} is a \mathfrak{g} -module together with an action of H whose induced action of \mathfrak{h} equals the restriction of the action of \mathfrak{g} . Then we can still define the associated tractor bundle by $\mathcal{W} = \mathcal{G} \times_H \mathbb{W}$. Recall that sections of \mathcal{W} are identified with elements of $\Gamma(\mathcal{G}, \mathbb{W})^H$, i.e., \mathbb{W} -valued functions on \mathcal{G} that are H-equivariant. Then a natural linear connection of \mathcal{W} can be defined as follows.

Definition 4.3. (1) For any *H*-module \mathbb{W} , the fundamental derivative on $\mathcal{W} = \mathcal{G} \times_H \mathbb{W}$ is defined by $D_{\xi}s = \omega^{-1}(\xi)s$ for any section s of \mathcal{W} and $\xi \in \mathfrak{g}$.

(2) For any (\mathfrak{g}, H) -module \mathbb{W} , we define $\nabla_{\xi} s = D_{\xi} s + \xi \cdot s$ for any section s of the associated tractor bundle $\mathcal{W} = \mathcal{G} \times_H \mathbb{W}$ and $\xi \in \mathfrak{g}$. Then ∇s gives an element of $\Gamma(\mathcal{G}, (\mathfrak{g}/\mathfrak{h})^* \otimes \mathbb{W})^H$, and thus ∇ can be understood as a linear connection of \mathcal{W} , which is called the *tractor connection*.

Now consider a parabolic geometry (\mathcal{G}, ω) of type (G, P), with associated |k|-grading (4.1) of \mathfrak{g} . Then any (\mathfrak{g}, P) -module \mathbb{W} carries, as discussed in the previous subsection, a natural \mathfrak{g}_0 -invariant eigendecomposition with respect to the grading element E, which is actually G_0 -invariant because E is fixed by the adjoint action of any element of G_0 . As a consequence, a P-invariant filtration of $C_k(\mathfrak{p}_+, \mathbb{W})$ is induced, and the bundle $\Omega^k \otimes \mathcal{W}$ of k-forms with values in the tractor bundle \mathcal{W} inherits a filtration.

Then it follows that ∇ is of homogeneity 0 in the sense that sections of \mathcal{W}^l are mapped by ∇ to sections of $(\Omega^1 \otimes \mathcal{W})^l$. Passing to the associated graded bundles, the induced mapping $\operatorname{gr} \nabla \colon \Gamma(\operatorname{gr}_l(\mathcal{W})) \to \Gamma(\operatorname{gr}_l(\Omega^1 \otimes \mathcal{W}))$ is in fact algebraic, and equals $\operatorname{gr} \partial$. This is also the case for differential forms of higher degree if we assume that (\mathcal{G}, ω) is a regular parabolic geometry (see the next subsection): the covariant exterior derivative d^{∇} maps sections of $(\Omega^k \otimes \mathcal{W})^l$ to sections of $(\Omega^{k+1} \otimes \mathcal{W})^l$, and $\operatorname{gr} d^{\nabla} = \operatorname{gr} \partial$.

A case of particular interest is when $\mathbb{W} = \mathfrak{g}$. In this case, the associated tractor bundle, which we write $\mathcal{A}M$, is called the *adjoint tractor bundle* and plays an important role. Note that there is a canonical projection $\Pi: \mathcal{A}M \to TM$ induced by the quotient map $\mathfrak{g} \to \mathfrak{g}/\mathfrak{p}$.

The curvature function κ of a parabolic geometry (\mathcal{G}, ω) , which takes values in $\bigwedge^2 (\mathfrak{g}/\mathfrak{p})^* \otimes \mathfrak{g}$, is clearly *P*-equivariant, so it can be interpreted as a 2-form on *M* with values in $\mathcal{A}M$. We can use this fact to introduce another linear connection $\tilde{\nabla}$ of $\mathcal{A}M$ by

(4.5)
$$\tilde{\nabla}s = \nabla s + \iota_{\Pi(s)}\kappa,$$

where s is a section of $\mathcal{A}M$ and $\Pi(s)$ denotes, by abuse of notation, the vector field $\Pi \circ s$.

Definition 4.4. We call $\tilde{\nabla}$ defined by (4.5) the modified adjoint tractor connection.

Cap [9] introduced this connection in relation with deformations of parabolic geometries. In fact, trivial infinitesimal deformations of a parabolic geometry (\mathcal{G}, ω) (or of any Cartan geometry) are given in the form $\tilde{\nabla}s$, as discussed in [9, Sections 3.1 and 3.2] and briefly summarized as follows. A section s of the adjoint tractor bundle $\mathcal{A}M$ corresponds to a P-invariant vector field $\omega^{-1}(s)$ on \mathcal{G} , or in other words, an infinitesimal principal bundle automorphism of \mathcal{G} . The induced infinitesimal change $\mathcal{L}_{\omega^{-1}(s)}\omega$ of the Cartan connection is a horizontal P-equivariant g-valued 1-form on \mathcal{G} and hence is an element of $\Omega^1(M, \mathcal{A}M)$, and actually it is given by $\tilde{\nabla}s$. In addition, it is also known by [9] that the covariant exterior differentiation $d^{\tilde{\nabla}} : \Omega^1(M, \mathcal{A}M) \to \Omega^2(M, \mathcal{A}M)$ assigns to an infinitesimal modification of the Cartan connection the induced infinitesimal change of the curvature.

4.4. Infinitesimal flag structures and regularity. For a parabolic geometry (\mathcal{G}, ω) of type (G, P), with Levi subgroup G_0 of P, we define the principal G_0 -bundle $\mathcal{G}_0 \to M$ by $\mathcal{G}_0 = \mathcal{G}/P_+$, which we call the graded frame bundle of (\mathcal{G}, ω) .

Note that, since ω_u defines a linear isomorphism $T_u \mathcal{G} \to \mathfrak{g}$ for each $u \in \mathcal{G}$, the filtration (4.2) of \mathfrak{g} induces the filtration

(4.6)
$$T\mathcal{G} = T^{-k}\mathcal{G} \supset T^{-k+1}\mathcal{G} \supset \cdots \supset T^0\mathcal{G} = V\mathcal{G},$$

where $T_u^i \mathcal{G}$ is the preimage of \mathfrak{g}^i by ω_u and $V\mathcal{G}$ is the vertical bundle for the projection $\mathcal{G} \to M$. Then (4.6) naturally induces the filtration

$$T\mathcal{G}_0 = T^{-k}\mathcal{G}_0 \supset T^{-k+1}\mathcal{G}_0 \supset \cdots \supset T^0\mathcal{G}_0 = V\mathcal{G}_0$$

of $T\mathcal{G}_0$, and furthermore, the one

$$TM = T^{-k}M \supset T^{-k+1}M \supset \cdots \supset T^0M = 0$$

of the tangent bundle TM of the base manifold M.

One can show that, for $-k \leq i \leq -1$, the \mathfrak{g}_i -component ω_i of the Cartan connection ω restricted to $T^i\mathcal{G}$ descends to a G_0 -equivariant section of $(T^i\mathcal{G}_0)^* \otimes \mathfrak{g}_i$ over \mathcal{G}_0 [13, Proposition 3.1.5], which we write θ_i . Thus \mathcal{G}_0 comes with a collection $(\theta_{-k}, \ldots, \theta_{-1})$ of partially defined \mathfrak{g}_i valued 1-forms with each θ_i satisfying ker $\theta_i = T^{i+1}\mathcal{G}_0$. The triple $((T^iM)_{i=-k}^{-1}, \mathcal{G}_0, (\theta_{-k}, \ldots, \theta_{-1}))$ is called the *induced infinitesimal flag structure* of a parabolic geometry (\mathcal{G}, ω) . Abstractly, infinitesimal flag structures are defined as follows.

Definition 4.5 ([13, Definition 3.1.6]). An *infinitesimal flag structure* of type (G, P) on a smooth manifold M is a triple $((T^i M)_{i=-k}^{-1}, \mathcal{G}_0, (\theta_{-k}, \ldots, \theta_{-1}))$, where:

- (i) $(T^i M)_{i=-k}^{-1}$ denotes a filtration $TM = T^{-k}M \supset T^{-k+1}M \supset \cdots \supset T^{-1}M$ satisfying rank $T^i M = \dim(\mathfrak{g}^i/\mathfrak{p});$
- (ii) \mathcal{G}_0 is a principal G_0 -bundle over M;

(iii) θ_i is a G_0 -equivariant section of $(T^i \mathcal{G}_0)^* \otimes \mathfrak{g}_i$, where $T^i \mathcal{G}_0$ is the preimage of $T^i M$, such that ker $\theta_i = T^{i+1} \mathcal{G}_0$.

There is a reinterpretation of infinitesimal flag structures in terms of a reduction of the structure group of the full graded frame bundle $\mathcal{F}_{gr}M$ of the graded tangent bundle gr(TM). Note that the adjoint action of G_0 preserves the grading (4.1) and thus defines a group homomorphism Ad: $G_0 \to GL_{gr}(\mathfrak{g}_-)$, with respect to which we reduce the structure group^{*}.

Proposition 4.6 ([13, Proposition 3.1.6]). An infinitesimal flag structure of type (G, P) on a manifold M is equivalent to the pair of a filtration $(T^iM)_{i=-k}^{-1}$ of TM as in Definition 4.5 (i) and a reduction of the structure group of $\mathcal{F}_{gr}M$ to G_0 with respect to the homomorphism Ad: $G_0 \to GL_{gr}(\mathfrak{g}_-)$.

The notion of infinitesimal flag structures should be supplemented by an important notion of regularity. An infinitesimal flag structure $((T^i M)_{i=-k}^{-1}, \mathcal{G}_0, (\theta_{-k}, \ldots, \theta_{-1}))$ is said to be *regular* if the filtration $(T^i M)_{i=-k}^{-1}$ is compatible with the Lie bracket and the induced bundle map

 $\operatorname{gr}_i(TM) \times \operatorname{gr}_j(TM) \to \operatorname{gr}_{i+i}(TM)$

coincides with the map induced by the Lie algebra bracket $\mathfrak{g}_i \times \mathfrak{g}_j \to \mathfrak{g}_{i+j}$ (see [13, Section 3.1.7] for details). A parabolic geometry is called *regular* if it induces a regular infinitesimal flag structure.

The following fact is crucial when we consider the BGG construction for the modified adjoint tractor connection in the next subsection.

Proposition 4.7 ([13, Corollary 3.1.8 (2)]). A parabolic geometry (\mathcal{G}, ω) is regular if and only if its curvature function κ is of homogeneity 1, i.e., seen as the $\mathcal{A}M$ -valued 2-form, κ is a section of $(\Omega^2 \otimes \mathcal{A}M)^1$.

Giving an infinitesimal flag structure is a universal way of describing certain kind of geometry of the base space M. For example, if G = PSU(n + 1, 1) and P is defined to be the stabilizer of a null complex line in the complex Minkowski space $\mathbb{C}^{n+1,1}$, then infinitesimal flag structures of type (G, P) on a (2n + 1)-dimensional smooth manifold M are in one-to-one correspondence with compatible almost CR structures on M, as discussed in detail in Section 6.2.

The following theorem, which is basically due to works of Tanaka in 1960–70s, provides a generalization in terms of parabolic geometries of the construction of normal Cartan connection associated with compatible almost CR structures carried out by Tanaka [32] and Chern–Moser [15] (in the integrable case).

Theorem 4.8 (cf. Čap–Slovák [13, Sections 3.1.13–14]). Let $((T^iM)_{i=-k}^{-1}, \mathcal{G}_0, (\theta_{-k}, \ldots, \theta_{-1}))$ be a regular infinitesimal flag structure of type (G, P), and suppose that $H^1(\mathfrak{g}_-, \mathfrak{g})$ is concentrated in non-positive homogeneity degrees and \mathfrak{g}_0 carries no simple ideals of \mathfrak{g} . Then, there exists a normal regular parabolic geometry (\mathcal{G}, ω) that induces $((T^iM)_{i=-k}^{-1}, \mathcal{G}_0, (\theta_{-k}, \ldots, \theta_{-1}))$, which is unique up to the action of principal P-bundle isomorphisms inducing the identity on the underlying infinitesimal structure.

The fact that CR geometry satisfies the assumption of the above theorem is well-known and checked later in Section 5.4. In fact, it suffices to compute the Lie algebra homology $H_1(\mathfrak{p}_+,\mathfrak{g})$ to verify the cohomological assumption, since it is known that $H^1(\mathfrak{g}_-,\mathfrak{g})$ is isomorphic to $H_1(\mathfrak{p}_+,\mathfrak{g})$ as a G_0 -module.

^{*}The homomorphism Ad: $G_0 \to GL_{gr}(\mathfrak{g}_-)$ need not be injective.

4.5. **BGG operators.** As an application of the theory of parabolic geometries, we can construct certain invariant linear differential operators in a systematic way. An implementation of such techniques is given by the "curved" BGG construction of Čap–Slovák–Souček [14], which is then simplified by Calderbank–Diemer [6]. It starts with the tractor connection ∇ of any tractor bundle $\mathcal{W} = \mathcal{G} \times_P \mathbb{W}$ of a parabolic geometry (\mathcal{G}, ω) and ends up with a sequence of "BGG operators" $D_k, k \geq 0$, which forms a complex when (\mathcal{G}, ω) is locally flat (i.e., locally homogeneous). In fact, the same construction can also be triggered for some modified connections of \mathcal{W} , including the modified adjoint tractor connection $\tilde{\nabla}$ discussed in Section 4.3, as pointed out by Čap [9] and sketched below.

Let (\mathcal{G}, ω) be a regular parabolic geometry of type (G, P), \mathcal{W} the tractor bundle associated with a (\mathfrak{g}, P) -module \mathbb{W} , and let ∇ be the tractor connection (unmodified, for the time being). Then the following twisted de Rham sequence can be considered, where d^{∇} is the covariant exterior differentiation:

(4.7)
$$\mathcal{W} \xrightarrow{\nabla} \Omega^1 \otimes \mathcal{W} \xrightarrow{d^{\nabla}} \Omega^2 \otimes \mathcal{W} \xrightarrow{d^{\nabla}} \cdots$$

The BGG operators are introduced to extend the sequence (4.7) into a certain commutative diagram. Recall that the Lie algebra homology $H_k(\mathfrak{p}_+, \mathbb{W})$ is defined by

$$H_k(\mathfrak{p}_+, \mathbb{W}) = \frac{\ker(\partial^* \colon C_k \to C_{k-1})}{\operatorname{im}(\partial^* \colon C_{k+1} \to C_k)},$$

where $C_k = C_k(\mathfrak{p}_+, \mathbb{W}) = \bigwedge^k \mathfrak{p}_+ \otimes \mathbb{W}$. Note that, in addition to the chain spaces C_k , we have another two families of *P*-modules, namely $Z_k = \ker \partial^* \subset C_k$ and H_k . The vector bundles associated with C_k are $\Omega^k \otimes \mathcal{W}$, and we set $\mathcal{Z}_k := \mathcal{G} \times_P Z_k$ and $\mathcal{H}_k := \mathcal{G} \times_P H_k$. Then, the diagram that extends (4.7) will be

The definition of the BGG operators D_k is given by

$$(4.8) D_k = \operatorname{proj} \circ d^{\nabla} \circ L_k$$

where $L_k: \mathcal{H}_k \to \mathcal{Z}_k$ is some differential splitting operator. In order that (4.8) may make sense, it is necessary that the image of $d^{\nabla} \circ L_k$ is contained in \mathcal{Z}_{k+1} . General constructions of such L_k are given by [14] and [6]. However, we do not need to use those constructions of L_k because it is known that the requirement we just mentioned also gives the characterization of L_k , as pointed out by Čap [8]. Hammerl–Somberg–Souček–Šilhan [23, Theorem 3.1] summarizes this as follows.

Proposition 4.9. Let E_k be a differential operator from $\Omega^k \otimes W$ to $\Omega^{k+1} \otimes W$ of homogeneity 0 with the property that the associated graded map coincides with $\operatorname{gr} \partial$. Then for every $\sigma \in \mathcal{H}_k$, there exists a unique element $s \in \mathcal{Z}_k$ with $\sigma = [s]$ and $E_k s \in \mathcal{Z}_{k+1}$. Moreover, the mapping $L_k: \sigma \mapsto s$ is given by a differential operator.

The definition of the BGG operators D_k is completed by applying Proposition 4.9 to the operator $E_k = d^{\nabla}$.

It is sometimes the case that the tractor connection ∇ happens to be a prolongation of the associated first BGG operator D_0 , which basically means that the system of differential equations $\nabla s = 0$, where $s \in \mathcal{W}$, can be recovered by extending the system $D_0 f = 0$, where $f \in \mathcal{H}_0$, by adjoining its trivial consequences. In this case, it follows that ker D_0 is in one-toone correspondence with ker ∇ , which often provides some geometric insight toward the space under study, because in many settings D_0 admits a down-to-earth geometric interpretation. Such examples and non-examples are overviewed by Hammerl–Somberg–Souček–Šilhan [23, Section 5].

The same relationship can also happen for other differential operators $E_0: \mathcal{W} \to \Omega^1 \otimes \mathcal{W}$ satisfying the assumption of Proposition 4.9 and its associated first BGG operator. In particular, the following fact regarding the first BGG operator $D_0^{\tilde{\nabla}}$ associated with the modified adjoint tractor connection $\tilde{\nabla}$, which is well-defined by Proposition 4.7 and which we call the *modified* first adjoint BGG operator, is proved in [23, Section 5.4] (or Hammerl [22, Section 4.3]).

Theorem 4.10. For any normal regular parabolic geometry (\mathcal{G}, ω) , the modified adjoint tractor connection $\tilde{\nabla}$ is always a prolongation of the associated first BGG operator $D_0^{\tilde{\nabla}}$.

Now let us turn to CR geometry, and recall from Section 3 that the CR Killing operator $D: \operatorname{Re} \mathcal{E}(1,1) \to \operatorname{Re}(\mathcal{E}_{(\alpha\beta)}(1,1) \oplus \mathcal{E}_{(\overline{\alpha\beta})}(1,1))$ is an operator describing trivial deformations of compatible almost CR structures induced by contact Hamiltonian vector fields. In particular, ker D is the space of infinitesimal symmetries. On the other hand, Theorem 4.10 implies that the modified first adjoint BGG operator $D_0^{\overline{\nabla}}$ associated with the CR normal regular Cartan geometry (\mathcal{G}, ω) shares the same property that ker $D_0^{\overline{\nabla}}$ is the space of infinitesimal principal bundle automorphisms of \mathcal{G} . But in any case, this observation strongly suggests that $D_0^{\overline{\nabla}}$ is equal to D (perhaps up to some nonzero constant factor), which is indeed the case as we shall see in Section 7 (without any factor, thanks to our normalization used in (1.2)).

Another point of interest is whether $D_0^{\tilde{\nabla}}$ is actually different from the original (i.e., unmodified) first adjoint BGG operator D_0^{∇} . The following theorem regarding this matter is due to Čap [9, 3.5 Theorem].

Theorem 4.11. If (\mathcal{G}, ω) is a torsion-free normal regular parabolic geometry and the homology $H_1(\mathfrak{p}_+, \mathfrak{g})$ is concentrated in non-positive homogeneity degrees, then $D_0^{\tilde{\nabla}} = D_0^{\nabla}$.

However, in CR geometry, the normal regular parabolic geometry (\mathcal{G}, ω) associated with a compatible almost CR manifold (M, H, J) by Theorem 4.8 is torsion-free only if (M, H, J) is integrable, as we shall see in Section 6. Therefore, in the non-integrable case, Theorem 4.11 does not guarantee that $D_0^{\nabla} = D_0^{\nabla}$. Our conclusion in Section 7 is going to be that they are actually not the same.

5. LIE ALGEBRA HOMOLOGY RELEVANT TO CR GEOMETRY

Hereafter \mathfrak{g} denotes $\mathfrak{su}(n+1,1)$, the special unitary algebra of indefinite signature (n+1,1), and we consider the parabolic subalgebra \mathfrak{p} associated with a certain [2]-grading of \mathfrak{g} (see (5.4)), which corresponds to geometry of compatible almost CR structures. In order to specialize the general theory outlined in the previous section to this case, in this section we express the Lie algebra homology $H_k(\mathfrak{p}_+, \mathbb{W})$ and the relevant Kostant codifferential ∂^* in explicit terms when \mathbb{W} is the standard representation $\mathbb{V} = \mathbb{C}^{n+1,1}$ or the adjoint representation \mathfrak{g} , and for k = 0, 1.

It suffices to treat the both representations simply as \mathfrak{g} -modules in this section, but as group representations we later need to consider \mathbb{V} as a G^{\sharp} -module, while \mathfrak{g} can be treated as a Gmodule, where $G^{\sharp} = SU(n+1,1)$ and G = PSU(n+1,1). In this article, parabolic geometries

or infinitesimal flag structures are said to be corresponding to geometry of compatible almost CR structures or simply of CR type when they are of type (G, P) or (G^{\sharp}, P^{\sharp}) , where P and P^{\sharp} are the parabolic subgroups defined in Section 6.2.

5.1. **Preliminaries.** We regard $\mathfrak{g} = \mathfrak{su}(n+1,1)$ as the Lie algebra of the special unitary group associated with the indefinite Hermitian inner product of \mathbb{C}^{n+2} given by

(5.1)
$$\begin{pmatrix} & 1 \\ I & \\ 1 & \end{pmatrix},$$

where I is the $n \times n$ identity matrix. It is easily seen that

$$\mathfrak{g} = \left\{ \begin{array}{ccc} a & Z & iz \\ X & A & -Z^* \\ ix & -X^* & -\overline{a} \end{array} \right) \left| \begin{array}{c} x, z \in \mathbb{R}, X \in \mathbb{C}^n, Z \in (\mathbb{C}^n)^*, \\ A \in \mathfrak{u}(n), a \in \mathbb{C}, a + \operatorname{tr} A - \overline{a} = 0 \end{array} \right\},$$

where \mathbb{C}^n and $(\mathbb{C}^n)^*$ denote the set of column vectors and that of row vectors, respectively, and * on the upper right of X^* and Z^* indicates the conjugate transpose. With index notation, we can also express elements of \mathfrak{g} as

(5.2)
$$\begin{pmatrix} a & Z_{\beta} & iz \\ X^{\alpha} & A_{\beta}^{\alpha} & -Z^{\alpha} \\ ix & -X_{\beta} & -\overline{a} \end{pmatrix}$$

by setting

$$X^{\overline{\alpha}} = \overline{X^{\alpha}}, \qquad Z_{\overline{\beta}} = \overline{Z_{\beta}}, \qquad X_{\beta} = h_{\beta\overline{\alpha}}X^{\overline{\alpha}}, \qquad Z^{\alpha} = h^{\alpha\overline{\beta}}Z_{\overline{\beta}},$$

where

(5.3)
$$h_{\alpha\overline{\beta}} = h^{\alpha\overline{\beta}} = \begin{cases} 1, & \alpha = \beta, \\ 0, & \text{otherwise} \end{cases}$$

We also use the complexification $\tilde{\mathfrak{g}}$ of \mathfrak{g} . Note that $\tilde{\mathfrak{g}}$ equals $\mathfrak{sl}(n+2,\mathbb{C})$, the set of complex trace-free matrices, with complex conjugation relative to the real form \mathfrak{g} . That is, if we express a general element of $\tilde{\mathfrak{g}}$ as

$$\begin{pmatrix} a & Z_{\beta} & iz \\ X^{\alpha} & A_{\beta}^{\alpha} & -W^{\alpha} \\ ix & -Y_{\beta} & -b \end{pmatrix},$$

where $x, z \in \mathbb{C}, X, W \in \mathbb{C}^n, Y, Z \in (\mathbb{C}^n)^*, A \in \mathfrak{gl}(n, \mathbb{C}), a, b \in \mathbb{C}$ with $a + \operatorname{tr} A - b = 0$, then

$$\begin{pmatrix} a & Z_{\beta} & iz \\ X^{\alpha} & A_{\beta}^{\alpha} & -W^{\alpha} \\ ix & -Y_{\beta} & -b \end{pmatrix} = \begin{pmatrix} \overline{b} & W_{\beta} & i\overline{z} \\ Y^{\alpha} & -A^{\alpha}{}_{\beta} & -Z^{\alpha} \\ i\overline{x} & -X_{\beta} & -\overline{a} \end{pmatrix},$$

where

$$X^{\overline{\alpha}} = \overline{X^{\alpha}}, \qquad Y_{\overline{\beta}} = \overline{Y_{\beta}}, \qquad Z_{\overline{\beta}} = \overline{Z_{\beta}}, \qquad W^{\overline{\alpha}} = \overline{W^{\alpha}}, \qquad A_{\overline{\beta}}^{\overline{\alpha}} = \overline{A_{\beta}^{\alpha}}$$

and indices are lowered/raised by (5.3).

We endow the Lie algebra \mathfrak{g} with the |2|-grading

(5.4)
$$\mathfrak{g} = \mathfrak{g}_{-2} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_0 \oplus \mathfrak{g}_1 \oplus \mathfrak{g}_2$$

given by the grading element

(5.5)
$$E = \begin{pmatrix} 1 & & \\ & O & \\ & & -1 \end{pmatrix}.$$

The subscript *i* of \mathfrak{g}_i , which is the eigenvalue of ad *E* on \mathfrak{g}_i , equals the distance from the diagonal of the (possibly) non-zero entries of its elements in the block form (5.2). That is,

$$\begin{pmatrix} & & \\ ix & & \\ & & \\ & & \\ & & \\ & & \begin{pmatrix} X^{\alpha} & \\ & -X_{\beta} & \\ & & -\overline{a} \end{pmatrix}, \quad \begin{pmatrix} a & & \\ & A_{\beta}{}^{\alpha} & \\ & & -\overline{a} \end{pmatrix}, \\ \begin{pmatrix} & & Z_{\beta} & \\ & & -Z^{\alpha} \end{pmatrix}, \quad \begin{pmatrix} & & iz \\ & & \\ & & \end{pmatrix}$$

are the elements of \mathfrak{g}_{-2} , \mathfrak{g}_{-1} , \mathfrak{g}_0 , \mathfrak{g}_1 , and \mathfrak{g}_2 , respectively.

Following the general notation used in Section 4, we write

$$\mathfrak{g}_{-}=\mathfrak{g}_{-2}\oplus\mathfrak{g}_{-1},\qquad \mathfrak{p}=\mathfrak{g}_{0}\oplus\mathfrak{g}_{1}\oplus\mathfrak{g}_{2},\qquad \mathfrak{p}_{+}=\mathfrak{g}_{1}\oplus\mathfrak{g}_{2}.$$

The complexification of the |2|-grading is expressed as $\tilde{\mathfrak{g}} = \tilde{\mathfrak{g}}_{-2} \oplus \tilde{\mathfrak{g}}_{-1} \oplus \tilde{\mathfrak{g}}_0 \oplus \tilde{\mathfrak{g}}_1 \oplus \tilde{\mathfrak{g}}_2$, and $\tilde{\mathfrak{g}}_-, \tilde{\mathfrak{p}}_+$ denote the complexification of their untilded counterparts.

We introduce the basis $\xi_0, \xi_1, \ldots, \xi_n, \xi_{\overline{1}}, \ldots, \xi_{\overline{n}}$ of $\tilde{\mathfrak{g}}_-$ by

(5.6)
$$\xi_0 = \begin{pmatrix} & & \\ i & & \end{pmatrix}, \quad \xi_{\sigma} = \begin{pmatrix} \delta_{\sigma}^{\ \alpha} & & \\ & 0 & \end{pmatrix}, \quad \xi_{\overline{\sigma}} = \begin{pmatrix} 0 & & \\ & -h_{\beta\overline{\sigma}} & \end{pmatrix},$$

and the basis $\zeta^0, \zeta^1, \ldots, \zeta^n, \zeta^{\overline{1}}, \ldots, \zeta^{\overline{n}}$ of $\tilde{\mathfrak{p}}_+$ by

$$\zeta^{0} = \begin{pmatrix} & & i \\ & & \end{pmatrix}, \qquad \zeta^{\sigma} = \begin{pmatrix} & \delta_{\beta}{}^{\sigma} & \\ & & 0 \end{pmatrix}, \qquad \zeta^{\overline{\sigma}} = \begin{pmatrix} & 0 & \\ & & -h^{\alpha \overline{\sigma}} \end{pmatrix}.$$

Note that ξ_0 and ζ^0 are real elements, which belong to \mathfrak{g}_{-2} and \mathfrak{g}_2 , respectively. The vectors ξ_{σ} , $\xi_{\overline{\sigma}} \in \tilde{\mathfrak{g}}_{-1}$ are the complex conjugates of each other, and so are ζ^{σ} , $\zeta^{\overline{\sigma}} \in \tilde{\mathfrak{g}}_1$.

Lemma 5.1. \mathfrak{g}_0 contains no nontrivial ideals of \mathfrak{g} .

Proof. Suppose that I is an ideal of \mathfrak{g} contained in \mathfrak{g}_0 . Then, since (5.4) is a grading, any element

$$F = \begin{pmatrix} a & & \\ & A_{\beta}{}^{\alpha} & \\ & & -\overline{a} \end{pmatrix} \in I$$

must satisfy $[F, \xi_0] = [F, \xi_\sigma] = 0$. Then $\operatorname{Re} a = 0$ and $A_\beta{}^\alpha - a\delta_\beta{}^\alpha = 0$ follow, and consequently, F is of the form

$$F = \begin{pmatrix} ic & & \\ & ic \delta_{\beta}{}^{\alpha} & \\ & & ic \end{pmatrix}, \qquad c \in \mathbb{R}.$$

However, since $F \in \mathfrak{g}_0$ we have c = 0, and hence I = 0.

Since (5.4) is a grading, the Killing form B of $\tilde{\mathfrak{g}}$ vanishes on $\tilde{\mathfrak{g}}_i \times \tilde{\mathfrak{g}}_j$ unless i + j = 0. It can be easily seen that, on $\tilde{\mathfrak{g}}_{-2} \times \tilde{\mathfrak{g}}_2$ and on $\tilde{\mathfrak{g}}_{-1} \times \tilde{\mathfrak{g}}_1$, we have

$$B(\xi_0, \zeta^0) = -2(n+2)$$

and

$$B(\xi_{\sigma},\zeta^{\tau}) = 2(n+2)\delta_{\sigma}^{\tau}, \qquad B(\xi_{\overline{\sigma}},\zeta^{\overline{\tau}}) = 2(n+2)\delta_{\overline{\sigma}}^{\overline{\tau}}, \qquad B(\xi_{\overline{\sigma}},\zeta^{\overline{\tau}}) = B(\xi_{\overline{\sigma}},\zeta^{\tau}) = 0.$$

Consequently, the dual basis of $\tilde{\mathfrak{p}}_+$ to the basis ξ_0 , ξ_{σ} , $\xi_{\overline{\sigma}}$ of $\tilde{\mathfrak{g}}_-$ with respect to B is given by

(5.7)
$$\xi_0^* = -\frac{1}{2(n+2)}\zeta^0, \qquad \xi_\sigma^* = \frac{1}{2(n+2)}\zeta^\sigma, \qquad \xi_{\overline{\sigma}}^* = \frac{1}{2(n+2)}\zeta^{\overline{\sigma}}.$$

The dual basis (5.7) can be used in computations of the action of the Kostant codifferential (4.3) on $C_k(\mathfrak{p}_+, \mathbb{W})$, identified with $\bigwedge^k (\mathfrak{g}/\mathfrak{p})^* \otimes \mathbb{W}$ by the Killing form B, as follows. For k = 1, we have for $\psi \in (\mathfrak{g}/\mathfrak{p})^* \otimes \mathbb{W}$

(5.8)
$$\partial^* \psi = \sum_A \xi_A^* \cdot \psi(\xi_A),$$

where A runs through $\{0, 1, \ldots, n, \overline{1}, \ldots, \overline{n}\}$. Indeed, (5.8) follows from $\partial^*(\xi_A^* \otimes w) = \xi_A^* \cdot w$, which is correct by (4.3). Similarly, for $\phi \in \bigwedge^2(\mathfrak{g}/\mathfrak{p})^* \otimes \mathbb{W}$ one has

(5.9)
$$\partial^* \phi(X) = 2 \sum_A [\xi_A^*, \phi(X, \xi_A)] - \sum_A \phi([\xi_A^*, X], \xi_A), \qquad X \in \mathfrak{g/p}.$$

This formula appears in [13, Lemma 3.1.11].

5.2. Filtration of the standard and the adjoint representations. Corresponding to the block form (5.2) of elements of \mathfrak{g} , those of the standard representation $\mathbb{V} = \mathbb{C}^{n+2}$ of \mathfrak{g} can be expressed as

(5.10)
$$\begin{pmatrix} s \\ t^{\alpha} \\ u \end{pmatrix},$$

which corresponds to the eigendecomposition

$$\mathbb{V} = \mathbb{V}_1 \oplus \mathbb{V}_0 \oplus \mathbb{V}_{-1}$$

induced by the grading element (5.5). The associated p-invariant filtration is

$$\mathbb{V} = \mathbb{V}^{-1} \supset \mathbb{V}^0 \supset \mathbb{V}^1,$$

where

$$\mathbb{V}^0 = \mathbb{V}_0 \oplus \mathbb{V}_1 = \left\{ \begin{pmatrix} s \\ t^{\alpha} \\ 0 \end{pmatrix} \right\}, \qquad \mathbb{V}^1 = \mathbb{V}_1 = \left\{ \begin{pmatrix} s \\ 0 \\ 0 \end{pmatrix} \right\}.$$

Note that $\mathbb V$ carries the $\mathfrak g\text{-invariant}$ in definite Hermitian inner product

(5.11)
$$\left\langle \begin{pmatrix} s \\ t^{\alpha} \\ u \end{pmatrix}, \begin{pmatrix} s' \\ t'^{\alpha} \\ u' \end{pmatrix} \right\rangle = s\overline{u}' + \sum_{\alpha=1}^{n} t^{\alpha} \overline{t'^{\alpha}} + u\overline{s}'.$$

The p-module $\mathbb{V}^1 = \mathbb{V}_1$ is denoted by E(-1,0), in view of the fact that its associated tractor bundle can be identified with the density bundle $\mathcal{E}(-1,0)$, as we see in Section 6. We set

$$E(1,0) = E(-1,0)^*, \qquad E(0,1) = \overline{E(1,0)}$$

and

$$E(w,w') = E(1,0)^{\otimes w} \otimes E(0,1)^{\otimes w'}.$$

The inner product (5.11) induces a duality between $\operatorname{gr}_{-1}(\mathbb{V}) = \mathbb{V}/\mathbb{V}^0$ and $\overline{\mathbb{V}}^1$. Consequently,

which means that the bottom component u of (5.10), which is regarded as representing an equivalence class in \mathbb{V}/\mathbb{V}^0 in this context, can be regarded as an element of E(0,1).

Next, we define the \mathfrak{p} -module E^{α} to be $\operatorname{gr}_0(\mathbb{V}) \otimes E(1,0)$. Then

$$\operatorname{gr}_0(\mathbb{V}) \cong E^{\alpha}(-1,0),$$

where we write $E^{\alpha}(w, w') = E^{\alpha} \otimes E(w, w')$. This means that the second component t^{α} of

(5.13)
$$\begin{pmatrix} s \\ t^{\alpha} \\ 0 \end{pmatrix},$$

representing an equivalence class in $\mathbb{V}^0/\mathbb{V}^1$, can be regarded as an element of $E^{\alpha}(-1,0)$. The inner product (5.11) naturally induces a positive-definite Hermitian inner product $\operatorname{gr}_0(\mathbb{V}) \times \operatorname{gr}_0(\mathbb{V}) \to \mathbb{C}$, and hence a canonical complex bilinear mapping

$$E^{\alpha} \times E^{\overline{\beta}} \to E(1,1),$$

which we write

(5.14)
$$h_{\alpha\overline{\beta}} \in E_{\alpha\overline{\beta}}(1,1).$$

Indeed, this pairing will induce the weighted Levi form of compatible almost CR structures.

The complexified adjoint representation $\tilde{\mathfrak{g}} = \mathfrak{sl}(n+2)$ is isomorphic to the trace-free part of $\operatorname{End}(\mathbb{V}) = \mathbb{V}^* \otimes \mathbb{V}$, and the associated graded module of $\operatorname{End}(\mathbb{V})$ is decomposed as

$$\begin{pmatrix} E & E_{\beta} & E(-1,-1) \\ E^{\alpha} & E_{\beta}^{\alpha} & E^{\alpha}(-1,-1) \\ E(1,1) & E_{\beta}(1,1) & E \end{pmatrix},$$

where E is the trivial representation. Consequently, we have the isomorphisms of \mathfrak{p} -modules

$$gr_{2}(\tilde{\mathfrak{g}}) = \tilde{\mathfrak{g}}^{2} \cong E(-1, -1),$$

$$gr_{1}(\tilde{\mathfrak{g}}) = \tilde{\mathfrak{g}}^{1}/\tilde{\mathfrak{g}}^{2} \cong E_{\beta} \oplus E^{\alpha}(-1, -1) \cong E_{\beta} \oplus E_{\overline{\alpha}}$$

$$gr_{0}(\tilde{\mathfrak{g}}) = \tilde{\mathfrak{g}}^{0}/\tilde{\mathfrak{g}}^{1} \cong E \oplus E \oplus \text{tf } E_{\beta}{}^{\alpha},$$

$$gr_{-1}(\tilde{\mathfrak{g}}) = \tilde{\mathfrak{g}}^{-1}/\tilde{\mathfrak{g}}^{0} \cong E^{\alpha} \oplus E_{\beta}(1, 1) \cong E^{\alpha} \oplus E^{\overline{\beta}},$$

$$gr_{-2}(\tilde{\mathfrak{g}}) = \tilde{\mathfrak{g}}/\tilde{\mathfrak{g}}^{-1} \cong E(1, 1).$$

In particular, if the vectors in (5.6) are understood as representing equivalence classes in $\tilde{\mathfrak{g}}/\tilde{\mathfrak{p}}$, then the first (resp. the second) summand of $\operatorname{gr}_{-1}(\tilde{\mathfrak{g}}) = \tilde{\mathfrak{g}}^{-1}/\tilde{\mathfrak{p}} = E^{\alpha} \oplus E^{\overline{\beta}}$ is spanned by ξ_{σ} (resp. by $\xi_{\overline{\sigma}}$). 5.3. Homology of \mathfrak{p}_+ with values in the standard representation. Based on the block form (5.10) for the standard representation \mathbb{V} , elements of $C_k(\mathfrak{p}_+, \mathbb{V})$, which are identified with elements of $\bigwedge^k(\mathfrak{g}/\mathfrak{p})^* \otimes \mathbb{V}$, will be denoted as

$$\begin{pmatrix} s_{A_1\cdots A_k} \\ t^{\alpha}_{A_1\cdots A_k} \\ u_{A_1\cdots A_k} \end{pmatrix}$$

using the basis (5.6), where each A_i is an index running through $\{0, 1, \ldots, n, \overline{1}, \ldots, \overline{n}\}$. Sometimes the indices $A_1 \cdots A_k$ in this notation will be suppressed, in which case we will use care so that any confusion does not occur.

Then, for an element of $C_1(\mathfrak{p}_+, \mathbb{V})$, (5.8) implies that the action of ∂^* is given by

$$\partial^* \begin{pmatrix} s \\ t^{\alpha} \\ u \end{pmatrix} = \frac{1}{2(n+2)} \begin{pmatrix} -iu_0 + t^{\gamma} \\ -u^{\alpha} \\ 0 \end{pmatrix}.$$

For an element of $C_2(\mathfrak{p}_+, \mathbb{V})$, we have from (5.9) that

$$\begin{pmatrix} \partial^* \begin{pmatrix} s \\ u \end{pmatrix} \end{pmatrix} (\xi_0) = \frac{1}{2(n+2)} \begin{pmatrix} t^{\gamma}_{0\gamma} + is_{\gamma}^{\gamma} \\ -u_0^{\alpha} + it^{\alpha}_{\gamma}^{\gamma} \\ iu_{\gamma}^{\gamma} \end{pmatrix},$$

$$\begin{pmatrix} \partial^* \begin{pmatrix} s \\ u \end{pmatrix} \end{pmatrix} (\xi_{\sigma}) = \frac{1}{2(n+2)} \begin{pmatrix} iu_{0\sigma} + t^{\gamma}_{\sigma\gamma} \\ -u_{\sigma}^{\alpha} \\ 0 \end{pmatrix},$$

$$\begin{pmatrix} \partial^* \begin{pmatrix} s \\ u \\ u \end{pmatrix} \end{pmatrix} (\xi_{\overline{\sigma}}) = \frac{1}{2(n+2)} \begin{pmatrix} iu_{0\overline{\sigma}} + t^{\gamma}_{\overline{\sigma}\gamma} \\ -u_{\overline{\sigma}}^{\alpha} \\ 0 \end{pmatrix}.$$

These computations can be used to identify the homology groups $H_0(\mathfrak{p}_+, \mathbb{V})$ and $H_1(\mathfrak{p}_+, \mathbb{V})$ as follows. The zeroth homology is given by

$$H_0(\mathfrak{p}_+,\mathbb{V}) = \mathbb{V}/\operatorname{im} \partial_1^* = \mathbb{V}/\mathbb{V}^0 \cong E(0,1),$$

where the last identification is nothing but (5.12). As mentioned after (5.12), we can regard the bottom component u of the vector (5.10) in the standard representation \mathbb{V} as an element of E(0,1) by identifying u with the equivalence class of the vector (5.10). Using this interpretation, we can express the projection $\mathbb{V} \to H_0(\mathfrak{p}_+, \mathbb{V}) \cong E(0,1)$ as, in fact tautologically,

$$\begin{pmatrix} s \\ t^{\alpha} \\ u \end{pmatrix} \mapsto u$$

The first homology is

$$H_{1}(\mathfrak{p}_{+},\mathbb{V}) = \frac{\ker \partial_{1}^{*}}{\operatorname{im} \partial_{2}^{*}} = \frac{\left\{ \begin{pmatrix} s_{A} \\ t_{A}^{\alpha} \\ u_{A} \end{pmatrix} \middle| u_{\overline{\sigma}} = 0, u_{0} = -it^{\gamma}{}_{\gamma} \right\}}{\left\{ \begin{pmatrix} s_{A} \\ t_{A}^{\alpha} \\ u_{A} \end{pmatrix} \middle| u_{\sigma} = u_{\overline{\sigma}} = 0, u_{0} = -it^{\gamma}{}_{\gamma}, t_{\overline{\sigma}\overline{\tau}} = t_{[\overline{\sigma}\overline{\tau}]} \right\}}$$
$$\cong \left\{ (u_{\sigma}) \right\} \oplus \left\{ (t^{\alpha}{}_{\overline{\beta}}) \mid t_{\overline{\alpha}\overline{\beta}} = t_{\overline{\beta}\overline{\alpha}} \right\} \cong E_{\sigma}(0,1) \oplus E_{(\overline{\alpha}\overline{\beta})}(0,1),$$

$$\begin{pmatrix} s_A \\ t^{\alpha}_A \\ u_A \end{pmatrix} \mapsto (u_{\sigma}) \quad \text{and} \quad \begin{pmatrix} s_A \\ t^{\alpha}_A \\ u_A \end{pmatrix} \mapsto (t_{(\overline{\alpha}\overline{\beta})}).$$

To understand the latter, i.e., to see that the component $(t_{(\overline{\alpha\beta})})$ of any element of ker ∂_1^* can be regarded as an element of $E_{(\overline{\alpha\beta})}(0,1)$, one must note that $u_{\overline{\sigma}} = 0$. By this, and by recalling (5.13), we can regard the middle component of the $A = \overline{\sigma}$ part

$$\begin{pmatrix} s_{\overline{\sigma}} \\ t^{\alpha}_{\overline{\sigma}} \\ 0 \end{pmatrix}$$

of any element of ker ∂_1^* as giving an element of $E^{\alpha}_{\overline{\sigma}}(-1,0)$. Then, by lowering an index using (5.14) and taking the symmetric part, we arrive at the conclusion that $(t_{(\overline{\alpha}\overline{\beta})})$ is interpretable as an element of $E_{(\overline{\alpha}\overline{\beta})}(0,1)$.

5.4. Homology of \mathfrak{p}_+ with values in the adjoint representation. Following the manner used in the previous subsection, elements of $C_k(\mathfrak{p}_+,\mathfrak{g})$, which are identified with elements of $\bigwedge^k(\mathfrak{g}/\mathfrak{p})^* \otimes \mathfrak{g}$, will be expressed as

(5.15)
$$\begin{pmatrix} a_{A_1\cdots A_k} & Z_{\beta A_1\cdots A_k} & i z_{A_1\cdots A_k} \\ X^{\alpha}_{A_1\cdots A_k} & A_{\beta}^{\alpha}_{A_1\cdots A_k} & -Z^{\alpha}_{A_1\cdots A_k} \\ i x_{A_1\cdots A_k} & -X_{\beta A_1\cdots A_k} & -\overline{a}_{A_1\cdots A_k} \end{pmatrix}$$

based on (5.2). As before, the indices $A_1 \cdots A_k$ in this notation can be suppressed.

Then, for an element $\psi \in (\mathfrak{g}/\mathfrak{p})^* \otimes \mathfrak{g}$ expressed as (5.15), it follows from (5.8) that

$$\partial^*\psi = \frac{1}{2(n+2)} \begin{pmatrix} x_0 + X^{\gamma}_{\gamma} & iX_{\beta 0} + A^{\gamma}_{\beta} \gamma - a_{\beta} & i(a_0 + \overline{a}_0) + Z_{\gamma} \gamma - Z^{\gamma}_{\gamma} \\ -ix^{\alpha} & -X^{\alpha}_{\ \beta} + X_{\beta}^{\ \alpha} & iX^{\alpha}_{\ 0} + \overline{a}^{\alpha} + A_{\gamma}^{\ \alpha\gamma} \\ 0 & -ix_{\beta} & -x_0 - X_{\gamma}^{\gamma} \end{pmatrix}.$$

Likewise, for $\phi \in \bigwedge^2 (\mathfrak{g}/\mathfrak{p})^* \otimes \mathfrak{g}$, (5.9) implies that

$$\begin{aligned} (\partial^*\phi)(\xi_{\sigma}) &= \frac{1}{2(n+2)} \begin{pmatrix} X^{\gamma}_{\sigma\gamma} - x_{0\sigma} & A_{\beta}^{\gamma}_{\sigma\gamma} - iX_{\beta0\sigma} - a_{\sigma\beta} & Z_{\gamma\sigma}^{\gamma} - Z^{\gamma}_{\sigma\gamma} - ia_{0\sigma} - i\overline{a}_{0\sigma} \\ -ix_{\sigma}^{\alpha} & -X^{\alpha}_{\sigma\beta} + X_{\beta\sigma}^{\alpha} & A_{\gamma}^{\alpha}_{\sigma\gamma}^{\gamma} - iX^{\alpha}_{0\sigma} + \overline{a}_{\sigma}^{\alpha} \\ 0 & -ix_{\sigma\beta} & -X_{\gamma\sigma}^{\gamma} + x_{0\sigma} \end{pmatrix}, \\ (\partial^*\phi)(\xi_{\sigma}) &= \frac{1}{2(n+2)} \begin{pmatrix} X^{\gamma}_{\overline{\sigma}\gamma} - x_{0\overline{\sigma}} & A_{\beta}^{\gamma}_{\overline{\sigma}\gamma} - iX_{\beta0\overline{\sigma}} - a_{\overline{\sigma}\beta} & Z_{\gamma\overline{\sigma}}^{\gamma} - Z^{\gamma}_{\overline{\sigma}\gamma} - ia_{0\overline{\sigma}} - i\overline{a}_{0\overline{\sigma}} \\ -ix_{\overline{\sigma}}^{\alpha} & -X^{\alpha}_{\overline{\sigma}\beta} + X_{\beta\overline{\sigma}}^{\alpha} & A_{\gamma}^{\alpha}_{\overline{\sigma}}^{\gamma} - iX^{\alpha}_{0\overline{\sigma}} + \overline{a}_{\overline{\sigma}}^{\alpha} \\ 0 & -ix_{\overline{\sigma}\beta} & -X_{\gamma\overline{\sigma}}^{\gamma} + x_{0\overline{\sigma}} \end{pmatrix}, \\ (\partial^*\phi)(\xi_0) &= \frac{1}{2(n+2)} \begin{pmatrix} X^{\gamma}_{0\gamma} + ia_{\gamma}^{\gamma} & iZ_{\beta\gamma}^{\gamma} + A_{\beta}^{\gamma}_{0\gamma} - a_{0\beta} & -z_{\gamma}^{\gamma} + Z_{\gamma0}^{\gamma} - Z^{\gamma}_{0\gamma} \\ i(X^{\alpha}_{\gamma}^{\gamma} - x_{0}^{\alpha}) & iA_{\beta}^{\alpha}_{\gamma}^{\gamma} - X^{\alpha}_{0\beta} + X_{\beta0}^{\alpha} & -iZ^{\alpha}_{\gamma}^{\gamma} + A_{\gamma}^{\alpha}_{0}^{\gamma} + \overline{a}_{0}^{\alpha} \\ -x_{\gamma}^{\gamma} & -i(X_{\beta\gamma}^{\gamma} + x_{0\beta}) & -X_{\gamma0}^{\gamma} - i\overline{a}_{\gamma}^{\gamma} \end{pmatrix}. \end{aligned}$$

It follows that the zeroth homology is

$$H_0(\mathfrak{p}_+,\mathfrak{g}) = \mathfrak{g}/\operatorname{im} \partial_1^* = \mathfrak{g}/\mathfrak{g}^{-1} \cong \operatorname{Re} E(1,1),$$

where the projection $\mathfrak{g} \to \operatorname{Re} E(1,1)$ is given by

$$\begin{pmatrix} a & Z_{\beta} & iz \\ X^{\alpha} & A_{\beta}^{\alpha} & -Z^{\alpha} \\ ix & -X_{\beta} & -\overline{a} \end{pmatrix} \mapsto x.$$

The first homology can be computed as

$$H_{1}(\mathfrak{p}_{+},\mathfrak{g}) = \frac{\ker \partial_{1}^{*}}{\operatorname{im} \partial_{2}^{*}} = \frac{\left\{ \begin{pmatrix} a_{A} & Z_{\beta A} & iz_{A} \\ X_{A}^{\alpha} & A_{\beta}^{\alpha} A & -Z_{A}^{\alpha} \\ ix_{A} & -X_{\beta A} & -\overline{a}_{A} \end{pmatrix} \middle| \begin{array}{l} x_{\sigma} = x_{\overline{\sigma}} = 0, \, x_{0} = -X_{\gamma}^{\gamma}, \\ X_{0}^{\alpha} = iA_{\gamma}^{\alpha\gamma} + i\overline{a}^{\alpha}, \\ a_{0} + \overline{a}_{0} = iZ_{\gamma}^{\gamma} - iZ^{\gamma} \end{pmatrix} \right\}}{\left\{ \begin{pmatrix} a_{A} & Z_{\beta A} & iz_{A} \\ X_{A}^{\alpha} & A_{\beta}^{\alpha} A & -Z^{\alpha} \\ ix_{A} & -X_{\beta A} & -\overline{a}_{A} \end{pmatrix} \middle| \begin{array}{l} x_{\sigma} = x_{\overline{\sigma}} = 0, \, x_{0} = -X^{\gamma}, \\ X_{\sigma\tau} = X_{[\sigma\tau]}, \\ X_{\sigma\tau} = X_{[\sigma\tau]}, \\ a_{0} + \overline{a}_{0} = iA_{\gamma}^{\alpha\gamma} + i\overline{a}^{\alpha}, \\ a_{0} + \overline{a}_{0} = iZ_{\gamma}^{\gamma} - iZ^{\gamma} \end{pmatrix} \right\}} \\ \cong \operatorname{Re}(\{ (X_{\overline{\beta}}) \mid X_{\overline{\alpha}\overline{\beta}} = X_{\overline{\beta}\overline{\alpha}} \} \oplus \{ (X_{\alpha\beta}) \mid X_{\alpha\beta} = X_{\beta\alpha} \}) \\ \cong \operatorname{Re}(E_{(\alpha\beta)}(1, 1) \oplus E_{(\overline{\alpha}\overline{\beta})}(1, 1)), \end{array}$$

where we define the projection ker $\partial_1^* \to \operatorname{Re}(E_{(\alpha\beta)}(1,1) \oplus E_{(\overline{\alpha\beta})}(1,1))$ by

$$\begin{pmatrix} a_A & Z_{\beta A} & iz_A \\ X^{\alpha}_{\ A} & A_{\beta}^{\alpha}_{\ A} & -Z^{\alpha}_{\ A} \\ ix_A & -X_{\beta A} & -\overline{a}_A \end{pmatrix} \mapsto (X_{(\alpha\beta)}, X_{(\overline{\alpha\beta})}).$$

Note that, in particular, $H_1(\mathfrak{p}_+,\mathfrak{g})$ is concentrated in (the equivalence classes of elements of) $\mathfrak{g}_1 \otimes \mathfrak{g}_{-1}$, and hence in homogeneity 0. Together with Lemma 5.1, this fact guarantees that Theorem 4.8 is applicable to regular infinitesimal flag structures of CR type.

6. Weyl structures and the CR normal Weyl forms

In this section and the next one, we will, for normal regular parabolic geometries of CR type, derive concrete formulae of the tractor connections associated with the standard representation \mathbb{V} and the adjoint representation \mathfrak{g} .

We are going to do so with the help of the general notion of Weyl structures of parabolic geometries (\mathcal{G}, ω) , which are by definition P_+ -equivariant sections $\sigma: \mathcal{G}_0 \to \mathcal{G}$ where $\mathcal{G}_0 = \mathcal{G}/P_+$ (see Čap–Slovák [13, Chapter 5]). A choice of a Weyl structure σ gives rise to the *induced Weyl* form $\sigma^*\omega \in \Omega^1(\mathcal{G}_0, \mathfrak{g})$, and by studying (normal) Weyl forms directly, one can effectively avoid using the original (normal) parabolic geometry in the description of tractor bundles, as we recall in the general setting in Section 6.1 following [13]. In Sections 6.2–6.4, we specialize in geometries of CR type and determine the normal Weyl form.

6.1. Tractor calculus in terms of Weyl forms. Let G be an arbitrary semisimple Lie group and P its parabolic subgroup. Recall the notion of infinitesimal flag structures of type (G, P)introduced in Section 4.4. Abstractly, Weyl forms of infinitesimal flag structures are defined as follows (see [13, Definition 5.2.1]).

Definition 6.1. A Weyl form of an infinitesimal flag structure $((T^i M)_{i=-k}^{-1}, \mathcal{G}_0, (\theta_{-k}, \dots, \theta_{-1}))$ of type (G, P) is a G_0 -invariant 1-form $\tau \in \Omega^1(\mathcal{G}_0, \mathfrak{g})$ such that

- (i) $\tau(\zeta_A) = A$ for $A \in \mathfrak{g}_0$, where ζ_A is the fundamental vector field;
- (ii) For $-k \leq i \leq -1$, $\tau|_{T^i \mathcal{G}_0}$ takes values in \mathfrak{g}^i and equals θ_i modulo \mathfrak{g}^{i+1} .

Given a Weyl structure σ of a parabolic geometry (\mathcal{G}, ω) , one can use the induced infinitesimal flag structure $((T^i M)_{i=-k}^{-1}, \mathcal{G}_0, (\theta_{-k}, \dots, \theta_{-1}))$ and the induced Weyl form $\tau = \sigma^* \omega$ to describe tractor bundles. First, if \mathbb{W} is a (\mathfrak{g}, P) -module, then the associated bundle is

$$\mathcal{W} = \mathcal{G} \times_P \mathbb{W} \cong \mathcal{G}_0 \times_{G_0} \mathbb{W},$$

the isomorphism being given by identifying $\llbracket g_0, w \rrbracket^{G_0}$ with $\llbracket \sigma(g_0), w \rrbracket^P$ (where $\llbracket \cdots \rrbracket$ denotes the equivalence class of (\cdots)). In order to describe the tractor connection ∇ using this σ -dependent expression $\mathcal{W} \cong \mathcal{G}_0 \times_{G_0} \mathbb{W}$, we need to introduce three objects related with the Weyl structure σ . Let

$$\sigma^*\omega = (\sigma^*\omega_-, \sigma^*\omega_0, \sigma^*\omega_+) \in \Omega^1(\mathcal{G}_0, \mathfrak{g}_-) \oplus \Omega^1(\mathcal{G}_0, \mathfrak{g}_0) \oplus \Omega^1(\mathcal{G}_0, \mathfrak{p}_+)$$

be the decomposition of the induced Weyl form $\sigma^*\omega$ with respect to $\mathfrak{g} = \mathfrak{g}_- \oplus \mathfrak{g}_0 \oplus \mathfrak{p}_+$. The middle part $\gamma^{\sigma} = \sigma^*\omega_0$ is a principal connection of \mathcal{G}_0 , which is called the Weyl connection. The negative part $\sigma^*\omega_-$ is the soldering form, which defines an isomorphism $T_{p(u)}M \cong \mathfrak{g}_-$ for each $u \in \mathcal{G}_0$, where $p: \mathcal{G}_0 \to M$ is the projection. The positive part $\mathsf{P}^{\sigma} = \sigma^*\omega_+$ is called the *Rho* tensor. Then it is known that ∇ can be expressed as follows.

Proposition 6.2 ([13, Proposition 5.1.10]). Let σ be a Weyl structure of a parabolic geometry (\mathcal{G}, ω) . Then the tractor connection of $\mathcal{W} = \mathcal{G} \times_P \mathbb{W} \cong \mathcal{G}_0 \times_{\mathcal{G}_0} \mathbb{W}$ is given by

$$\nabla_{\xi} s = \nabla^{\sigma}_{\xi} s + \mathsf{P}^{\sigma}(\xi) \cdot s + \xi \cdot s$$

for a vector field ξ , where ∇^{σ} denotes the covariant differentiation with respect to the Weyl connection γ^{σ} and, in the last term on the right-hand side, ξ is identified with a \mathfrak{g}_{-} -valued function by the soldering form $\sigma^*\omega_{-}$.

It is crucially important in this approach to know that, for normal regular parabolic geometries, we can characterize the Weyl form $\tau = \sigma^* \omega$ induced by some Weyl structure σ directly at the level of the infinitesimal flag structure. For an arbitrary Weyl form τ of the induced regular infinitesimal flag structure (or of an infinitesimal flag structure in general), its *curvature form* $K \in \Omega^2(\mathcal{G}_0, \mathfrak{g})$ is defined by

$$K = d\tau + \frac{1}{2}[\tau \wedge \tau],$$

and, since $TM \cong \mathcal{G}_0 \times_{G_0} \mathfrak{g}_-$, the curvature K is equivalently expressed by the curvature function $\kappa: \mathcal{G}_0 \to \bigwedge^2 \mathfrak{g}_- \otimes \mathfrak{g}$. Then τ is said to be normal if $\partial^* \kappa = 0$ is satisfied. Under the assumption that $H^1(\mathfrak{g}_-, \mathfrak{g})$ is concentrated in non-positive homogeneity degrees (cf. Theorem 4.8), the normality is in fact a necessary and sufficient condition for τ being induced by some Weyl structure [13, Theorem 5.2.2]. Therefore, in order to compute the normal tractor connections explicitly, it just suffices to investigate normal Weyl forms of the induced infinitesimal flag structure.

6.2. Frame bundles in CR geometry and the Tanaka–Webster connection. We next discuss how the geometry of a compatible almost CR structure (H, J) on M is encoded in terms of regular infinitesimal flag structures, or equivalently (see Proposition 4.6), in terms of reductions of the structure group of the full graded frame bundle \mathcal{F}_{gr} associated with the filtration $TM = T^{-2}M \supset T^{-1}M = H$. We also need to discuss how the geometry of $(H, J, \mathcal{E}(1, 0))$, where $\mathcal{E}(1, 0)$ is an (n+2)-nd root of the canonical bundle \mathcal{K} (cf. Section 2.1), can be encoded similarly. To some extent, this subsection is an elaboration of [13, Example 3.1.7].

Let $G^{\sharp} = SU(n+1,1)$ be the special unitary group with respect to the indefinite Hermitian inner product (5.1) and $G = PSU(n+1,1) = G^{\sharp}/Z(G^{\sharp})$ its quotient by its center $Z(G^{\sharp}) \cong \mathbb{Z}_{n+2}$ (the set of constant matrices of determinant 1 in G^{\sharp}). We define the parabolic subgroup P of Gas the stabilizer of the null complex line $\langle t(1 \ 0 \ \cdots \ 0 \ 0) \rangle$ in $\mathbb{C}^{n+1,1}$, and P^{\sharp} is defined to be the pullback of P by the projection $G^{\sharp} \to G$. Then the Levi subgroups are

$$G_0^{\sharp} = \left\{ \begin{array}{c} c \\ U \\ 1/\overline{c} \end{array} \right| c \in \mathbb{C}^{\times}, U \in U(n), \text{ and } \frac{c}{\overline{c}} \det U = 1 \right\}$$

and $G_0 = G_0^{\sharp} / \mathbb{Z}_{n+2}$.

First, given a compatible almost CR structure (H, J) on a smooth manifold M, we define

$$\mathcal{G}_{0} = \bigsqcup_{x \in M} \left\{ \varphi \colon \mathfrak{g}_{-} \to \operatorname{gr}(T_{x}M) \middle| \begin{array}{l} \varphi \text{ is a grading respecting linear isomorphism preserving} \\ \text{the complex structures } j \text{ on } \mathfrak{g}_{-1} \text{ and } J \text{ on } H_{x}, \text{ and} \\ \text{the brackets } \mathfrak{g}_{-1} \times \mathfrak{g}_{-2} \text{ and } H_{x} \times H_{x} \to T_{x}M/H_{x} \end{array} \right\},$$

where $H_x \times H_x \to T_x M/H_x$ is the Levi bracket. Clearly, \mathcal{G}_0 can be equivalently described as

(6.1)
$$\mathcal{G}_0 = \bigsqcup_{x \in M} \left\{ \left(Z_1, \dots, Z_n, T \right) \middle| \begin{array}{c} Z_1, \dots, Z_n \in H_x^{1,0}, T \in T_x M/H_x, \text{ and} \\ \left[Z_\alpha, Z_{\overline{\beta}} \right] = -i\delta_{\alpha\overline{\beta}}T \text{ in } T_x M/H_x \end{array} \right\}$$

or even as

(6.2)
$$\mathcal{G}_0 = \bigsqcup_{x \in M} \left\{ (Z_1, \dots, Z_n) \middle| \begin{array}{l} Z_1, \dots, Z_n \in H_x^{1,0} \text{ is a conformal unitary frame} \\ \text{with respect to } i[\cdot, \cdot] \colon H_x^{1,0} \times H_x^{0,1} \to T_x M/H_x \end{array} \right\}.$$

The adjoint action of the group G_0 on \mathfrak{g}_- induces its right action on \mathcal{G}_0 , given explicitly using the second expression (6.1) by

(6.3)
$$(Z_1, \dots, Z_n, T) \cdot \begin{bmatrix} c & & \\ & U & \\ & & 1/\overline{c} \end{bmatrix} = (c^{-1}(Z_1, \dots, Z_n)U, |c|^{-2}T).$$

Thus the bundle \mathcal{G}_0 is a reduction of the structure group of \mathcal{F}_{gr} to G_0 , and the agreement of the brackets $\mathfrak{g}_{-1} \times \mathfrak{g}_{-1} \to \mathfrak{g}_{-2}$ and $H_x \times H_x \to T_x M/H_x$ means that the corresponding infinitesimal flag structure is regular. Conversely, any regular infinitesimal flag structure corresponding to a structure group reduction of \mathcal{F}_{gr} to G_0 is induced this way by some compatible almost CR structure.

The third expression (6.2) of \mathcal{G}_0 shows that the conformal unitary group $CU(n) \subset GL(n, \mathbb{C})$ is naturally acting on \mathcal{G}_0 from the right. This action and the one defined by (6.3) are compatible with the isomorphism $G_0 \cong CU(n)$ given by

(6.4)
$$\begin{bmatrix} c & & \\ & U & \\ & & 1/\overline{c} \end{bmatrix} \mapsto c^{-1}U.$$

Next, suppose that we are moreover given a complex line bundle $\mathcal{E}(1,0)$ with $\mathcal{E}(1,0)^{-n-2} = \mathcal{K}$. Then the (n+2)-sheeted covering \mathcal{G}_0^{\sharp} of \mathcal{G}_0 is defined by

$$\mathcal{G}_{0}^{\sharp} = \bigsqcup_{x \in M} \left\{ \left(Z_{1}, \dots, Z_{n}, T, \eta \right) \middle| \begin{array}{c} Z_{1}, \dots, Z_{n} \in H_{x}^{1,0}, T \in T_{x}M/H_{x}, \\ [Z_{\alpha}, Z_{\overline{\beta}}] = -i\delta_{\alpha\overline{\beta}}T \text{ in } T_{x}M/H_{x}, \text{ and} \\ \eta \in \mathcal{E}(1,0)_{x}, \eta^{n+2} = T \wedge Z_{1} \wedge \dots \wedge Z_{n} \in \mathcal{K}_{x}^{*} \end{array} \right\},$$

on which G_0^{\sharp} acts by

$$(Z_1, \dots, Z_n, T, \eta) \cdot \begin{pmatrix} c & & \\ & U & \\ & & 1/\overline{c} \end{pmatrix} = (c^{-1}(Z_1, \dots, Z_n)U, |c|^{-2}T, c^{-1}\eta).$$

The principal bundle structures of \mathcal{G}_0 and \mathcal{G}_0^{\sharp} are compatible with the projections $G_0^{\sharp} \to G_0$ and $\mathcal{G}_0^{\sharp} \to \mathcal{G}_0$, and thus \mathcal{G}_0^{\sharp} is a reduction of the structure group of \mathcal{F}_{gr} to G_0^{\sharp} . Giving such a reduction is equivalent to giving a structure $(H, J, \mathcal{E}(1, 0))$.

The Tanaka–Webster connection associated with any fixed contact form θ can be thought of as a principal connection of \mathcal{G}_0 or \mathcal{G}_0^{\sharp} . To describe this, take any local unitary frame $\{Z_{\alpha}\}$ of $H^{1,0}$ with respect to θ , defined over an open set U of M. Let $\omega = \omega_{\alpha}^{\ \beta}$ be the Tanaka–Webster

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connection form with respect $\{Z_{\alpha}\}$, which takes values in $\mathfrak{u}(n)$. Then, in terms of the local trivialization $\mathcal{G}_0|_U \cong U \times CU(n)$ given by the frame $\{Z_{\alpha}\}$, we define the $\mathfrak{cu}(n)$ -valued principal connection form γ of \mathcal{G}_0 by

$$\gamma = \omega + g^{-1} dg_{j}$$

where $g \in CU(n)$ denotes the fiber coordinate of \mathcal{G}_0 with respect to the above local trivialization. Since $G_0 \cong CU(n)$ by (6.4), γ can also be regarded as a \mathfrak{g}_0 -valued 1-form, whose pullback $\underline{\gamma}$ by the local section $\mathbf{Z} \colon U \to \mathcal{G}_0|_U$ given by $\{Z_\alpha\}$ is

$$\underline{\gamma} = \mathbf{Z}^* \gamma = \begin{pmatrix} -\frac{1}{n+2} \omega_{\gamma}^{\gamma} & \\ & \omega_{\alpha}^{\beta} - \frac{1}{n+2} \omega_{\gamma}^{\gamma} \delta_{\alpha}^{\beta} & \\ & & -\frac{1}{n+2} \omega_{\gamma}^{\gamma} \end{pmatrix}.$$

The pullback of γ by the covering $\mathcal{G}_0^{\sharp} \to \mathcal{G}_0$, which is a principal G_0^{\sharp} -connection form on \mathcal{G}_0^{\sharp} , is denoted by γ^{\sharp} .

6.3. Exact Weyl structures and determination of the induced normal Weyl form. There is a special class of Weyl structures called *exact Weyl structures* in the theory of parabolic geometries (see [13, Section 5.1.7]). Exact Weyl structures are in one-to-one correspondence with flat connections of any fixed "bundle of scales" induced by its global trivializations. For parabolic geometries of CR type (or more generally, for parabolic contact structures), the bundle H^{\perp} of annihilators of H, which is associated with \mathcal{G}_0 through the homomorphism

(6.5)
$$G_0 \to \mathbb{R}^*, \qquad \begin{bmatrix} c & & \\ & U & \\ & & 1/\overline{c} \end{bmatrix} \mapsto |c|^2$$

or with \mathcal{G}_0^{\sharp} through the composition $G_0^{\sharp} \to G_0 \to \mathbb{R}^*$ of (6.5) and the quotient mapping, is a bundle of scales [13, Section 5.2.11]. Consequently, any contact form θ determines an exact Weyl structure $\sigma_{\theta} \colon \mathcal{G}_0 \to \mathcal{G}$, or $\sigma_{\theta}^{\sharp} \colon \mathcal{G}_0^{\sharp} \to \mathcal{G}^{\sharp}$, which is characterized by the fact that the associated Weyl connection on \mathcal{G}_0 or \mathcal{G}_0^{\sharp} induces a linear connection of H^{\perp} with respect to which θ is parallel.

We are going to determine the Weyl form induced by an exact Weyl structure from a given normal regular parabolic geometry of CR type. In fact, we discuss only the case of type (G, P)in detail; then the Weyl form τ_{θ}^{\sharp} induced by σ_{θ}^{\sharp} from a normal regular parabolic geometry of type (G^{\sharp}, P^{\sharp}) can simply be obtained by pulling back the Weyl form τ_{θ} induced from the corresponding normal regular parabolic geometry of type (G, P) by the standard covering mapping $\mathcal{G}_{0}^{\sharp} \to \mathcal{G}_{0}$.

So, let (\mathcal{G}, ω) be a regular parabolic geometry of type (G, P) and let $\sigma_{\theta} \colon \mathcal{G}_0 \to \mathcal{G}$ be an exact Weyl structure as above. Take an arbitrary local unitary frame $\{Z_{\alpha}\}$ of $H^{1,0}$ with respect to θ and let $\{\theta^{\alpha}\}$ be the dual admissible coframe. The induced Weyl form $\sigma_{\theta}^* \omega$ is denoted by τ_{θ} , or simply by τ in the sequel. Then, since the induced Weyl form τ satisfies the conditions in Definition 6.1, its pullback $\underline{\tau} = \mathbf{Z}^* \tau$ by the local section $\mathbf{Z} \colon U \to \mathcal{G}_0|_U$ given by $\{Z_{\alpha}\}$ must be of the form

(6.6)
$$\underline{\tau} = \begin{pmatrix} * & * & * \\ \theta^{\alpha} \mod \theta & * & * \\ i\theta & -\theta_{\beta} \mod \theta & * \end{pmatrix},$$

where each * denotes an unspecified component and $\theta_{\beta} = \delta_{\beta \overline{\gamma}} \theta^{\overline{\gamma}}$.

If we furthermore assume the normality of (\mathcal{G}, ω) and hence that of τ , we can determine all the components of $\underline{\tau}$, which means that τ is determined completely. We make the following

observation as the first step toward this. Note that some general theory regarding this step is developed in [13, Section 5.2.11], to which we do not appeal here.

Lemma 6.3. Let (\mathcal{G}, ω) be a normal parabolic geometry of type (G, P), and let τ be the Weyl form induced by the exact Weyl structure $\sigma_{\theta} \colon \mathcal{G}_0 \to \mathcal{G}$ associated with a contact form θ . Then its pullback $\underline{\tau}$ by the local section $\mathbf{Z} \colon U \to \mathcal{G}_0|_U$ given by a unitary frame $\{Z_{\alpha}\}$ must be of the form

(6.7)
$$\underline{\tau} = \begin{pmatrix} -\frac{1}{n+2}\omega_{\gamma}^{\gamma} \mod \theta & * & * \\ \theta^{\alpha} & \omega_{\beta}^{\alpha} - \frac{1}{n+2}\omega_{\gamma}^{\gamma}\delta_{\beta}^{\alpha} \mod \theta & * \\ i\theta & -\theta_{\beta} & -\frac{1}{n+2}\omega_{\gamma}^{\gamma} \mod \theta \end{pmatrix},$$

where $\{\theta^{\alpha}\}$ be the dual admissible coframe and ω_{β}^{α} is the Tanaka–Webster connection forms with respect to $\{Z_{\alpha}\}$.

We remark that the notion of homogeneity is convenient to prove the above lemma and to determine the remaining components in the next subsection. We say that a *p*-form τ with values in \mathfrak{g} on an open set of \mathcal{G}_0 is of homogeneity $\geq l$ if $\xi_1 \in T^{i_1}\mathcal{G}_0, \ldots, \xi_p \in T^{i_p}\mathcal{G}_0$ implies $\tau(\xi_1, \ldots, \xi_p) \in \mathfrak{g}^{i_1+\cdots+i_p+l}$. For example, Definition 6.1 implies that any Weyl form is of homogeneity ≥ 0 . Similar language is used for differential forms with values in \mathfrak{g} on open sets of M, using the filtration $T^{-2}M \supset T^{-1}M$, as well. Thus, if we set

(6.8)
$$\eta^{(0)} = \begin{pmatrix} \theta^{\alpha} & \\ i\theta & -\theta_{\beta} \end{pmatrix},$$

then (6.6) implies that $\underline{\tau}$ equals $\eta^{(0)}$ modulo terms of homogeneity ≥ 1 .

Proof of Lemma 6.3. Let

$$\tilde{\eta}^{(0)} = \begin{pmatrix} -\frac{1}{n+2}\omega_{\gamma}^{\gamma} & \\ \theta^{\alpha} & \omega_{\beta}^{\alpha} - \frac{1}{n+2}\omega_{\gamma}^{\gamma}\delta_{\beta}^{\alpha} & \\ i\theta & -\theta_{\beta} & -\frac{1}{n+2}\omega_{\gamma}^{\gamma} \end{pmatrix}.$$

Then, (6.6) implies that the pullback of the Weyl form τ to the base should be expressed as

$$\underline{\tau} = \tilde{\eta}^{(0)} + \underbrace{\begin{pmatrix} \mathsf{a}_{\sigma}\theta^{\sigma} + \mathsf{a}_{\overline{\sigma}}\theta^{\sigma} \mod \theta & * & * \\ \mathsf{X}^{\alpha}{}_{0}\theta & \mathsf{A}_{\beta}{}^{\alpha}{}_{\sigma}\theta^{\sigma} + \mathsf{A}_{\beta}{}^{\alpha}{}_{\overline{\sigma}}\theta^{\overline{\sigma}} \mod \theta & * \\ & -\mathsf{X}_{\beta0}\theta & -\overline{\mathsf{a}}_{\sigma}\theta^{\sigma} - \overline{\mathsf{a}}_{\overline{\sigma}}\theta^{\overline{\sigma}} \mod \theta \end{pmatrix}}_{\text{homogeneity} \geq 1},$$

where the correction term (the second term) on the right-hand side is \mathfrak{g} -valued and transforms tensorially with respect to the indices α , β (and, of course, with respect to σ and $\overline{\sigma}$ as well) for changes of unitary frames { Z_{α} }. Note that, since the correction term is \mathfrak{g} -valued, in particular we have

$$\overline{\mathbf{a}_{\sigma}} = \overline{\mathbf{a}}_{\overline{\sigma}}, \qquad \overline{\mathbf{a}_{\overline{\sigma}}} = \overline{\mathbf{a}}_{\sigma}, \qquad \mathbf{a}_{\sigma} + \mathbf{A}_{\gamma}{}^{\gamma}{}_{\sigma} - \overline{\mathbf{a}}_{\sigma} = 0.$$

Moreover, since the contact form θ should be parallel with respect to the linear connection of H^{\perp} induced by the Weyl connection $\gamma^{\sigma_{\theta}}$, (6.5) implies that

$$\mathbf{a}_{\sigma} + \overline{\mathbf{a}}_{\sigma} = 0$$

is necessary. It follows, therefore, that

(6.9)
$$\mathsf{A}_{\gamma}{}^{\gamma}{}_{\sigma} + 2\mathsf{a}_{\sigma} = 0.$$

The pullback of the curvature form K of τ to the base is given by

$$\begin{split} \underline{K} &\equiv d\tilde{\eta}^{(0)} + \frac{1}{2} [\tilde{\eta}^{(0)} \wedge \tilde{\eta}^{(0)}] \\ &+ d \begin{pmatrix} \mathsf{a}_{\sigma} \theta^{\sigma} + \mathsf{a}_{\overline{\sigma}} \theta^{\overline{\sigma}} \mod \theta & * & * \\ & \mathsf{X}^{\alpha}{}_{0} \theta & \mathsf{A}_{\beta}{}^{\alpha}{}_{\sigma} \theta^{\sigma} + \mathsf{A}_{\beta}{}^{\alpha}{}_{\overline{\sigma}} \theta^{\overline{\sigma}} \mod \theta & * \\ & -\mathsf{X}_{\beta 0} \theta & -\overline{\mathsf{a}}_{\sigma} \theta^{\sigma} - \overline{\mathsf{a}}_{\overline{\sigma}} \theta^{\overline{\sigma}} \mod \theta \end{pmatrix} \\ &+ \left[\eta^{(0)} \wedge \begin{pmatrix} \mathsf{a}_{\sigma} \theta^{\sigma} + \mathsf{a}_{\overline{\sigma}} \theta^{\overline{\sigma}} \mod \theta & * & * \\ & \mathsf{X}^{\alpha}{}_{0} \theta & \mathsf{A}_{\beta}{}^{\alpha}{}_{\sigma} \theta^{\sigma} + \mathsf{A}_{\beta}{}^{\alpha}{}_{\overline{\sigma}} \theta^{\overline{\sigma}} \mod \theta & * \\ & -\mathsf{X}_{\beta 0} \theta & -\overline{\mathsf{a}}_{\sigma} \theta^{\sigma} - \overline{\mathsf{a}}_{\overline{\sigma}} \theta^{\overline{\sigma}} \mod \theta \end{pmatrix} \right] \end{split}$$

modulo terms of homogeneity ≥ 2 , where $\eta^{(0)}$ is defined by (6.8), because the bracketed wedge product of two homogeneity ≥ 1 terms is of homogeneity ≥ 2 . By omitting more homogeneity ≥ 2 terms, the above formula can be simplified further to

(6.10)
$$\frac{K}{E} \equiv d\tilde{\eta}^{(0)} + \frac{1}{2} [\tilde{\eta}^{(0)} \wedge \tilde{\eta}^{(0)}] + \begin{pmatrix} \mathsf{X}^{\alpha}{}_{0} & \\ & -\mathsf{X}_{\beta 0} \end{pmatrix} d\theta \\
+ \begin{bmatrix} \eta^{(0)} \wedge \begin{pmatrix} \mathsf{a}_{\sigma} \theta^{\sigma} + \mathsf{a}_{\overline{\sigma}} \theta^{\overline{\sigma}} \\ \mathsf{X}^{\alpha}{}_{0} \theta & \mathsf{A}_{\beta}{}^{\alpha}{}_{\sigma} \theta^{\sigma} + \mathsf{A}_{\beta}{}^{\alpha}{}_{\overline{\sigma}} \theta^{\overline{\sigma}} \\ & -\mathsf{X}_{\beta 0} \theta & -\overline{\mathsf{a}}_{\sigma} \theta^{\sigma} - \overline{\mathsf{a}}_{\overline{\sigma}} \theta^{\overline{\sigma}} \end{pmatrix} \end{bmatrix}.$$

The normality of τ means that its curvature function κ satisfies $\partial^* \kappa = 0$, which is equivalent to

(6.11)
$$\partial^* \underline{\kappa} = 0.$$

We now determine the correction term using (6.11) and (6.9). First, we have

$$d\tilde{\eta}^{(0)} + \frac{1}{2} [\tilde{\eta}^{(0)} \wedge \tilde{\eta}^{(0)}] = \begin{pmatrix} * & * & * \\ \frac{1}{2} N^{\alpha}_{\sigma\tau} \theta^{\overline{\sigma}} \wedge \theta^{\overline{\tau}} \mod \theta & * & * \\ & -\frac{1}{2} N_{\beta\sigma\tau} \theta^{\sigma} \wedge \theta^{\tau} \mod \theta & * \end{pmatrix}.$$

Consequently, (6.10) implies that \underline{K} is of homogeneity ≥ 1 , and if we write

$$\underline{K} = \begin{pmatrix} * & * & * \\ \boldsymbol{X}^{\alpha} & * & * \\ i\boldsymbol{x} & -\boldsymbol{X}_{\beta} & * \end{pmatrix},$$

then

$$\begin{split} \boldsymbol{x}_{0\sigma} &= i \mathsf{X}_{\sigma 0}, \\ \boldsymbol{X}^{\alpha}_{ \sigma \tau} &= \mathsf{A}_{\tau}{}^{\alpha}{}_{\sigma} - \mathsf{A}_{\sigma}{}^{\alpha}{}_{\tau} + \mathsf{a}_{\tau} \delta_{\sigma}{}^{\alpha} - \mathsf{a}_{\sigma} \delta_{\tau}{}^{\alpha}, \\ \boldsymbol{X}^{\alpha}_{ \sigma \overline{\tau}} &= i h_{\sigma \overline{\tau}} \mathsf{X}^{\alpha}{}_{0} - \mathsf{A}_{\sigma}{}^{\alpha}{}_{\overline{\tau}} + \mathsf{a}_{\overline{\tau}} \delta_{\sigma}{}^{\alpha}, \\ \boldsymbol{X}^{\alpha}_{ \overline{\sigma \tau}} &= N^{\alpha}{}_{\overline{\sigma \tau}}. \end{split}$$

The normality (6.11) implies, by the computation in Section 5.4,

- (6.12a) $\boldsymbol{X}^{\gamma}_{\sigma\gamma} \boldsymbol{x}_{0\sigma} = 0,$
- (6.12b) $\boldsymbol{X}^{\alpha}_{\ \sigma\beta} \boldsymbol{X}_{\beta\sigma}^{\ \alpha} = 0,$
- (6.12c) $\boldsymbol{X}_{\gamma\sigma}{}^{\gamma} \boldsymbol{x}_{0\sigma} = 0,$
- (6.12d) $\boldsymbol{X}_{\beta\gamma}{}^{\gamma} + \boldsymbol{x}_{0\beta} = 0.$

Equations (6.12a), (6.12c), (6.12d) imply

$$\begin{split} -i\mathsf{X}_{\sigma0} + \mathsf{A}_{\gamma}{}^{\gamma}{}_{\sigma} - \mathsf{A}_{\sigma}{}^{\gamma}{}_{\gamma} - (n-1)\mathsf{a}_{\sigma} &= 0, \\ -2i\mathsf{X}_{\sigma0} + \mathsf{A}_{\gamma}{}^{\gamma}{}_{\sigma} + n\mathsf{a}_{\sigma} &= 0, \\ i(n+1)\mathsf{X}_{\sigma0} - \mathsf{A}_{\sigma}{}^{\gamma}{}_{\gamma} - \mathsf{a}_{\sigma} &= 0, \end{split}$$

from which, together with (6.9), we can conclude that $X_{\sigma 0} = A_{\gamma}{}^{\gamma}{}_{\sigma} = A_{\sigma}{}^{\gamma}{}_{\gamma} = a_{\sigma} = 0$. Then we moreover obtain from (6.12b) that $2A_{\beta}{}^{\alpha}{}_{\sigma} - A_{\sigma}{}^{\alpha}{}_{\beta} = 0$, which implies that $A_{\beta}{}^{\alpha}{}_{\sigma} = 0$. \Box

Note that curvature form of (6.7) is of the form

(6.13)
$$\underline{K} = \begin{pmatrix} * & * & * \\ \frac{1}{2}N^{\alpha}_{\ \overline{\sigma\tau}}\theta^{\overline{\sigma}} \wedge \theta^{\overline{\tau}} \mod \theta & * & * \\ -\frac{1}{2}N_{\beta\sigma\tau}\theta^{\sigma} \wedge \theta^{\tau} \mod \theta & * \end{pmatrix},$$

as the computation in the above proof shows.

We also remark that the soldering form τ_{-} is completely determined by Lemma 6.3; the pullback of τ_{-} to the base manifold by any local unitary frame $\mathbf{Z} = \{Z_{\alpha}\}$ equals $\eta^{(0)}$ in (6.8). Thus, differential forms on U with values in \mathfrak{g} can be thought of as functions on U with values in $\bigwedge^{p} \mathfrak{g}_{-}^{*} \otimes \mathfrak{g}$ via $\eta^{(0)}$. This in particular implies that the homogeneity l component of a \mathfrak{g} -valued differential form on U makes sense.

6.4. Determination of the induced normal Weyl form (continued). We continue our discussion to determine the rest of the components of the normal Weyl form τ induced by an exact Weyl structure $\sigma_{\theta}: \mathcal{G}_0 \to \mathcal{G}$. Actually, it suffices to determine $\underline{\tau}$ only modulo terms of homogeneity ≥ 3 for our purpose of identifying the first BGG operators in Section 7. However, we derive the full formula for future reference.

6.4.1. Homogeneity 2 components. Our task here is to determine $\underline{\tau}$ modulo terms of homogeneity ≥ 3 . Lemma 6.3 implies that, if we set

$$\eta^{(1)} = \begin{pmatrix} -\frac{1}{n+2}\omega_{\gamma}^{\gamma} & \\ \theta^{\alpha} & \omega_{\beta}^{\alpha} - \frac{1}{n+2}\omega_{\gamma}^{\gamma}\delta_{\beta}^{\alpha} & \\ i\theta & -\theta_{\beta} & -\frac{1}{n+2}\omega_{\gamma}^{\gamma} \end{pmatrix},$$

then $\underline{\tau}$ can be expressed as

$$\underline{\tau} = \eta^{(1)} + \underbrace{\begin{pmatrix} \mathsf{a}_0 \theta & \mathsf{Z}_{\beta\sigma} \theta^{\sigma} + \mathsf{Z}_{\beta\overline{\sigma}} \theta^{\overline{\sigma}} \mod \theta & * \\ & \mathsf{A}_{\beta}{}^{\alpha}{}_0 \theta & -\mathsf{Z}{}^{\alpha}{}_{\sigma} \theta^{\sigma} - \mathsf{Z}{}^{\alpha}{}_{\overline{\sigma}} \theta^{\overline{\sigma}} \mod \theta \\ & & -\overline{\mathsf{a}}_0 \theta \end{pmatrix}}_{\text{homogeneity} > 2},$$

where $\overline{\mathbf{a}_0} = \overline{\mathbf{a}}_0$ and $\mathbf{a}_0 + \mathbf{A}_{\gamma \ 0}^{\ \gamma} - \overline{\mathbf{a}}_0 = 0$. Furthermore, as before, since the Weyl connection makes θ parallel, \mathbf{a}_0 should be purely imaginary and hence

$$\mathsf{(6.14)}\qquad\qquad \mathsf{A}_{\gamma \ 0}^{\ \gamma} + 2\mathsf{a}_0 = 0.$$

The computation of the curvature form K pulled back to the base can be carried out modulo terms of homogeneity ≥ 3 as follows:

(6.15)
$$\begin{split} \underline{K} &\equiv d\eta^{(1)} + \frac{1}{2} [\eta^{(1)} \wedge \eta^{(1)}] + \begin{pmatrix} \mathsf{a}_0 & \\ & \mathsf{A}_{\beta}{}^{\alpha}{}_0 \\ & & -\overline{\mathsf{a}}_0 \end{pmatrix} d\theta \\ & + \left[\eta^{(0)} \wedge \begin{pmatrix} \mathsf{a}_0 \theta & \mathsf{Z}_{\beta\sigma} \theta^{\sigma} + \mathsf{Z}_{\beta\overline{\sigma}} \theta^{\overline{\sigma}} \\ & \mathsf{A}_{\beta}{}^{\alpha}{}_0 \theta & -\mathsf{Z}{}^{\alpha}{}_{\sigma} \theta^{\sigma} - \mathsf{Z}{}^{\alpha}{}_{\overline{\sigma}} \theta^{\overline{\sigma}} \\ & & -\overline{\mathsf{a}}_0 \theta \end{pmatrix} \right]. \end{split}$$

The first two terms of the right-hand side is given by (6.13) modulo terms of homogeneity ≥ 2 , and here we need to compute it one homogeneity higher. By a direct computation, we get

$$d\eta^{(1)} + \frac{1}{2}[\eta^{(1)} \wedge \eta^{(1)}] = \begin{pmatrix} \Pi^{(1)} & * & * \\ \Pi^{(1)\alpha} & \Pi^{(1)}{}_{\beta}{}^{\alpha} & * \\ & -\Pi^{(1)}{}_{\beta} & -\overline{\Pi^{(1)}} \end{pmatrix},$$

which is a \mathfrak{g} -valued 2-form, where

$$\begin{split} \Pi^{(1)\alpha} &= \frac{1}{2} N^{\alpha}_{\ \overline{\sigma\tau}} \theta^{\overline{\sigma}} \wedge \theta^{\overline{\tau}} + A^{\alpha}_{\ \overline{\sigma}} \theta \wedge \theta^{\overline{\sigma}}, \\ \Pi^{(1)} &\equiv -\frac{1}{n+2} (R_{\sigma\overline{\tau}} \theta^{\sigma} \wedge \theta^{\overline{\tau}} + \frac{1}{2} V_{\sigma\tau} \theta^{\sigma} \wedge \theta^{\tau} + \frac{1}{2} V_{\overline{\sigma\tau}} \theta^{\overline{\sigma}} \wedge \theta^{\overline{\tau}}) \mod \theta, \\ \Pi^{(1)}{}_{\beta}{}^{\alpha} &\equiv (R_{\beta}{}^{\alpha}{}_{\sigma\overline{\tau}} - \frac{1}{n+2} \delta_{\beta}{}^{\alpha} R_{\sigma\overline{\tau}}) \theta^{\sigma} \wedge \theta^{\overline{\tau}} \\ &\quad + \frac{1}{2} (V_{\beta}{}^{\alpha}{}_{\sigma\tau} - \frac{1}{n+2} \delta_{\beta}{}^{\alpha} V_{\sigma\tau}) \theta^{\sigma} \wedge \theta^{\tau} + \frac{1}{2} (V_{\beta}{}^{\alpha}{}_{\overline{\sigma\tau}} - \frac{1}{n+2} \delta_{\beta}{}^{\alpha} V_{\overline{\sigma\tau}}) \theta^{\overline{\sigma}} \wedge \theta^{\overline{\tau}} \mod \theta. \end{split}$$

(Note that $\Pi^{(1)}$ is purely imaginary because $\eta^{(1)}$ induces a flat connection of H^{\perp} .) So if we write

$$\underline{K} = \begin{pmatrix} oldsymbol{a} & * & * \ oldsymbol{X}^lpha & oldsymbol{A}_eta^lpha & * \ oldsymbol{X}_eta & oldsymbol{--} - \overline{oldsymbol{a}} \end{pmatrix},$$

then, by calculating the right-hand side of (6.15), we obtain

$$\begin{split} \boldsymbol{X}^{\alpha}_{\ \sigma\tau} &= \boldsymbol{X}^{\alpha}_{\ \sigma\overline{\tau}} = \boldsymbol{0}, \\ \boldsymbol{X}^{\alpha}_{\ \overline{\sigma\tau}} &= N^{\alpha}_{\ \overline{\sigma\tau}}, \\ \boldsymbol{X}^{\alpha}_{\ 0\sigma} &= \boldsymbol{A}_{\sigma}^{\ \alpha}_{\ 0} - \delta_{\sigma}^{\ \alpha} \boldsymbol{a}_{0} + i\boldsymbol{Z}^{\alpha}_{\ \sigma}, \\ \boldsymbol{X}^{\alpha}_{\ 0\overline{\sigma}} &= A^{\alpha}_{\ \overline{\sigma}} + i\boldsymbol{Z}^{\alpha}_{\ \overline{\sigma}}, \\ \boldsymbol{A}_{\beta}^{\ \alpha}_{\ \sigma\overline{\tau}} &= V_{\beta}^{\ \alpha}_{\ \sigma\overline{\tau}} - \frac{1}{n+2}\delta_{\beta}^{\ \alpha}V_{\sigma\tau} + \delta_{\sigma}^{\ \alpha}\boldsymbol{Z}_{\beta\tau} - \delta_{\tau}^{\ \alpha}\boldsymbol{Z}_{\beta\sigma}, \\ \boldsymbol{A}_{\beta}^{\ \alpha}_{\ \sigma\overline{\tau}} &= R_{\beta}^{\ \alpha}_{\ \sigma\overline{\tau}} - \frac{1}{n+2}\delta_{\beta}^{\ \alpha}R_{\sigma\overline{\tau}} + ih_{\sigma\overline{\tau}}\boldsymbol{A}_{\beta}^{\ \alpha}_{\ 0} + \delta_{\sigma}^{\ \alpha}\boldsymbol{Z}_{\beta\overline{\tau}} + h_{\beta\overline{\tau}}\boldsymbol{Z}^{\alpha}_{\ \sigma}, \\ \boldsymbol{A}_{\beta}^{\ \alpha}_{\ \overline{\sigma\overline{\tau}}} &= V_{\beta}^{\ \alpha}_{\ \overline{\sigma\overline{\tau}}} - \frac{1}{n+2}\delta_{\beta}^{\ \alpha}V_{\overline{\sigma\overline{\tau}}} - h_{\beta\overline{\sigma}}\boldsymbol{Z}^{\alpha}_{\ \overline{\tau}} + h_{\beta\overline{\tau}}\boldsymbol{Z}^{\alpha}_{\ \sigma}, \\ \boldsymbol{a}_{\sigma\overline{\tau}} &= -\frac{1}{n+2}V_{\sigma\tau} - \boldsymbol{Z}_{\sigma\tau} + \boldsymbol{Z}_{\tau\sigma}, \\ \boldsymbol{a}_{\overline{\sigma\overline{\tau}}} &= -\frac{1}{n+2}R_{\sigma\overline{\tau}} + ih_{\sigma\overline{\tau}}\boldsymbol{a}_{0} - \boldsymbol{Z}_{\sigma\overline{\tau}}, \\ \boldsymbol{a}_{\overline{\sigma\overline{\tau}}} &= -\frac{1}{n+2}V_{\overline{\sigma\overline{\tau}}}. \end{split}$$

The normality condition (6.11) implies that

(6.16a)
$$i\boldsymbol{A}_{\beta}{}^{\alpha}{}^{\gamma}-\boldsymbol{X}{}^{\alpha}{}_{0\beta}+\boldsymbol{X}_{\beta0}{}^{\alpha}=0,$$
(6.16b)
$$\boldsymbol{X}{}^{\gamma}{}_{\alpha}+i\boldsymbol{a}{}^{\gamma}=0.$$

(6.16c)
$$\mathbf{A}_{\beta}^{\gamma}{}_{\sigma\gamma} - i\mathbf{X}_{\beta0\sigma} + \mathbf{a}_{\beta\sigma} = 0,$$

$$\mathbf{A}_{\beta}^{\gamma}{}_{\sigma\gamma} - i\mathbf{X}_{\beta0\sigma} + \mathbf{a}_{\beta\sigma} = 0,$$

(6.16d)
$$-\boldsymbol{A}_{\beta}^{\gamma}{}_{\gamma\overline{\sigma}} - i\boldsymbol{X}_{\beta0\overline{\sigma}} + \boldsymbol{a}_{\beta\overline{\sigma}} = 0.$$

It follows from (6.16a) that

$$i{R'}_{\beta}{}^{\alpha} - \frac{i}{n+2}R\delta_{\beta}{}^{\alpha} - (n+2)\mathsf{A}_{\beta}{}^{\alpha}{}_{0} + 2\delta_{\beta}{}^{\alpha}\mathsf{a}_{0} = 0.$$

Therefore, using (6.14) together, we can deduce that

(6.17a)
$$\mathbf{a}_0 = -\frac{i}{n+2}P, \qquad \mathbf{A}_\beta{}^\alpha{}_0 = iP'{}^\alpha{}_\beta - \frac{i}{n+2}\delta^\alpha{}_\beta P.$$

Next, (6.16c) implies that

$$V_{\beta} \gamma_{\sigma\gamma} - iA_{\beta\sigma} - (n+1)\mathsf{Z}_{\beta\sigma} + \mathsf{Z}_{\sigma\beta} = 0.$$

and hence

(6.17b)
$$Z_{\beta\sigma} = -iA_{\beta\sigma} + \frac{1}{n} (\nabla^* N)^{\text{sym}}_{\beta\sigma} + \frac{1}{n+2} (\nabla^* N)^{\text{skew}}_{\beta\sigma}$$
$$= -iA_{\beta\sigma} + \frac{n+1}{n(n+2)} (\nabla^* N)_{\beta\sigma} + \frac{1}{n(n+2)} (\nabla^* N)_{\sigma\beta}.$$

Finally, by (6.16d),

$$-R_{\beta\overline{\sigma}}^{\prime\prime} - (n+2)\mathsf{Z}_{\beta\overline{\sigma}} - h_{\beta\overline{\sigma}}\mathsf{Z}_{\gamma}{}^{\gamma} = 0,$$

and thus we obtain

(6.17c) $\mathsf{Z}_{\beta\overline{\sigma}} = -P_{\beta\overline{\sigma}}''$

Then (6.16b) is also satisfied.

6.4.2. Homogeneity 3 components. Similarly, in the next step, we determine the normal Weyl form τ modulo terms of homogeneity ≥ 4 . We have already shown that $\underline{\tau}$ equals

$$\eta^{(2)} = \begin{pmatrix} -\frac{1}{n+2}\omega_{\gamma}{}^{\gamma} + \mathsf{a}_{0}\theta & \mathsf{Z}_{\beta\sigma}\theta^{\sigma} + \mathsf{Z}_{\beta\overline{\sigma}}\theta^{\overline{\sigma}} \\ \theta^{\alpha} & \omega_{\beta}{}^{\alpha} - \frac{1}{n+2}\omega_{\gamma}{}^{\gamma}\delta_{\beta}{}^{\alpha} + \mathsf{A}_{\beta}{}^{\alpha}{}_{0}\theta & -\mathsf{Z}^{\alpha}{}_{\sigma}\theta^{\sigma} - \mathsf{Z}^{\alpha}{}_{\overline{\sigma}}\theta^{\overline{\sigma}} \\ i\theta & -\theta_{\beta} & -\frac{1}{n+2}\omega_{\gamma}{}^{\gamma} - \overline{\mathsf{a}}_{0}\theta \end{pmatrix}$$

modulo terms of homogeneity ≥ 3 , where the homogeneity 2 components are given by (6.17a), (6.17b), and (6.17c). So we can write

$$\underline{\tau} = \eta^{(2)} + \underbrace{\begin{pmatrix} & \mathsf{Z}_{\beta 0}\theta & i\mathsf{z}_{\sigma}\theta^{\sigma} + i\mathsf{z}_{\overline{\sigma}}\theta^{\overline{\sigma}} \mod \theta \\ & & -\mathsf{Z}^{\alpha}_{0}\theta \end{pmatrix}}_{\text{homogeneity} \geq 3}.$$

Its curvature is given modulo terms of homogeneity ≥ 4 by

(6.18)
$$\underline{K} \equiv d\eta^{(2)} + \frac{1}{2} [\eta^{(2)} \wedge \eta^{(2)}] + \begin{pmatrix} \mathsf{Z}_{\beta 0} & \\ & -\mathsf{Z}_{0}^{\alpha} \end{pmatrix} d\theta + \left[\eta^{(0)} \wedge \begin{pmatrix} \mathsf{Z}_{\beta 0} \theta & i\mathsf{z}_{\sigma}\theta^{\sigma} + i\mathsf{z}_{\overline{\sigma}}\theta^{\overline{\sigma}} \\ & -\mathsf{Z}_{0}^{\alpha}\theta \end{pmatrix} \right].$$

Note that, to determine $Z_{\beta 0}$ and z_{σ} using the normality condition (6.11), only the homogeneity 3 components of <u>K</u> are involved. So we set

$$d\eta^{(2)} + \frac{1}{2}[\eta^{(2)} \wedge \eta^{(2)}] = \begin{pmatrix} \Pi^{(2)} & \Pi^{(2)}{}_{\beta} & * \\ * & \Pi^{(2)}{}_{\beta}{}^{\alpha} & -\Pi^{(2)}{}_{\alpha} \\ & * & -\overline{\Pi^{(2)}} \end{pmatrix}$$

and

$$\begin{split} \Pi^{(2)}{}_{\beta}{}^{\alpha} &= \frac{1}{2} \Pi^{(2)}{}_{\beta}{}^{\alpha}{}_{KL} \theta^{K} \wedge \theta^{L}, \qquad \Pi^{(2)} &= \frac{1}{2} \Pi^{(2)}{}_{KL} \theta^{K} \wedge \theta^{L}, \\ \Pi^{(2)}{}_{\beta} &= \frac{1}{2} \Pi^{(2)}{}_{\beta KL} \theta^{K} \wedge \theta^{L}, \end{split}$$

where the indices K and L run through $\{0, 1, \ldots, n, \overline{1}, \ldots, \overline{n}\}$, and compute its homogeneity 3 components, namely $\Pi^{(2)}{}_{\beta}{}^{\alpha}{}_{0\sigma}$, $\Pi^{(2)}{}_{\beta}{}^{\alpha}{}_{0\overline{\sigma}}$, $\Pi^{(2)}{}_{0\sigma}$, $\Pi^{(2)}{}_{0\overline{\sigma}}$, and $\Pi^{(2)}{}_{\beta\sigma\overline{\tau}}$, $\Pi^{(2)}{}_{\beta\sigma\tau}$, $\Pi^{(2)}{}_{\beta\overline{\sigma\tau}}$. By a direct calculation, we obtain

$$\begin{split} \Pi^{(2)}{}_{\beta}{}^{\alpha}{}_{0\sigma} &= -W_{\beta}{}^{\alpha}{}_{\sigma} + \frac{1}{n+2}\delta_{\beta}{}^{\alpha}W_{\gamma}{}^{\gamma}{}_{\sigma} - i\nabla_{\sigma}\mathsf{A}_{\beta}{}^{\alpha}{}_{0}, \\ \Pi^{(2)}{}_{\beta}{}^{\alpha}{}_{0\overline{\sigma}} &= -W_{\beta}{}^{\alpha}{}_{\overline{\sigma}} + \frac{1}{n+2}\delta_{\beta}{}^{\alpha}W_{\gamma}{}^{\gamma}{}_{\overline{\sigma}} - i\nabla_{\overline{\sigma}}\mathsf{A}_{\beta}{}^{\alpha}{}_{0}, \\ \Pi^{(2)}{}_{0\sigma} &= \frac{1}{n+2}W_{\gamma}{}^{\gamma}{}_{\overline{\sigma}} - \nabla_{\sigma}\mathsf{a}_{0}, \\ \Pi^{(2)}{}_{0\overline{\sigma}\overline{\tau}} &= \frac{1}{n+2}W_{\gamma}{}^{\gamma}{}_{\overline{\sigma}} - \nabla_{\overline{\sigma}}\mathsf{a}_{0}, \\ \Pi^{(2)}{}_{\beta\sigma\overline{\tau}} &= \nabla_{\sigma}\mathsf{Z}_{\beta\overline{\tau}} - \nabla_{\overline{\tau}}\mathsf{Z}_{\beta\sigma}, \\ \Pi^{(2)}{}_{\beta\sigma\overline{\tau}} &= 2\nabla_{[\sigma}|\mathsf{Z}_{\beta|\overline{\tau}]} + N^{\overline{\gamma}}{}_{\sigma\overline{\tau}}\mathsf{Z}_{\beta\overline{\gamma}}, \\ \Pi^{(2)}{}_{\beta\overline{\sigma\overline{\tau}}} &= 2\nabla_{[\overline{\sigma}}|\mathsf{Z}_{\beta|\overline{\tau}]} + N^{\overline{\gamma}}{}_{\overline{\sigma\overline{\tau}}}\mathsf{Z}_{\beta\gamma}. \end{split}$$

Now if we write

$$\underline{K} = egin{pmatrix} oldsymbol{a} & oldsymbol{Z}_{eta} & * \ * & oldsymbol{A}_{eta}^{lpha} & -oldsymbol{Z}^{lpha} \ * & -oldsymbol{\overline{a}} \end{pmatrix},$$

then we obtain from (6.18) that

$$\begin{split} \boldsymbol{A}_{\beta}^{\ \alpha}{}_{0\sigma} &= \Pi^{(2)}{}_{\beta}{}^{\alpha}{}_{0\sigma} - \delta^{\alpha}{}_{\sigma}\boldsymbol{Z}_{\beta 0}, \\ \boldsymbol{a}_{0\sigma} &= \Pi^{(2)}{}_{0\sigma} + \boldsymbol{Z}_{\sigma 0} + \boldsymbol{z}_{\sigma}, \\ \boldsymbol{a}_{0\overline{\sigma}} &= \Pi^{(2)}{}_{0\overline{\sigma}} + \boldsymbol{z}_{\overline{\sigma}}, \\ \boldsymbol{Z}_{\beta\sigma\overline{\tau}} &= \Pi^{(2)}{}_{\beta\sigma\overline{\tau}} - ih_{\beta\overline{\tau}}\boldsymbol{z}_{\sigma} + ih_{\sigma\overline{\tau}}\boldsymbol{Z}_{\beta 0}, \\ \boldsymbol{Z}_{\beta\sigma\overline{\tau}} &= \Pi^{(2)}{}_{\beta\sigma\overline{\tau}}, \\ \boldsymbol{Z}_{\beta\overline{\sigma\tau}} &= \Pi^{(2)}{}_{\beta\overline{\sigma\tau}} + ih_{\beta\overline{\sigma}}\boldsymbol{z}_{\overline{\tau}} - ih_{\beta\overline{\tau}}\boldsymbol{z}_{\overline{\sigma}}. \end{split}$$

The normality condition (6.11) implies that

(6.19a)
$$\begin{aligned} \boldsymbol{A}_{\beta}{}^{\gamma}{}_{0\gamma} - \boldsymbol{a}_{0\beta} + i\boldsymbol{Z}_{\beta\gamma}{}^{\gamma} = \boldsymbol{0}, \\ (6.19b) & -i\boldsymbol{a}_{0\sigma} - i\overline{\boldsymbol{a}}_{0\sigma} + \boldsymbol{Z}_{\gamma\sigma}{}^{\gamma} - \boldsymbol{Z}{}^{\gamma}{}_{\sigma\gamma} = \boldsymbol{0}. \end{aligned}$$

It follows from (6.19a) that

(6.20a)

$$\begin{split} \mathsf{Z}_{\beta 0} &= \frac{1}{2n+1} (\Pi^{(2)}{}_{\beta}{}^{\gamma}{}_{0\gamma} - \Pi^{(2)}{}_{0\beta} + i\Pi^{(2)}{}_{\beta\gamma}{}^{\gamma}) \\ &= \frac{1}{2n+1} (-W_{\beta}{}^{\gamma}{}_{\gamma} + \frac{1}{n+2} W_{\gamma}{}^{\gamma}{}_{\beta} - i\nabla_{\gamma}\mathsf{A}_{\beta}{}^{\gamma}{}_{0} - \frac{1}{n+2} W_{\gamma}{}^{\gamma}{}_{\beta} + \nabla_{\beta}\mathsf{a}_{0} + i\nabla_{\gamma}\mathsf{Z}_{\beta}{}^{\gamma} - i\nabla^{\gamma}\mathsf{Z}_{\beta\gamma}) \\ &= -\frac{i}{2n+1} (\nabla_{\gamma}P'{}_{\beta}{}^{\gamma} + \nabla_{\gamma}P''{}_{\beta}{}^{\gamma} - 2i\nabla^{\gamma}A_{\beta\gamma} + \frac{1}{n}\nabla^{\gamma}(\nabla^{*}N)^{\mathrm{sym}}_{\beta\gamma} + \frac{1}{n+2}\nabla^{\gamma}(\nabla^{*}N)^{\mathrm{skew}}_{\beta\gamma}). \end{split}$$

Likewise, (6.19b) implies that

$$(6.20b)$$

$$z_{\sigma} = -\frac{i}{2n+1} (\Pi^{(2)}{}_{\gamma\sigma}{}^{\gamma} - \Pi^{(2)}{}_{\sigma\gamma})$$

$$= -\frac{i}{2n+1} (\nabla_{\sigma} Z_{\gamma}{}^{\gamma} - \nabla^{\gamma} Z_{\gamma\sigma} - \nabla_{\sigma} Z^{\gamma}{}_{\gamma} + \nabla_{\gamma} Z^{\gamma}{}_{\sigma} - N_{\gamma_{1}\sigma\gamma_{2}} Z^{\gamma_{2}\gamma_{1}})$$

$$= \frac{i}{2n+1} (\nabla_{\gamma} P''{}_{\sigma}{}^{\gamma} - i\nabla^{\gamma} A_{\sigma\gamma} - iA^{\gamma_{1}\gamma_{2}} N_{\gamma_{1}\gamma_{2}\sigma}$$

$$+ \frac{1}{n} (\nabla^{\gamma} (\nabla^{*} N)^{\text{sym}}_{\sigma\gamma} - (\nabla^{*} N)^{\text{sym}}_{\overline{\gamma_{1}}\overline{\gamma_{2}}} N^{\overline{\gamma_{1}}\overline{\gamma_{2}}}_{\sigma}) - \frac{1}{n+2} (\nabla^{\gamma} (\nabla^{*} N)^{\text{skew}}_{\sigma\gamma} - (\nabla^{*} N)^{\text{skew}}_{\overline{\gamma_{1}}\overline{\gamma_{2}}} N^{\overline{\gamma_{1}}\overline{\gamma_{2}}}_{\sigma})).$$

The formulae that we have just obtained may be simplified further by the Bianchi identities of the Tanaka–Webster connection, but there is no point in doing it here in full generality. In the integrable case (i.e., if N = 0), we have (see Lee [27, Lemma 2.2])

$$\nabla_{\gamma} P_{\alpha}{}^{\gamma} = \frac{1}{n+2} ((2n+1)\nabla_{\alpha} P - i(n-1)\nabla^{\gamma} A_{\alpha\gamma}).$$

Therefore, (6.20a) becomes

$$\mathsf{Z}_{\beta 0} = -\frac{2}{2n+1} (\nabla^{\gamma} A_{\beta \gamma} + i \nabla_{\gamma} P_{\beta}^{\ \gamma}) = -\frac{2i}{n+2} (\nabla_{\beta} P - i \nabla^{\gamma} A_{\beta \gamma}),$$

which equals $-2iT_{\beta}$ in the notation of Gover–Graham [20], and (6.20b) becomes

$$\mathsf{z}_{\sigma} = \frac{i}{2n+1} (\nabla_{\gamma} P_{\sigma}{}^{\gamma} - i \nabla^{\gamma} A_{\sigma\gamma}) = \frac{i}{n+2} (\nabla_{\beta} P - i \nabla^{\gamma} A_{\beta\gamma}),$$

which is iT_{β} of [20].

6.4.3. Homogeneity 4 component. This is the last step of the determination of the normal Weyl form τ . We already know that $\underline{\tau}$ equals

$$\eta^{(3)} = \begin{pmatrix} -\frac{1}{n+2}\omega_{\gamma}{}^{\gamma} + \mathsf{a}_{0}\theta & \mathsf{Z}_{\beta\sigma}\theta^{\sigma} + \mathsf{Z}_{\beta\overline{\sigma}}\theta^{\overline{\sigma}} + \mathsf{Z}_{\beta0}\theta & i\mathsf{z}_{\sigma}\theta^{\sigma} + i\mathsf{z}_{\overline{\sigma}}\theta^{\overline{\sigma}} \\ \theta^{\alpha} & \omega_{\beta}{}^{\alpha} - \frac{1}{n+2}\omega_{\gamma}{}^{\gamma}\delta_{\beta}{}^{\alpha} + \mathsf{A}_{\beta}{}^{\alpha}{}_{0}\theta & -\mathsf{Z}^{\alpha}{}_{\sigma}\theta^{\sigma} - \mathsf{Z}^{\alpha}{}_{\overline{\sigma}}\theta^{\overline{\sigma}} - \mathsf{Z}^{\alpha}{}_{0}\theta \\ i\theta & -\theta_{\beta} & -\frac{1}{n+2}\omega_{\gamma}{}^{\gamma} - \overline{\mathsf{a}}_{0}\theta \end{pmatrix}$$

modulo terms of homogeneity ≥ 4 , where the homogeneity ≥ 2 components in the matrix entries are given by (6.17a), (6.17b), (6.17c), and (6.20a), (6.20b). We write

$$\underline{\tau} = \eta^{(3)} + \underbrace{\begin{pmatrix} i \mathbf{z}_0 \theta \\ \\ \\ \end{pmatrix}}_{\text{homogeneity} \ge 4}.$$

Then the curvature is given by the following formula modulo terms of homogeneity ≥ 5 :

(6.21)
$$\underline{K} \equiv d\eta^{(3)} + \frac{1}{2} [\eta^{(3)} \wedge \eta^{(3)}] + \begin{pmatrix} & iz_0 \\ & & \end{pmatrix} d\theta + \begin{bmatrix} \eta^{(0)} \wedge \begin{pmatrix} & iz_0\theta \\ & & \end{pmatrix} \end{bmatrix}.$$

In determining z_0 , only the homogeneity 4 components of \underline{K} are involved. So if we set

$$d\eta^{(3)} + \frac{1}{2} [\eta^{(3)} \wedge \eta^{(3)}] = \begin{pmatrix} * & \Pi^{(3)}{}_{\beta} & i\Pi^{(3)} \\ * & * & -\Pi^{(3)}{}_{\alpha} \\ & * & * \end{pmatrix}$$

and

$$\Pi^{(3)}{}_{\beta} = \frac{1}{2}\Pi^{(3)}{}_{\beta KL}\theta^K \wedge \theta^L, \qquad \Pi^{(3)} = \frac{1}{2}\Pi^{(3)}{}_{KL}\theta^K \wedge \theta^L,$$

where the indices K and L run through $\{0, 1, \ldots, n, \overline{1}, \ldots, \overline{n}\}$, then we only need to compute its homogeneity 4 components, namely $\Pi^{(3)}{}_{\beta 0 \sigma}$, $\Pi^{(3)}{}_{\beta 0 \overline{\sigma}}$, and $\Pi^{(3)}{}_{\sigma \overline{\tau}}$, $\Pi^{(3)}{}_{\sigma \overline{\tau}}$, $\Pi^{(3)}{}_{\overline{\sigma \tau}}$. Actually, we do not need all of them as we see as follows. If the curvature of $\underline{\tau}$ is expressed as

$$\underline{K} = \begin{pmatrix} * & \boldsymbol{Z}_{\beta} & i\boldsymbol{z} \\ * & * & -\boldsymbol{Z}^{\alpha} \\ & * & * \end{pmatrix},$$

then (6.21) implies

$$\begin{aligned} \boldsymbol{Z}_{\beta 0 \sigma} &= \Pi^{(3)}{}_{\beta 0 \sigma}, \\ \boldsymbol{Z}_{\beta 0 \overline{\sigma}} &= \Pi^{(3)}{}_{\beta 0 \overline{\sigma}} - i h_{\beta \overline{\sigma}} \boldsymbol{z}_0, \\ \boldsymbol{z}_{\sigma \overline{\tau}} &= \Pi^{(3)}{}_{\sigma \overline{\tau}} + i h_{\sigma \overline{\tau}} \boldsymbol{z}_0, \\ \boldsymbol{z}_{\sigma \overline{\tau}} &= \Pi^{(3)}{}_{\sigma \overline{\tau}}, \\ \boldsymbol{z}_{\overline{\sigma \tau}} &= \Pi^{(3)}{}_{\overline{\sigma \tau}}, \end{aligned}$$

and the normality condition (6.11) in this degree reads

$$\boldsymbol{Z}_{\gamma 0}{}^{\gamma} - \boldsymbol{Z}_{0\gamma}{}^{\gamma} - \boldsymbol{z}_{\gamma}{}^{\gamma} = \boldsymbol{0},$$

which implies that

$$\mathsf{z}_{0} = \frac{i}{3n} (-\Pi^{(3)}{}_{\gamma 0}{}^{\gamma} + \Pi^{(3)}{}_{0\gamma}{}^{\gamma} + \Pi^{(3)}{}_{\gamma}{}^{\gamma})$$

Therefore, it suffices to compute $\Pi^{(3)}{}_{\beta 0 \overline{\sigma}}$ and $\Pi^{(3)}{}_{\sigma \overline{\tau}}$. By a direct computation, we obtain

$$\begin{split} \Pi^{(3)}{}_{\beta 0 \overline{\sigma}} &= -\nabla_{\overline{\sigma}} \mathsf{Z}_{\beta 0} + \nabla_{0} \mathsf{Z}_{\beta \overline{\sigma}} + A_{\overline{\sigma}}{}^{\gamma} \mathsf{Z}_{\beta \gamma} - \mathsf{A}_{\beta}{}^{\gamma}{}_{0} \mathsf{Z}_{\gamma \overline{\sigma}} + \mathsf{a}_{0} \mathsf{Z}_{\beta \overline{\sigma}}, \\ \Pi^{(3)}{}_{\sigma \overline{\tau}} &= \nabla_{\sigma} \mathsf{z}_{\overline{\tau}} - \nabla_{\overline{\tau}} \mathsf{z}_{\sigma} - i \mathsf{Z}^{\gamma}{}_{\sigma} \mathsf{Z}_{\gamma \overline{\tau}} + i \mathsf{Z}_{\gamma \sigma} \mathsf{Z}^{\gamma}{}_{\overline{\tau}}. \end{split}$$

Consequently, we get

$$\begin{array}{l} (6.22) \quad \mathsf{z}_{0} = \frac{i}{3n} (\nabla^{\gamma} \mathsf{Z}_{\gamma 0} - \nabla^{\overline{\gamma}} \mathsf{Z}_{\overline{\gamma} 0} - A^{\gamma_{1} \gamma_{2}} \mathsf{Z}_{\gamma_{1} \gamma_{2}} + A^{\overline{\gamma}_{1} \overline{\gamma}_{2}} \mathsf{Z}_{\overline{\gamma}_{1} \overline{\gamma}_{2}} \\ \qquad + \mathsf{A}_{\gamma_{1}}{}^{\gamma_{2}}{}_{0} \mathsf{Z}_{\gamma_{2}}{}^{\gamma_{1}} - \mathsf{A}_{\overline{\gamma}_{1}}{}^{\overline{\gamma}_{2}} \mathsf{Z}_{\overline{\gamma}_{2}}{}^{\overline{\gamma}_{1}} - 2\mathsf{a}_{0} \mathsf{Z}_{\gamma}{}^{\gamma} - \nabla^{\gamma} \mathsf{z}_{\gamma} + \nabla^{\overline{\gamma}} \mathsf{z}_{\overline{\gamma}} - i \mathsf{Z}_{\gamma_{1} \overline{\gamma}_{2}} \mathsf{Z}^{\gamma_{1} \overline{\gamma}_{2}} + i \mathsf{Z}_{\gamma_{1} \gamma_{2}} \mathsf{Z}^{\gamma_{1} \gamma_{2}}). \end{array}$$

The explicit formula in terms of the Tanaka–Webster invariants, which we omit, can be obtained by putting (6.17a), (6.17b), (6.17c), and (6.20a), (6.20b) into the above. In the integrable case, it becomes

$$\mathsf{z}_0 = \frac{1}{n} (\nabla^{\gamma} T_{\gamma} + \nabla^{\overline{\gamma}} T_{\overline{\gamma}} + P_{\alpha \overline{\beta}} P^{\alpha \overline{\beta}} - A_{\alpha \beta} A^{\alpha \beta}),$$

which is -S in the notation of [20].

7. Computation of CR BGG operators

Having written down the CR normal Weyl form explicitly in the previous section, we are now able to express the normal tractor connection associated with the standard representation of $G^{\sharp} = SU(n+1,1)$ and the one associated with the adjoint representation of G = PSU(n+1,1) using Proposition 6.2. Then we can also derive the formula of the modified adjoint tractor connection $\tilde{\nabla}$. We are going to compute the first BGG operator associated with these three tractor connections.

7.1. The case of the normal standard tractor connection. Let σ_{θ} be the Weyl structure associated with a contact form θ . Then, the conclusion from the previous section is that the associated normal Weyl form τ is given by

$$\underline{\tau} = \begin{pmatrix} -\frac{1}{n+2}\omega_{\gamma}{}^{\gamma} + \mathbf{a}_{0}\theta & \mathbf{Z}_{\beta\sigma}\theta^{\sigma} + \mathbf{Z}_{\beta\overline{\sigma}}\theta^{\overline{\sigma}} + \mathbf{Z}_{\beta0}\theta & i\mathbf{z}_{\sigma}\theta^{\sigma} + i\mathbf{z}_{\overline{\sigma}}\theta^{\overline{\sigma}} + i\mathbf{z}_{0}\theta \\ \theta^{\alpha} & \omega_{\beta}{}^{\alpha} - \frac{1}{n+2}\omega_{\gamma}{}^{\gamma}\delta_{\beta}{}^{\alpha} + \mathbf{A}_{\beta}{}^{\alpha}{}_{0}\theta & -\mathbf{Z}^{\alpha}{}_{\sigma}\theta^{\sigma} - \mathbf{Z}^{\alpha}{}_{\overline{\sigma}}\theta^{\overline{\sigma}} - \mathbf{Z}^{\alpha}{}_{0}\theta \\ i\theta & -\theta_{\beta} & -\frac{1}{n+2}\omega_{\gamma}{}^{\gamma} - \overline{\mathbf{a}}_{0}\theta \end{pmatrix},$$

where (6.17a), (6.17b), (6.17c), (6.20a), (6.20b), and (6.22) are observed.

Proposition 6.2 implies that the normal tractor connection ∇ for the standard tractor bundle $\mathcal{V} = \mathcal{G}^{\sharp} \times_{P^{\sharp}} \mathbb{V} \cong \mathcal{G}_{0}^{\sharp} \times_{G_{0}^{\sharp}} \mathbb{V}$, the latter identification being given by the Weyl structure σ_{θ} , can be expressed as

(7.1a)
$$\nabla_{\sigma} \begin{pmatrix} s \\ t^{\alpha} \\ u \end{pmatrix} = \begin{pmatrix} \nabla_{\sigma} s + \mathsf{Z}_{\beta\sigma} t^{\beta} + i\mathsf{z}_{\sigma} u \\ \nabla_{\sigma} t^{\alpha} + \delta_{\sigma}{}^{\alpha} s - \mathsf{Z}{}^{\alpha}{}_{\sigma} u \\ \nabla_{\sigma} u \end{pmatrix},$$

(7.1b)
$$\nabla_{\overline{\sigma}} \begin{pmatrix} s \\ t^{\alpha} \\ u \end{pmatrix} = \begin{pmatrix} \nabla_{\overline{\sigma}} s + \mathsf{Z}_{\beta\overline{\sigma}} t^{\beta} + i\mathsf{Z}_{\overline{\sigma}} u \\ \nabla_{\overline{\sigma}} t^{\alpha} - \mathsf{Z}^{\alpha}_{\overline{\sigma}} u \\ \nabla_{\overline{\sigma}} u - t_{\overline{\sigma}} \end{pmatrix},$$

(7.1c)
$$\nabla_0 \begin{pmatrix} s \\ t^{\alpha} \\ u \end{pmatrix} = \begin{pmatrix} \nabla_0 s + \mathbf{a}_0 s + \mathsf{Z}_{\beta 0} t^{\beta} + i z_0 u \\ \nabla_0 t^{\alpha} + \mathsf{A}_{\beta}{}^{\alpha}{}_0 t^{\beta} - \mathsf{Z}{}^{\alpha}{}_0 u \\ \nabla_0 u - \overline{\mathbf{a}}_0 u + i s \end{pmatrix}$$

For later purpose, let us also write down the normal tractor connection associated with the dual representation of \mathbb{V} (the normal standard cotractor connection). It is given by

$$\begin{aligned} \nabla_{\sigma} \begin{pmatrix} \sigma & \tau_{\alpha} & \rho \end{pmatrix} &= \begin{pmatrix} \nabla_{\sigma} \sigma - \tau_{\sigma} & \nabla_{\sigma} \tau_{\alpha} - \mathsf{Z}_{\alpha\sigma} \sigma & \nabla_{\sigma} \rho + \mathsf{Z}^{\gamma}{}_{\sigma} \tau_{\gamma} - i\mathsf{z}_{\sigma} \sigma \end{pmatrix}, \\ \nabla_{\overline{\sigma}} \begin{pmatrix} \sigma & \tau_{\alpha} & \rho \end{pmatrix} &= \begin{pmatrix} \nabla_{\overline{\sigma}} \sigma & \nabla_{\overline{\sigma}} \tau_{\alpha} + h_{\alpha\overline{\sigma}} \rho - \mathsf{Z}_{\alpha\overline{\sigma}} \sigma & \nabla_{\overline{\sigma}} \rho + \mathsf{Z}^{\gamma}{}_{\overline{\sigma}} \tau_{\gamma} - i\mathsf{z}_{\overline{\sigma}} \sigma \end{pmatrix}, \\ \nabla_{0} \begin{pmatrix} \sigma & \tau_{\alpha} & \rho \end{pmatrix} &= \begin{pmatrix} \nabla_{0} \sigma - \mathsf{a}_{0} \sigma - i\rho & \nabla_{0} \tau_{\alpha} - \mathsf{A}_{\alpha}{}^{\beta}{}_{0} \tau_{\beta} - \mathsf{Z}_{\alpha0} \sigma & \nabla_{0} \rho + \overline{\mathsf{a}}_{0} \rho + \mathsf{Z}^{\beta}{}_{0} \tau_{\beta} - i\mathsf{z}_{0} \sigma \end{pmatrix}, \end{aligned}$$

which boils down to [20, Equation (3.3)] in the integrable case.

In order to compute the associated first BGG operator D_0 , we need to identify the lifting operator $L: \mathcal{H}_0(\mathfrak{p}_+, \mathbb{V}) \to \mathcal{V}$ satisfying that ∇Lu lies in the kernel of $\partial^*: \Omega^1(\mathcal{V}) \to \mathcal{V}$ for every $u = \mathcal{H}_0(\mathfrak{p}_+, \mathbb{V}) \cong \mathcal{E}(0, 1)$. If we write

$$Lu = \begin{pmatrix} s \\ t^{\alpha} \\ u \end{pmatrix},$$

then computations in Section 5.3 shows that $\partial^* \nabla L u = 0$ implies

$$t^{\alpha} = \nabla^{\alpha} u, \qquad s = \frac{1}{n+1} (-\nabla_{\gamma} t^{\gamma} + i \nabla_0 u - i \overline{\mathbf{a}}_0 u + \mathbf{Z}^{\gamma}{}_{\gamma} u).$$

Therefore, ∇Lu projects down to the element $(\nabla_{\sigma}u, \nabla_{(\overline{\alpha}}t_{\overline{\beta})} - \mathsf{Z}_{(\overline{\alpha}\overline{\beta})}u)$ of $\mathcal{H}_1(\mathfrak{p}_+, \mathbb{V}) = \mathcal{E}_{\sigma}(0, 1) \oplus \mathcal{E}_{(\overline{\alpha}\overline{\beta})}(0, 1)$. As a consequence, we can conclude that the first BGG operator D_0 is given by

(7.3)
$$D_0 u = (\nabla_\alpha u, \nabla_{(\overline{\alpha}} t_{\overline{\beta}}) - \mathsf{Z}_{(\overline{\alpha}\overline{\beta})} u) = \left(\nabla_\alpha u, \nabla_{(\overline{\alpha}} \nabla_{\overline{\beta})} u - iA_{\overline{\alpha}\overline{\beta}} u - \frac{1}{n} (\nabla^* N)_{\overline{\alpha}\overline{\beta}}^{\mathrm{sym}} u\right).$$

In the integrable case, the above operator reduces to

(7.4)
$$D_0: u \mapsto (\nabla_{\alpha} u, \nabla_{\overline{\alpha}} \nabla_{\overline{\beta}} u - iA_{\overline{\alpha}\overline{\beta}} u).$$

This system of equations for $u \in \mathcal{E}(0, 1)$ is essentially discussed in Čap–Gover [11, Section 4.14] in terms of the standard cotractor connection (see also [11, Section 4.2] carefully). Their computation in the proof of [11, Proposition 4.13] shows that the standard tractor connection ∇ is a prolongation of the operator (7.4).

Therefore, it is a remarkable observation that if we relax the integrability condition, then D_0 no longer prolongs to ∇ . Formally, we can formulate this fact as follows.

Proposition 7.1. Let ∇ be the standard tractor connection and $D_0: \mathcal{E}(0,1) \to \mathcal{E}_{\sigma}(0,1) \oplus \mathcal{E}_{(\overline{\alpha}\overline{\beta})}(0,1)$ the associated first BGG operator (7.3). Assume that the Nijenhuis tensor N is nonzero at a point $p \in M$, and there exists a nontrivial jet solution of the equation $D_0 u = 0$ at p. Then there are no linear differential operators $u \mapsto t^{\alpha}$ and $u \mapsto s$ in any neighborhood of p such that

$$D_0 u = 0$$
 at the level of jets at p

implies

$$abla \begin{pmatrix} s \\ t^{\alpha} \\ u \end{pmatrix} = 0 \qquad at \ the \ level \ of \ jets \ at \ p.$$

Proof. Suppose that there were such differential operators $u \mapsto t^{\alpha}$ and $u \mapsto s$. Then, if $D_0 u = 0$ is satisfied, then in view of (7.1b) and (7.1c), t^{α} and s must be given by

$$t^{\alpha} = \nabla^{\alpha} u$$
 and $s = i\nabla_0 u - i\overline{\mathsf{a}}_0 u = i\nabla_0 u + \frac{1}{n+2}Pu.$

Moreover, (7.1a) implies that such u should also satisfy $\nabla_{\beta}t^{\alpha} + \delta_{\beta}{}^{\alpha}s - \mathsf{Z}^{\alpha}{}_{\beta}u = 0$, or equivalently,

$$\nabla_{\beta}\nabla^{\alpha}u + \delta_{\beta}{}^{\alpha}\left(i\nabla_{0}u + \frac{1}{n+2}Pu\right) + P^{\prime\prime\alpha}{}_{\beta}u = 0.$$

Then it follows from Proposition 2.5 that

$$\nabla^{\alpha}\nabla_{\beta}u - \frac{1}{n+2}R_{\beta}^{\ \alpha}u + \frac{1}{n+2}\delta_{\beta}^{\ \alpha}Pu + P^{\prime\prime\alpha}_{\ \beta}u = 0$$

and hence, since $D_0 u = 0$ implies $\nabla_\beta u = 0$,

$$-\frac{1}{n+2}R_{\beta}^{\ \alpha}u + \frac{1}{n+2}\delta_{\beta}^{\ \alpha}Pu + P^{\prime\prime\alpha}_{\ \beta}u = 0.$$

Taking the trace and R = 2(n+1)P yields (P'' - P)u = 0, which implies $|N|^2 u = 0$ by (2.15). Note that our argument so far works as well at the level of jets. Therefore, there must be a nontrivial jet u at p satisfying $|N|^2 u = 0$, but this contradicts our assumption that N does not vanish at p.

7.2. The case of the normal adjoint tractor connection. Note that

$$\mathfrak{g} = \operatorname{Re}\mathfrak{sl}(n+2,\mathbb{C}) = \operatorname{Re}\operatorname{tf}\operatorname{End}(\mathbb{V})$$

as a G^{\sharp} -module. Consequently, the adjoint tractor bundle $\mathcal{A}M = \mathcal{G} \times_P \mathfrak{g} = \mathcal{G}^{\sharp} \times_{P^{\sharp}} \mathfrak{g}$ can be seen as

$$\mathcal{A}M = \operatorname{Re}\operatorname{tf}\operatorname{End}(\mathcal{V}),$$

and hence it follows from the results in the previous subsection that the normal tractor connection of $\mathcal{A}M$ reads as in Figure 1.

The lifting operator L acting on $\mathcal{H}_0(\mathfrak{p}_+,\mathfrak{g}) \cong \operatorname{Re} \mathcal{E}(1,1)$ is defined so that ∇Lx lies in the kernel of $\partial^* \colon \Omega^1(\mathcal{A}M) \to \mathcal{A}M$ for every $x \in \operatorname{Re} \mathcal{E}(1,1)$. This implies that $Lx \in \mathcal{A}M$ is of the form

$$Lx = \begin{pmatrix} * & * & * \\ i\nabla^{\alpha}x & * & * \\ ix & i\nabla_{\beta}x & * \end{pmatrix}.$$

Then

$$\nabla_{\sigma} Lx = \begin{pmatrix} * & * & * \\ * & * & * \\ 0 & i \nabla_{\sigma} \nabla_{\beta} x - i \mathbb{Z}_{\beta \sigma} x & * \end{pmatrix}$$
$$= \begin{pmatrix} * & * & * \\ * & * & * \\ 0 & i \nabla_{\sigma} \nabla_{\beta} x - A_{\beta \sigma} x - \frac{i}{n} (\nabla^* N)^{\text{sym}}_{\beta \sigma} - \frac{i}{n+2} (\nabla^* N)^{\text{skew}}_{\beta \sigma} & * \end{pmatrix}$$

This implies that the first BGG operator is given by

$$x \mapsto \left(-i\nabla_{(\alpha} \nabla_{\beta)} x + A_{\alpha\beta} x + \frac{i}{n} (\nabla^* N)^{\text{sym}}_{\alpha\beta}, i\nabla_{(\overline{\alpha}} \nabla_{\overline{\beta})} x + A_{\overline{\alpha}\overline{\beta}} x - \frac{i}{n} (\nabla^* N)^{\text{sym}}_{\overline{\alpha}\overline{\beta}} \right).$$

7.3. The case of the modified adjoint tractor connection. Recall from (4.5) that, in order to compute the action

$$\tilde{\nabla} \begin{pmatrix} a & Z_{\beta} & iz \\ X^{\alpha} & A_{\beta}^{\alpha} & -Z^{\alpha} \\ ix & -X_{\beta} & -\overline{a} \end{pmatrix}$$

of the modified adjoint tractor connection $\tilde{\nabla}$, we need to know the interior product of the curvature function $\underline{\kappa}$ and the vector field given by

$$\begin{pmatrix} * & * & * \\ X^{\alpha} & * & * \\ ix & -X_{\beta} & * \end{pmatrix}$$

$$\begin{aligned} \nabla_{\sigma} \begin{pmatrix} a & Z_{\beta} & iz \\ X^{\alpha} & A_{\beta}^{\alpha} & -Z^{\alpha} \\ ix & -X_{\beta} & -\overline{a} \end{pmatrix} &= \begin{pmatrix} \nabla_{\sigma}a - Z_{\sigma} + Z_{\gamma\sigma}X^{\gamma} - z_{\sigma}x & \nabla_{\sigma}Z_{\beta} + Z_{\gamma\sigma}A_{\beta}^{\gamma} - Z_{\beta\sigma}a - iz_{\sigma}X_{\beta} & i\nabla_{\sigma}z + Z_{\gamma\sigma}^{\gamma}Z_{\gamma} - Z_{\gamma\sigma}Z^{\gamma} - 2iz_{\sigma}\operatorname{Re}a \\ \nabla_{\sigma}X^{\alpha} - A_{\sigma}^{\alpha} + \delta^{\alpha}{}_{\sigma}a - iZ^{\alpha}{}_{\sigma}x & \nabla_{\sigma}A_{\beta}^{\alpha} + \delta_{\sigma}^{\alpha}Z_{\beta} + Z^{\alpha}{}_{\sigma}X_{\beta} - Z_{\beta\sigma}X^{\alpha} & -\nabla_{\sigma}Z^{\alpha} + i\delta_{\sigma}^{\alpha}z + Z^{\gamma}{}_{\sigma}A_{\gamma}^{\alpha} + Z^{\alpha}{}_{\sigma}\overline{a} - iz_{\sigma}X^{\alpha} \\ i\nabla_{\sigma}x + X_{\sigma} & -\nabla_{\sigma}X_{\beta} - iZ_{\beta\sigma}x & -\nabla_{\sigma}Z^{\alpha} + i\delta_{\sigma}^{\alpha}z - Z_{\gamma\sigma}Z^{\gamma} + z^{\gamma}{}_{\sigma}A_{\gamma}^{\alpha} + z^{\alpha}{}_{\sigma}\overline{a} - iz_{\sigma}X^{\alpha} \\ \sum_{i\nabla_{\sigma}x^{\alpha}} A_{\beta}^{\alpha} - Z^{\alpha} \\ ix & -X_{\beta} & -\overline{a} \end{pmatrix} &= \begin{pmatrix} \nabla_{\overline{\sigma}a} + Z_{\gamma\overline{\sigma}}X^{\gamma} - z_{\overline{\sigma}x} & \nabla_{\overline{\sigma}}Z_{\beta} + ih_{\beta\overline{\sigma}}z + Z_{\gamma\overline{\sigma}}A_{\beta}^{\gamma} - Z_{\beta\overline{\sigma}}a - iz_{\overline{\sigma}}X_{\beta} & i\nabla_{\overline{\sigma}}z - Z_{\gamma\overline{\sigma}}Z^{\gamma} + Z^{\gamma}{}_{\sigma}Z_{\gamma} - 2iz_{\overline{\sigma}}\operatorname{Re}a \\ \nabla_{\overline{\sigma}}X^{\alpha} - iZ^{\alpha}{}_{\overline{\sigma}}x & \nabla_{\overline{\sigma}}A_{\beta}^{\alpha} - h_{\beta\overline{\sigma}}Z^{\alpha} - Z_{\beta\overline{\sigma}}Z^{\alpha} + Z^{\alpha}{}_{\overline{\sigma}}A_{\beta}^{\alpha} - z_{\beta\overline{\sigma}}Z^{\alpha} + Z^{\alpha}{}_{\overline{\sigma}}A_{\gamma}^{\alpha} + Z^{\alpha}{}_{\overline{\sigma}}\overline{a} - iz_{\overline{\sigma}}X^{\alpha} \\ i\nabla_{\overline{\sigma}}x - X_{\overline{\sigma}} & -\nabla_{\overline{\sigma}}X_{\beta} - A_{\beta\overline{\sigma}} - h_{\beta\overline{\sigma}}\overline{a} - iZ_{\beta\overline{\sigma}}x & -\nabla_{\overline{\sigma}}\overline{a} + Z_{\overline{\sigma}} - Z^{\gamma}{}_{\overline{\sigma}}X_{\gamma} + z_{\overline{\sigma}}x \end{pmatrix} \\ &= \begin{pmatrix} \nabla_{0}a + z + Z_{\gamma0}X^{\gamma} - z_{0}x & \nabla_{0}Z_{\beta} - A_{\beta}^{\gamma}{}_{0}Z_{\gamma} + a_{0}Z_{\beta} + Z_{\gamma0}A_{\beta}^{\gamma} - Z_{\beta0}a - iz_{0}X_{\beta} & i\nabla_{0}z + Z^{\gamma}{}_{0}Z_{\gamma} - Z_{\gamma0}Z^{\gamma} - 2iz_{0}\operatorname{Re}a \\ ix - X_{\beta} & -\overline{a} \end{pmatrix} \\ &= \begin{pmatrix} \nabla_{0}x^{\alpha} + iZ^{\alpha} + A_{\gamma}^{\alpha}{}_{0}X^{\gamma} - a_{0}X^{\alpha} - iZ^{\alpha}{}_{0}x & \nabla_{0}A_{\beta}^{\alpha} + A_{\gamma}^{\alpha}{}_{0}}A_{\beta}^{\gamma} - A_{\beta}^{\gamma}{}_{0}A_{\gamma}^{\alpha} - Z_{\beta}{}_{0}X^{\alpha} - Z_{0}X_{\beta} & -\nabla_{0}Z^{\alpha} - A_{\gamma}^{\alpha}{}_{0}Z^{\gamma} + a_{0}Z^{\alpha} + Z^{\alpha}{}_{0}\overline{a} - iz_{0}X^{\alpha} \\ -\nabla_{0}X^{\alpha} + iZ^{\alpha} + A_{\gamma}^{\alpha}{}_{0}X^{\gamma} - a_{0}X^{\alpha} - iZ^{\alpha}{}_{0}x & \nabla_{0}A_{\beta}^{\alpha} + A_{\gamma}^{\alpha}{}_{0}}A_{\gamma}^{\beta} - Z_{\beta}{}_{0}X^{\gamma} - a_{0}X_{\beta} - Z^{\alpha}{}_{0}X_{\beta} & -\nabla_{0}Z^{\alpha} - A_{\gamma}^{\alpha}{}_{0}Z^{\gamma} + a_{0}Z^{\alpha} + Z^{\alpha}{}_{0}\overline{a} - iz_{0}X^{\alpha} \\ -\nabla_{0}X^{\alpha} + iZ^{\alpha} + A_{\gamma}^{\alpha}{}_{0}X^{\gamma} - a_{0}X^{\alpha} - iZ^{\alpha}{}_{0}X^{\gamma} - a_{0}X^{\beta} - A_{\gamma}^{\alpha}{}_{0}X^{\gamma} - a_{0}X^{\beta} - Z^{\alpha}{$$

FIGURE 1. The normal adjoint tractor connection

which is $X^{\alpha}Z_{\alpha} + X^{\overline{\alpha}}Z_{\overline{\alpha}} + xT$. The computation in the previous subsection implies that only the \mathfrak{g}_{-2} - and the \mathfrak{g}_{-1} -valued components are relevant to the first BGG operator associated with $\tilde{\nabla}$.

We know from (6.13) that the curvature of the normal Weyl form is of the form

$$\underline{K} = \begin{pmatrix} * & * & * \\ \Pi^{(2)\alpha} & * & * \\ 0 & -\Pi^{(2)}{}_{\beta} & * \end{pmatrix}$$

where

$$\Pi^{(2)\alpha} = \frac{1}{2} N^{\alpha}_{\ \overline{\sigma\tau}} \theta^{\overline{\sigma}} \wedge \theta^{\overline{\tau}} + \Pi^{(2)\alpha}_{\ 0\sigma} \theta \wedge \theta^{\sigma} + \Pi^{(2)\alpha}_{\ 0\overline{\sigma}} \theta \wedge \theta^{\overline{\sigma}}.$$

The curvature components $\Pi^{(2)\alpha}_{0\sigma}$ and $\Pi^{(2)\alpha}_{0\overline{\sigma}}$ can be computed using (6.15), and it follows that

$$\iota_{X^{\alpha}Z_{\alpha}+X^{\overline{\alpha}}Z_{\overline{\alpha}}+xT}\Pi^{(2)\alpha} \equiv -N^{\alpha}_{\overline{\sigma\tau}}X^{\overline{\tau}}\theta^{\overline{\sigma}} + (\mathsf{A}^{\alpha}_{\sigma 0} - \delta^{\alpha}_{\sigma}\mathsf{a}_{0} + i\mathsf{Z}^{\alpha}_{\sigma})x\theta^{\sigma} + (A^{\alpha}_{\overline{\sigma}} + i\mathsf{Z}^{\alpha}_{\overline{\sigma}})x\theta^{\overline{\sigma}} \mod \theta.$$

Consequently, the lifting operator L remains the same as in the previous subsection and the first BGG operator is given by

$$\begin{split} D_0^{\nabla} x &= D_0^{\nabla} x + \operatorname{proj}(\iota_{\Pi(Lx)}\underline{K}) \\ &= D_0^{\nabla} x + (-iN_{\alpha\beta\gamma}^{\operatorname{sym}} \nabla^{\gamma} x + A_{\alpha\beta} x - i\mathsf{Z}_{(\alpha\beta)} x, iN_{\overline{\alpha}\overline{\beta}\overline{\gamma}}^{\operatorname{sym}} \nabla^{\overline{\gamma}} x + A_{\overline{\alpha}\overline{\beta}} x + i\mathsf{Z}_{(\overline{\alpha}\overline{\beta})} x) \\ &= \left(-i\nabla_{(\alpha}\nabla_{\beta)} x + A_{\alpha\beta} x - iN_{\alpha\beta\gamma}^{\operatorname{sym}} \nabla^{\gamma} x, i\nabla_{(\overline{\alpha}}\nabla_{\overline{\beta})} x + A_{\overline{\alpha}\overline{\beta}} x + iN_{\overline{\alpha}\overline{\beta}\overline{\gamma}}^{\operatorname{sym}} \nabla^{\overline{\gamma}} x\right). \end{split}$$

This shows that $D_0^{\tilde{\nabla}}$ is nothing but the CR Killing operator.

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